

Making Complex Protection and Control Systems Easy to Maintain

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What Does This Mean?

Using a technology solution to address business needs

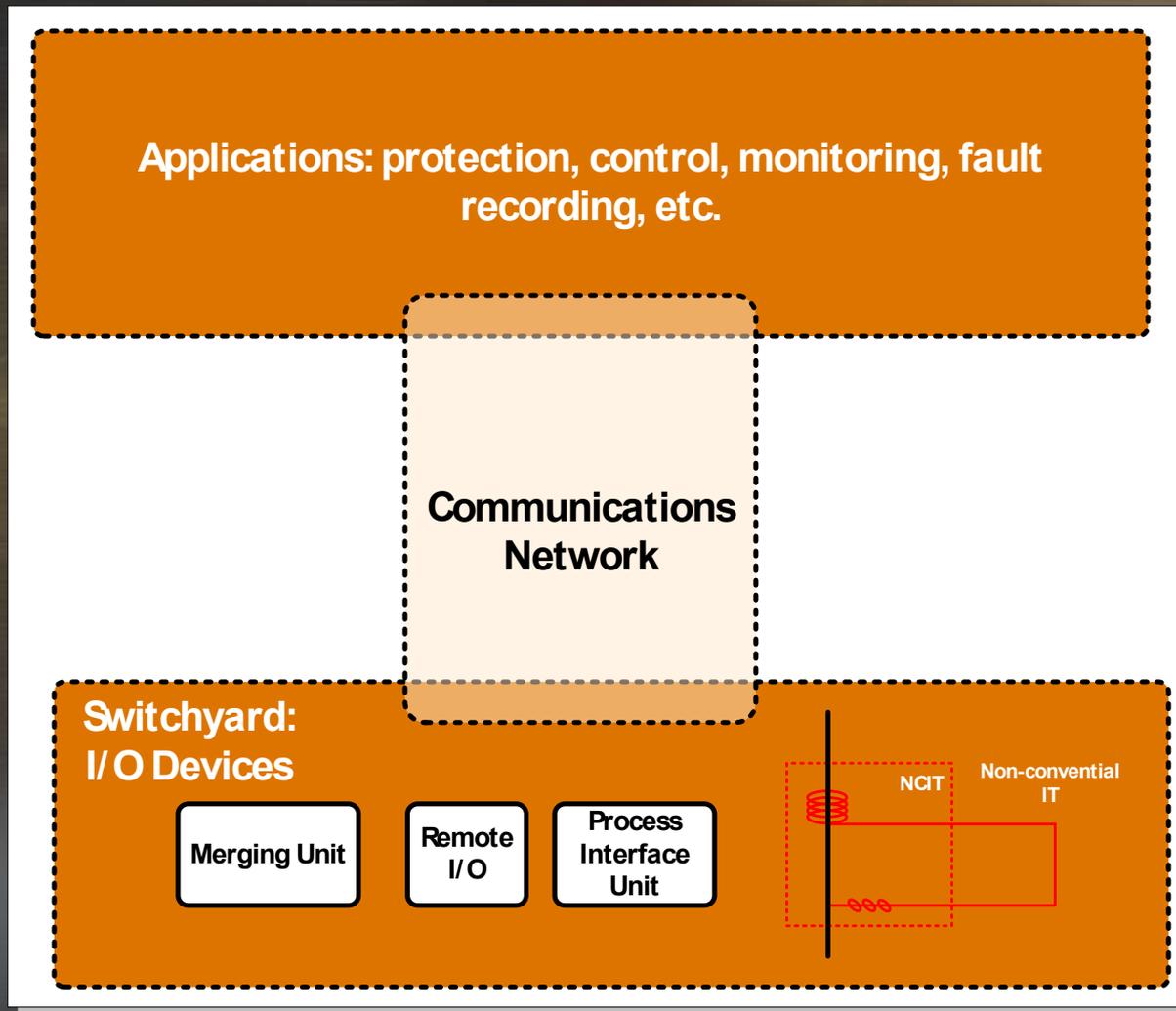
Business need

- Cost and effort to maintain protection and control systems

Technology solution

- Process bus

Process Bus



Process Bus Discussions To Date

Business case

- Project cost advantages unclear
- Less skilled resources is a strong case for adoption

