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REQUIREMENTS FOR AND PRACTICAL EXPERIENCE ON PARTICULAR GENERATOR PROTECTION FUNCTIONS

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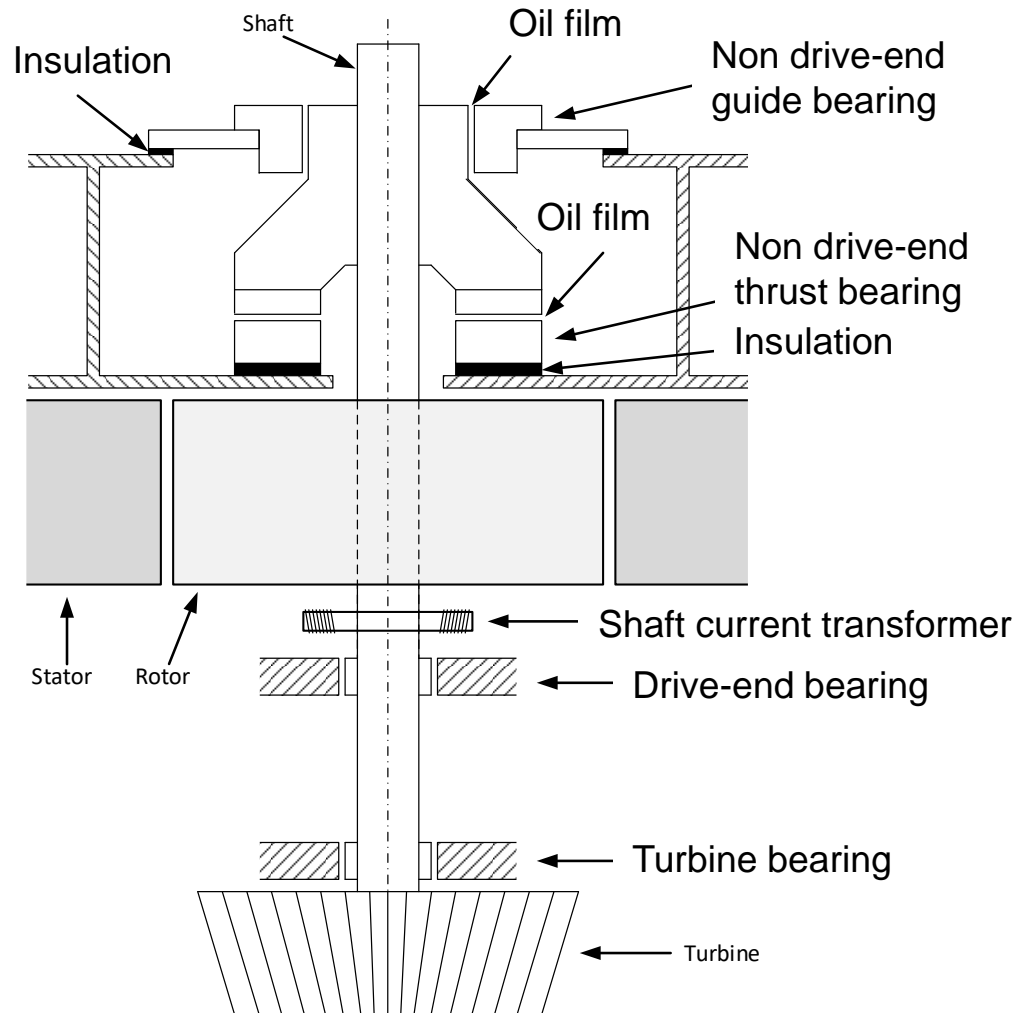
Statkraft Energi