Technical Issues

- Practical considerations for installation
- Network performance / concerns
- How to test
- Reducing the need for testing

Reliability

- Availability will be the same as conventional

The Big Questions

Long term system reliability

- More parts make up a system
- Will process bus be as reliable

Long term costs

- More parts make up a system
- What is the cost to maintain, with more possible device failures

To Answer These Questions:

Process bus is a possible solution

If the end result is that

PDT (Process Down Time) $\rightarrow 0$

Which only works if

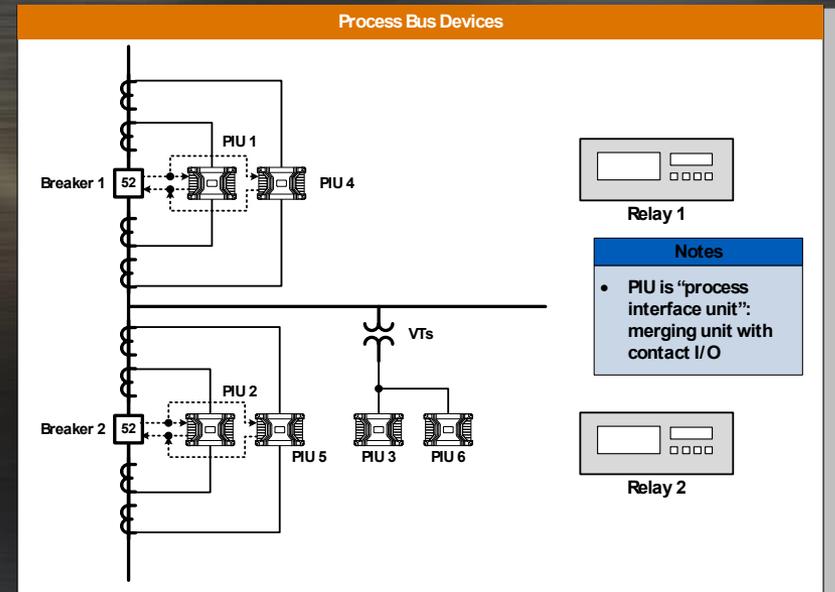
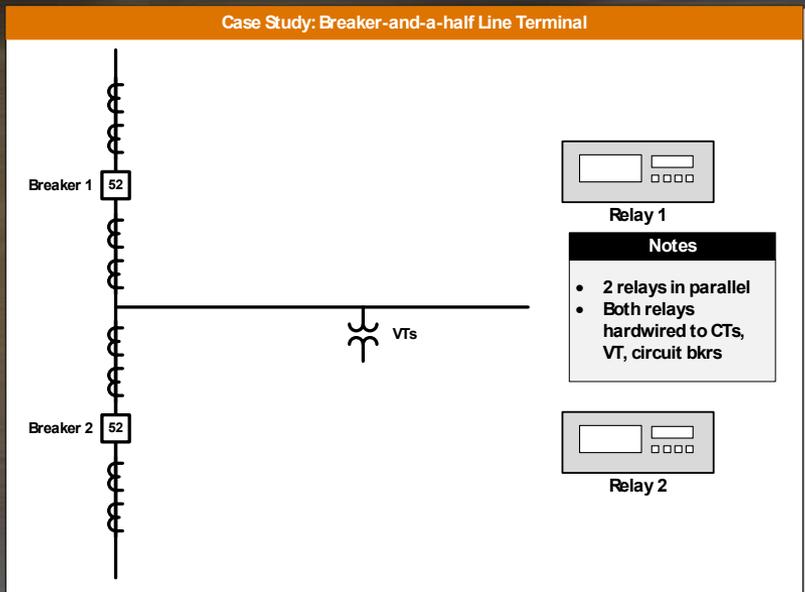
MTTR (Mean Time to Repair or Replace) $\rightarrow 0$

Devices can be quickly swapped out

Reliability Analysis

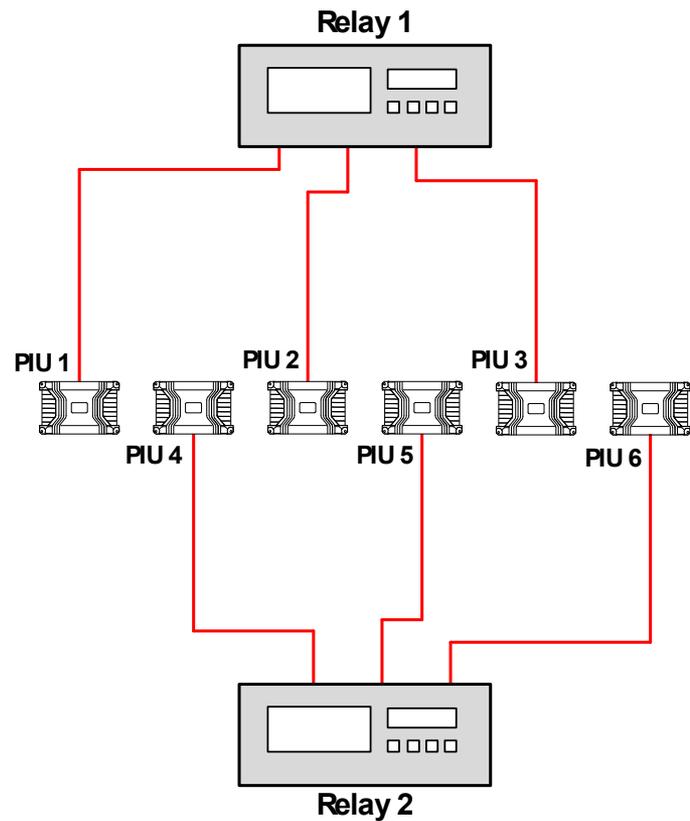
Case Study

Breaker-and-a-half line terminal with process bus

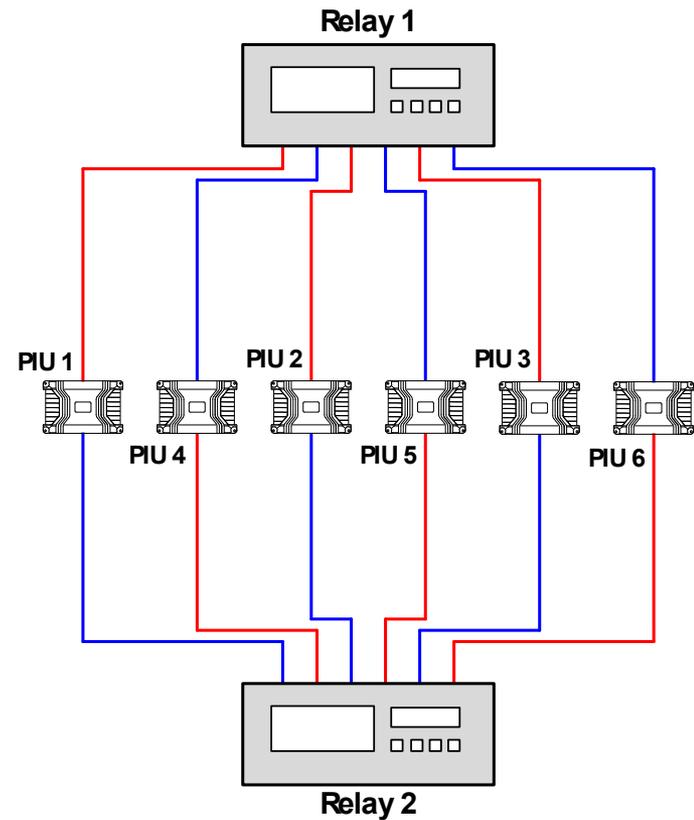


Architectures

Architecture 1: Independent Point-to-Point Process Bus



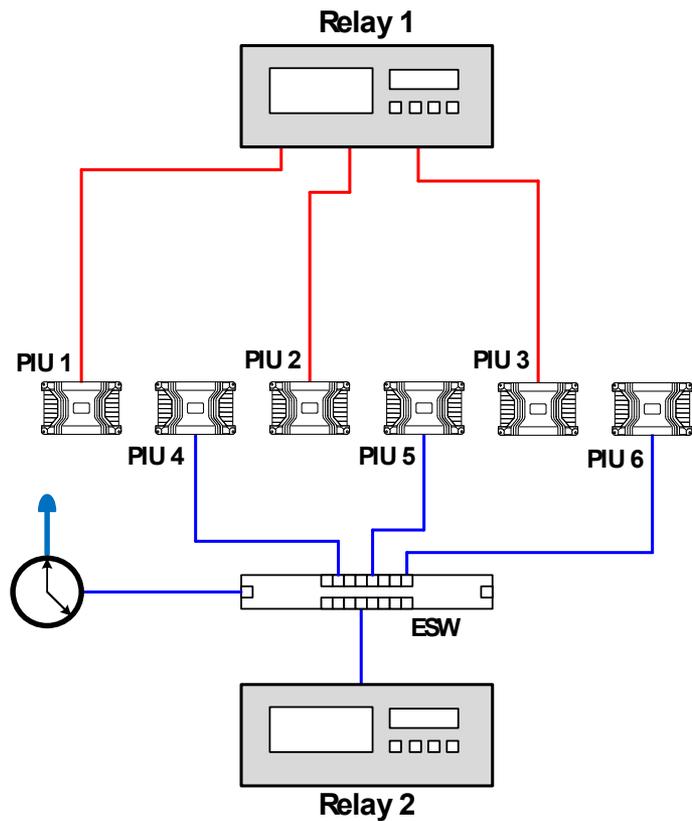
Architecture 2: Interoperable Point-to-Point Process Bus