Norway

Introduction

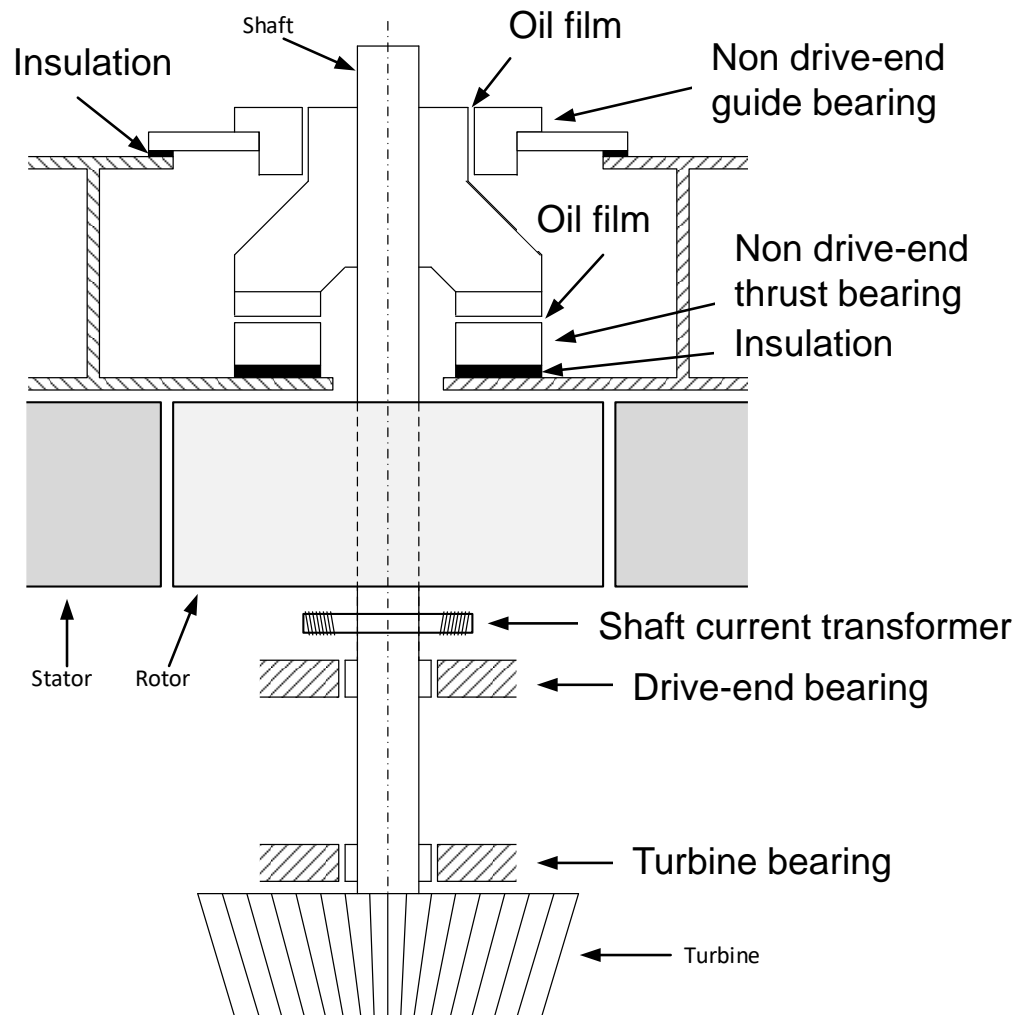
- Statkraft
 - owns and operates
 - \approx 90 hydro power plants in Norway
 - > 340 hydro power plants globally
- Generator protection
 - includes differential, impedance-based, overcurrent functions
 - includes also functions specific for generator protection
 - presentation overview
 - shaft overcurrent protection
 - injection-based 100% stator ground fault protection
 - generator out-of-phase synchronizing
 - hydro generator islanding operation

Shaft overcurrent protection



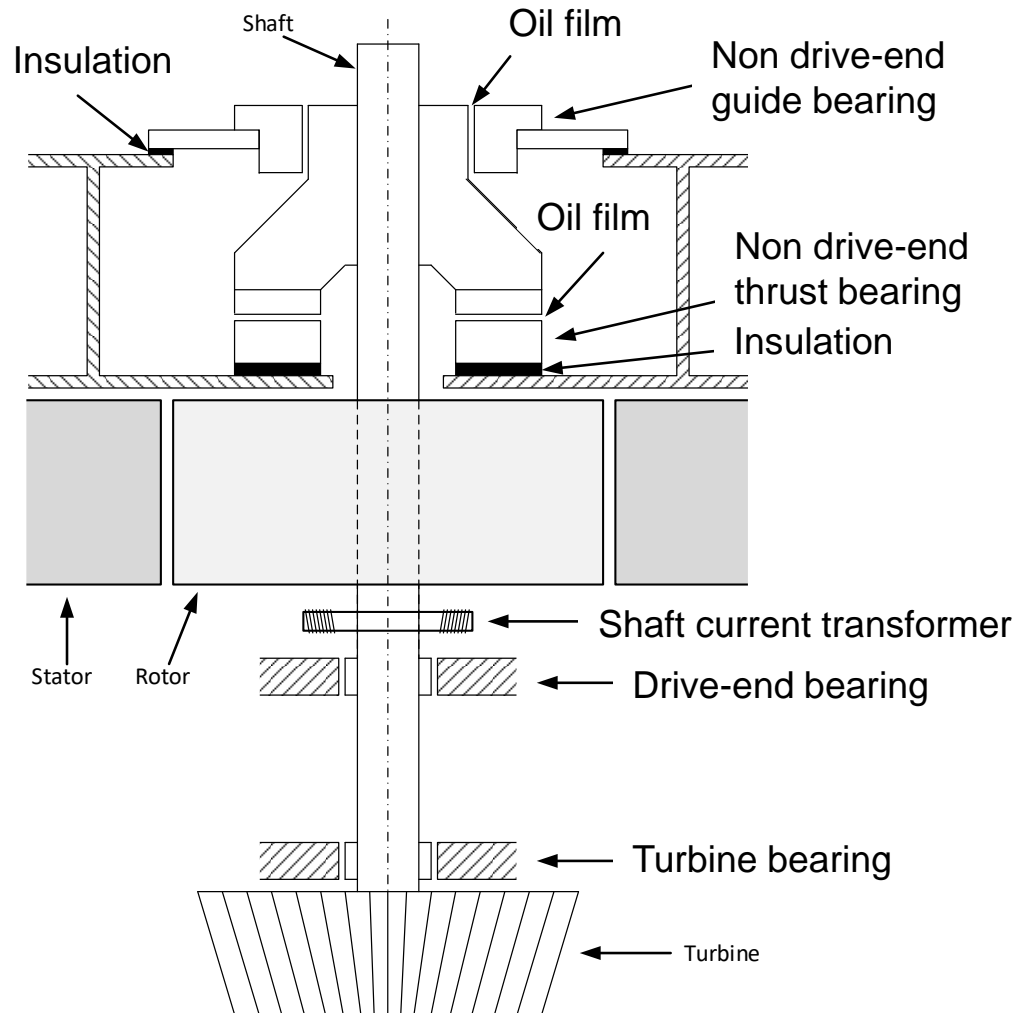
- When a generator is excited it can induce a voltage along the shaft
- This induced voltage is caused by asymmetry in the stator core - how high the magnitude of this will be depends on the stator construction
- If the shaft voltage is higher than one volt (1V), shaft overcurrent protection (or other types of mitigation) should be considered