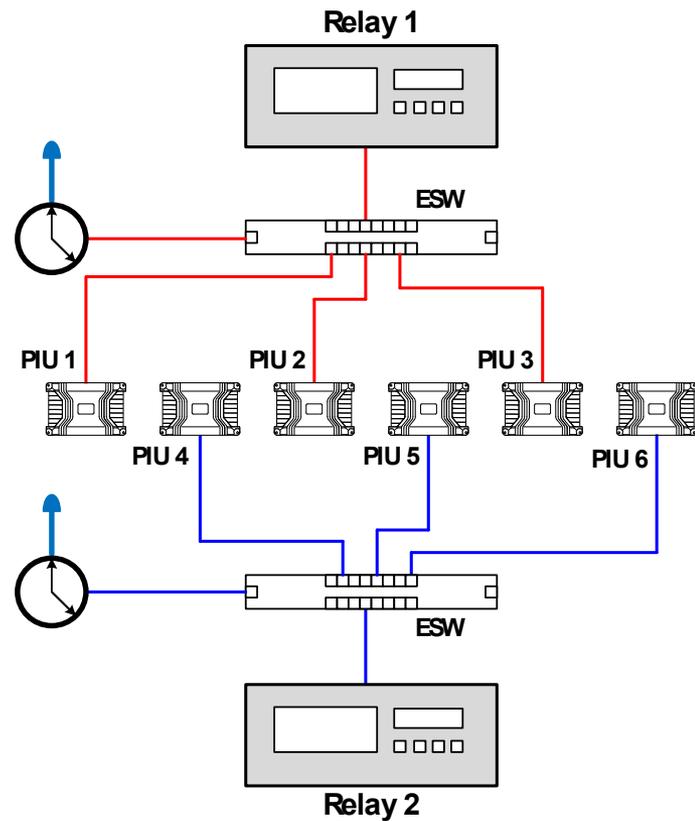
Architectures

- continued

Architecture 3: Point-to-Point / Network Process Bus

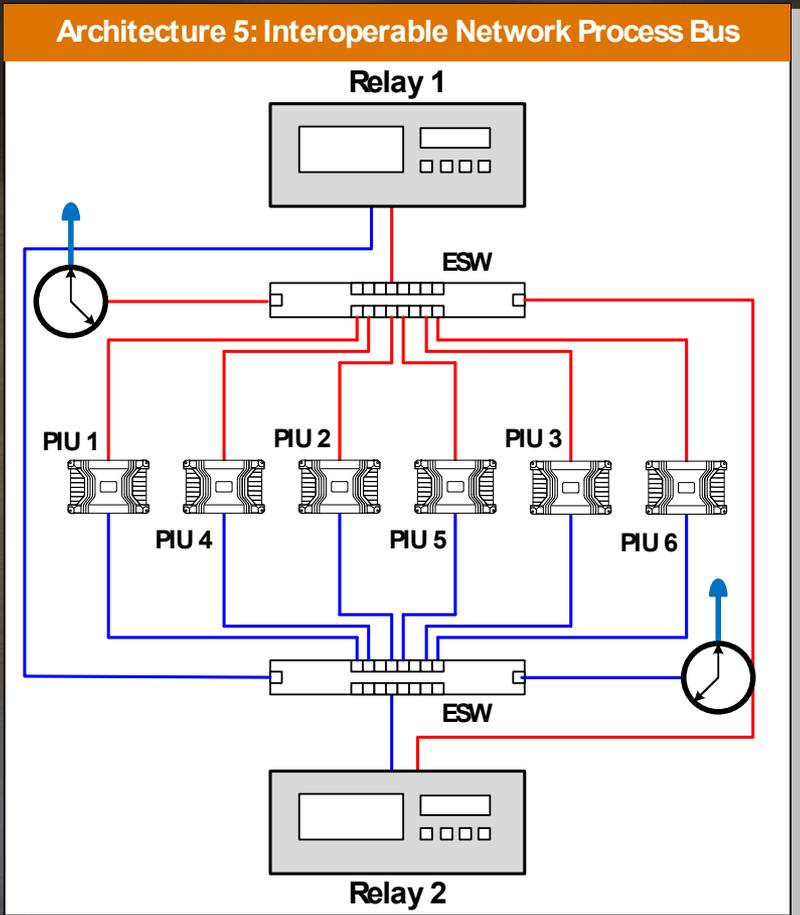


Architecture 4: Independent Network Process Bus



Architectures

- continued



- All architectures are legitimate
- All have advantages / disadvantages in terms of cost, performance, reliability, usability
- Fault tree analysis shows any of these architectures will be as available as conventional protection

Reliability Analysis

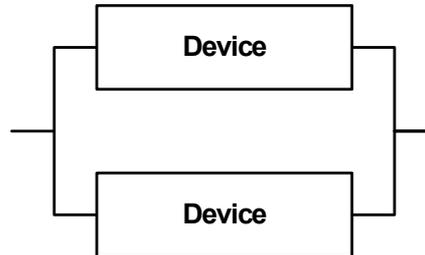
Reliability is defined by $R(t) = e^{-\lambda t}$ where $\lambda = \frac{1}{MTTF}$

Reliability in concept (identical devices)

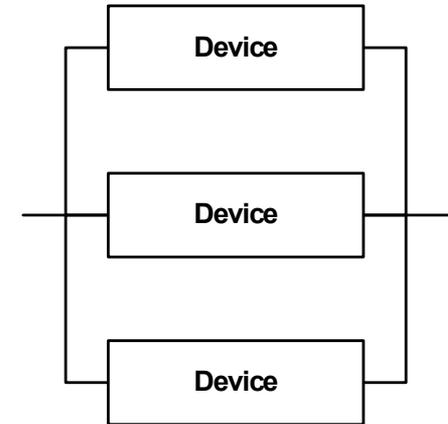
MTBF = $\frac{1}{2}$ MTBF of individual device



MTBF = 1.5 x MTBF of individual device



MTBF = 1.83 x MTBF of individual device



System Reliability Analysis

Actual device data

	General		At 1 year		At 10 years		At 20 years		At 30 years	
	Availability	MTBF	Reliability	Prob of Failure						
Conv.	1.00000	300	0.99998	0.0%	0.99762	0.2%	0.99094	0.9%	0.98060	1.9%
Option 1	1.00000	47	0.99903	0.1%	0.92659	7.3%	0.78053	21.9%	0.62486	37.5%
Option 2	1.00000	47	0.99974	0.0%	0.97646	2.4%	0.91522	8.5%	0.82995	17.0%
Option 3	1.00000	33	0.99586	0.4%	0.79411	20.6%	0.55853	44.1%	0.39599	60.4%
Option 4	1.00000	11	0.98232	1.8%	0.42253	57.7%	0.11196	88.8%	0.02749	97.3%
Option 5	1.00000	11	0.99183	0.8%	0.60797	39.2%	0.24339	75.7%	0.08357	91.6%