Shaft overcurrent protection



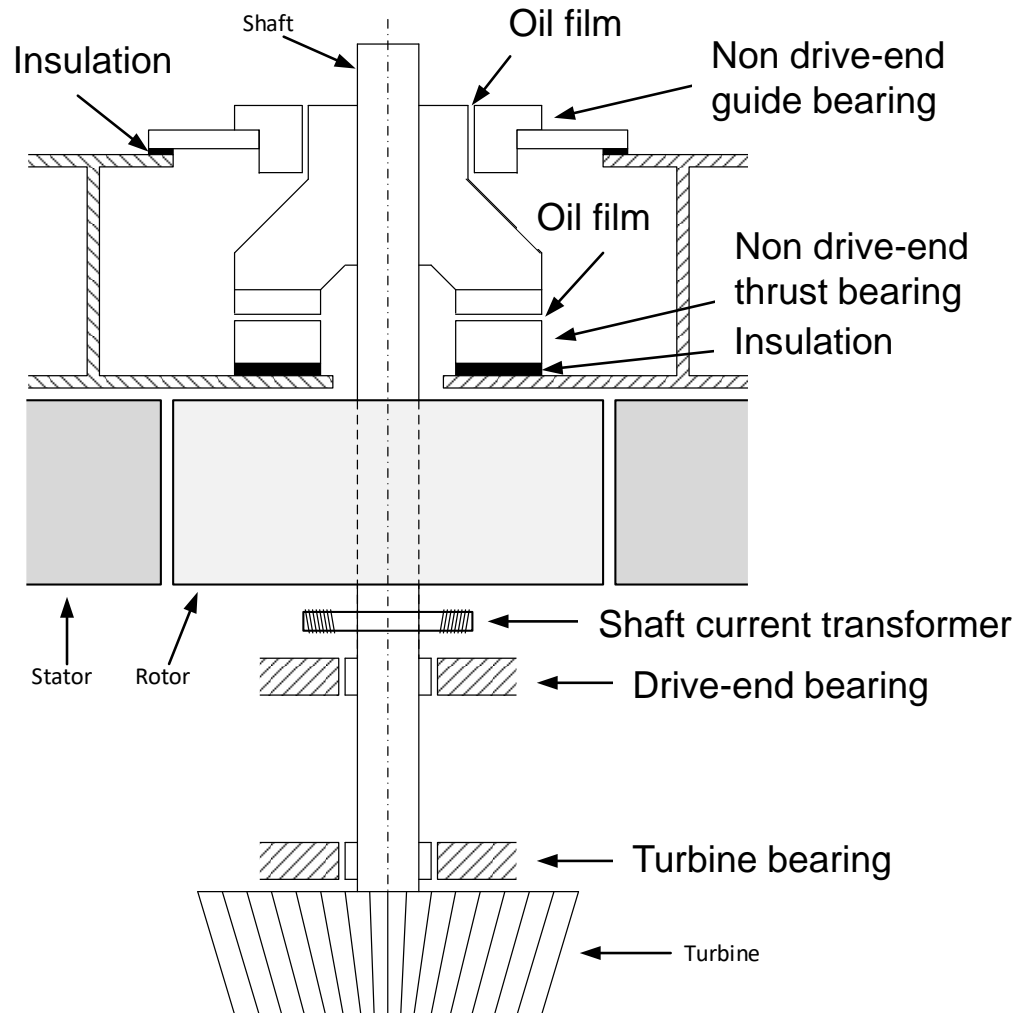
- Turbine and drive-end bearings are normally grounded
- Non drive-end bearings are normally isolated
- Non drive-end bearings
 - there is an oil film between the shaft and the bearing
 - there is insulation between the bearing and ground
 - normally the shaft voltage will be present between the bearing and ground
 - if the bearing insulation is broken due to a fault, the shaft voltage will be present between the shaft and the bearing, i.e. over the oil film

Shaft overcurrent protection



- If this voltage is too high
 - the oil will lose its electric insulation ability and a current will start to flow between the shaft and ground through the oil film
 - if this shaft current is too high
 - the oil film will lose its lubrication abilities and the bearing may be destroyed
- Statkraft installations – shaft currents of up to $\approx 70\text{A}$ have been measured, but normally the shaft current is lower than 10A
- Statkraft practice
 - 1V induced voltage is the limit to install shaft overcurrent
 - 1A shaft current is considered to be the max allowed