- Ethernet switches, clocks, clock antennas are the weak links

System Reliability Analysis

Ideal device data

	General		At 1 year		At 10 years		At 20 years		At 30 years	
	Availability	MTBF	Reliability	Prob of Failure						
Conv.	1.00000	300	0.99998	0.0%	0.99762	0.2%	0.99094	0.9%	0.98060	1.9%
Option 1	1.00000	69	0.99954	0.0%	0.96226	3.8%	0.87695	12.3%	0.77256	22.7%
Option 2	1.00000	69	0.99988	0.0%	0.98899	1.1%	0.95873	4.1%	0.91349	8.7%
Option 3	1.00000	59	0.99933	0.1%	0.94680	5.3%	0.83418	16.6%	0.70570	29.4%
Option 4	1.00000	47	0.99901	0.1%	0.92501	7.5%	0.77655	22.3%	0.61918	38.1%
Option 5	1.00000	47	0.99983	0.0%	0.98391	1.6%	0.94010	6.0%	0.87573	12.4%

- Assumes all devices have an identical MTBF of 200 years.

Comments on Reliability Analysis

Simplistic modeling

- Assumes failed devices aren't replaced
- Assumes replacement devices have same reliability, are same age as failed devices

In practice, reliability will be better than this

Obvious conclusions:

- Point-to-point is better than LAN (fewer devices in critical path)
- Redundant point-to-point is better (parallel paths)

Practical Considerations For Reliability

System Design

- Point-to-point: MTBF of 50 years, 95% reliability over 20 years
- Can we make LAN match this?
- Switches and clocks are the weak link
- Triple redundant networks, triple redundant clocks don't really improve MTBF, reliability
 - Clock ---> 11 years for 1, 17 years for 2, 20 years for 3
 - Not a practical solution anyway

Practical Considerations For Reliability

Device Design

- Make devices better
- To have a system MTBF of 50 years on LAN

$$MTBF = 50 = \frac{MTBF \text{ per device}}{6 \text{ devices}}$$

- Individual devices must have MTBF of 200 years
 - Relays there, possible for PIUs
 - Difficult for clocks (antennas, oscillators, transceivers)
 - Not really possible for switches (transceivers, power supplies). Already really optimized

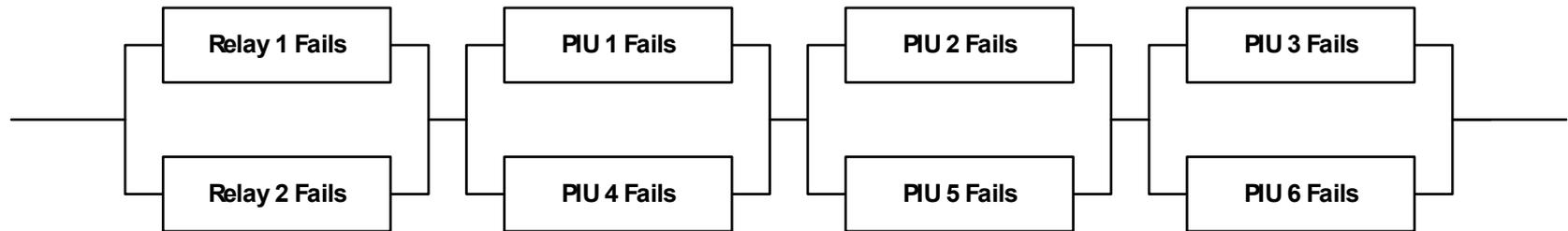
Practical Considerations For Reliability

Make Repair Better

- Focus on MDT (Mean Down Time) or PDT (Process Down Time)
- PDT is total time down for problem diagnosis, device repair / replacement, testing
- Must focus on PDT for process bus
- Process bus PDT can (and should, and must) be lower than conventional PDT!