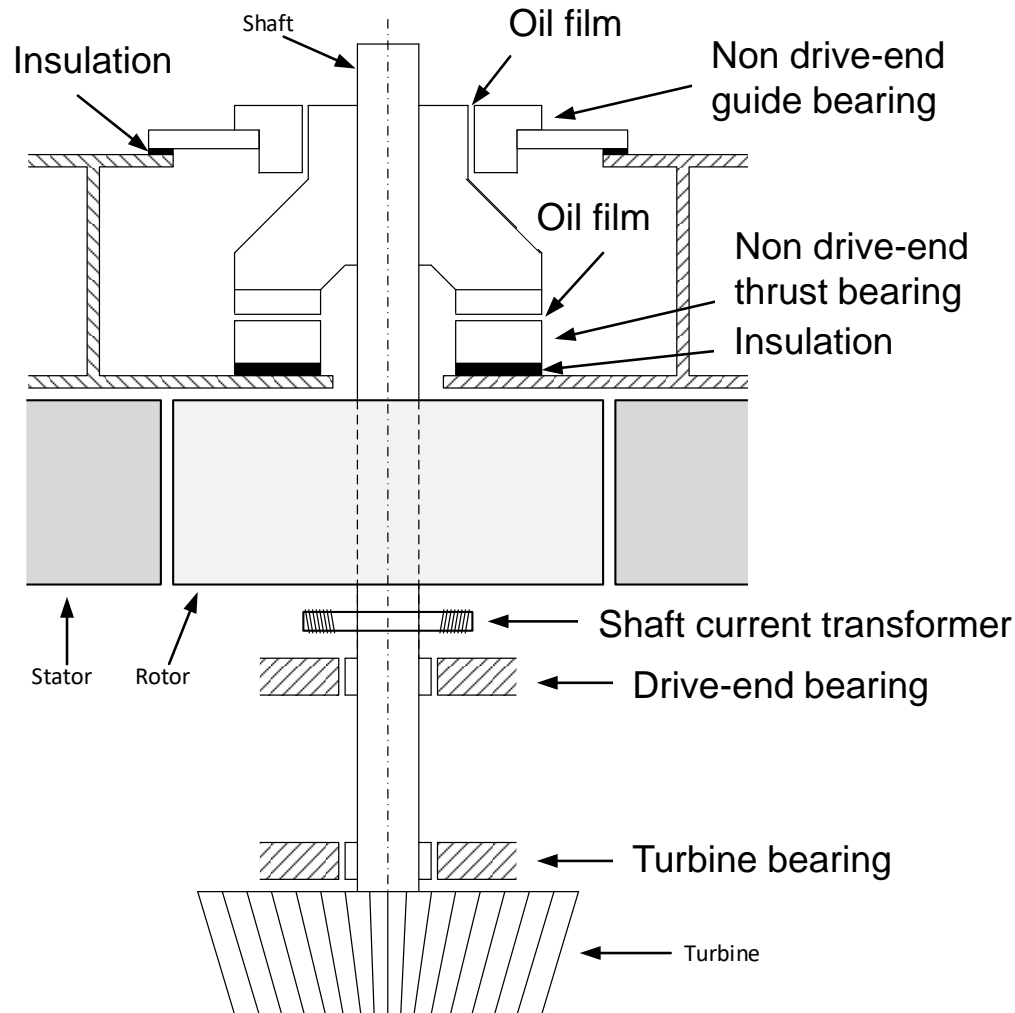
Shaft overcurrent protection



- Old Solution

- use magnetic core CT to measure the shaft current
- split core but still bulky and heavy
- very difficult to mount in a confined space
- requires specialized magnetic material
- very low secondary current (500-1000 turns)
- secondary winding connected to overcurrent protection
- difficulties to produce it in recent years