Making Protection And Control Systems Easier To Maintain

Reliability Model: Redundant Point-to-Point

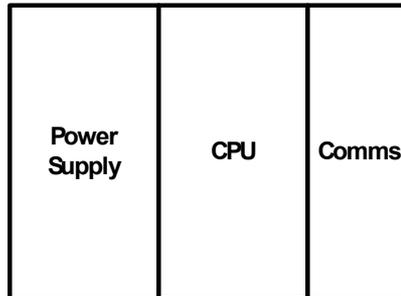


- System works with any individual device failure
- Treat devices as “black boxes”, or modules
 - Connectorized, defined functions
 - Simple swap out to replace failed unit
 - Don't test, don't analyze, just replace on alarms

Reducing PDT

Process Bus: Ideal Devices to Reduce PDT

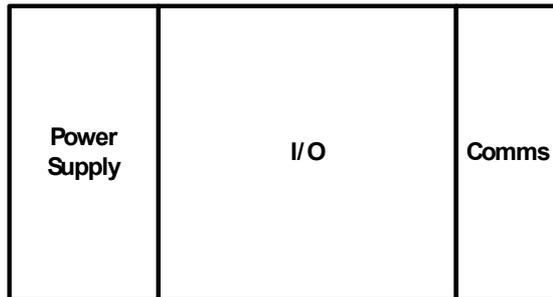
Relay



Simple field replacement through
"plug and play"

- ### Relay
- Plug in power supply for simple field replacement
 - Plug in communications module for simple replacement
 - Reduces PDT for most common failure components towards 0

PIU or I/O Device

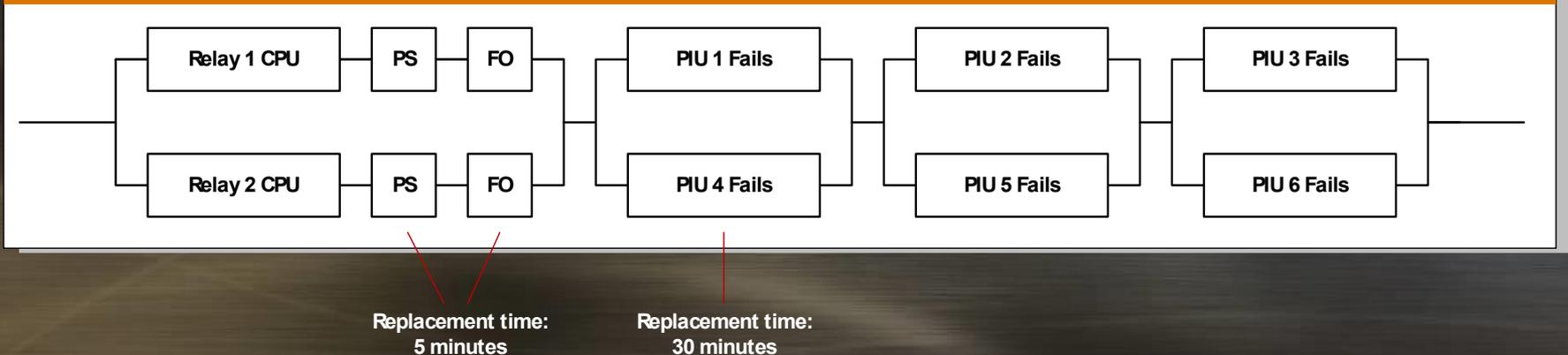


Connectorized field wiring
Remove and replace entire unit without
recommissioning

- ### Distributed I/O
- Connectorized field wiring to support simple physical replacement
 - Settings free device to support only simple physical replacement
 - No recommissioning necessary on replacement reduces PDT towards 0

Reducing PDT

Reliability Model: Redundant Point-to-Point, Designed for Replacement



- Power supply and transceivers are plug-in modules
- PIUs can be easily designed as modules
- Even Relay CPU / application replacement is simpler

Conclusions

- The real concern with protection and control systems is PDT
- PDT is better with process bus
- Repair process is swap out failed devices
- Can implement “run to failure” modes, regular replacement cycles
- Makes device failure and repair a known, predictable quantity

Thank You

Questions?