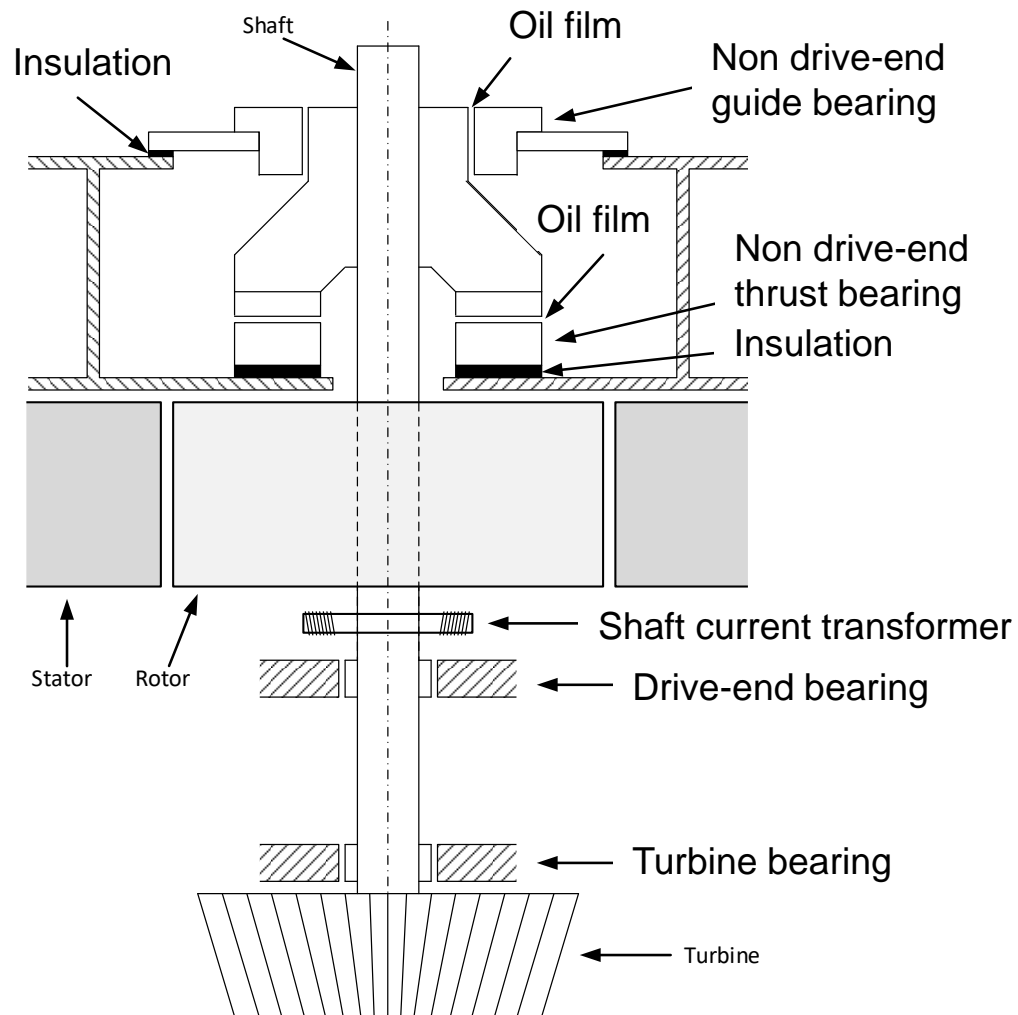
Shaft overcurrent protection



- New Statkraft solution

- Rogowski coil – output is a voltage signal proportional to the rate of change of the shaft current
- wall-mounted box containing electronic equipment
 - located 10m away from the Rogowski coil to minimize any influence from stray flux - coaxial cable connection
 - analog integrator – output is a voltage signal proportional to the shaft current magnitude, e.g. 200mV per 1A shaft current
 - amplifier to amplify the output voltage from the integrator (40x)
- connected to the IED in control room (via 1.5mm² twisted pair)

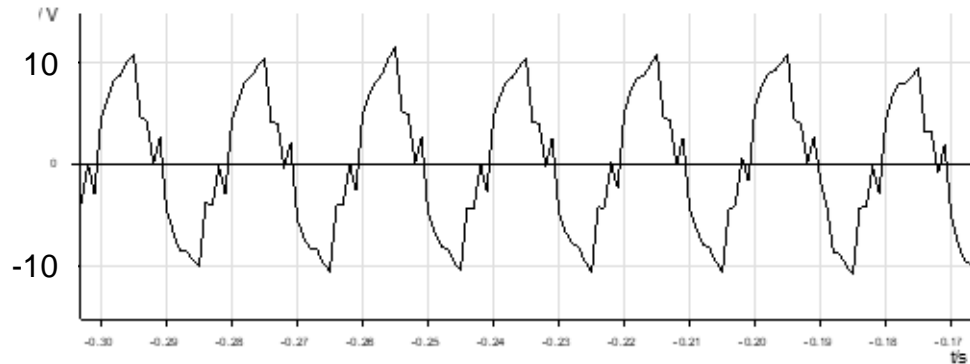
Shaft overcurrent protection



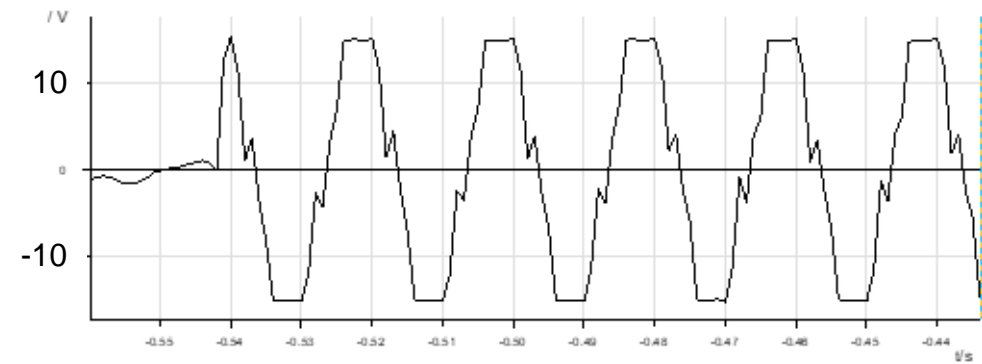
- New Statkraft solution

- amplifier output connected to the voltage input of a generator protection IED
- precise filtering filters out the required frequency component (typically either fundamental or 3rd harmonic)
- overvoltage protection having two stages (e.g. alarm and trip stage) within the IED
 - alarm: $0.25A_{pri}$
 - trip: $0.8A_{pri}$

Shaft overcurrent protection



Measured voltage by the IED during primary testing

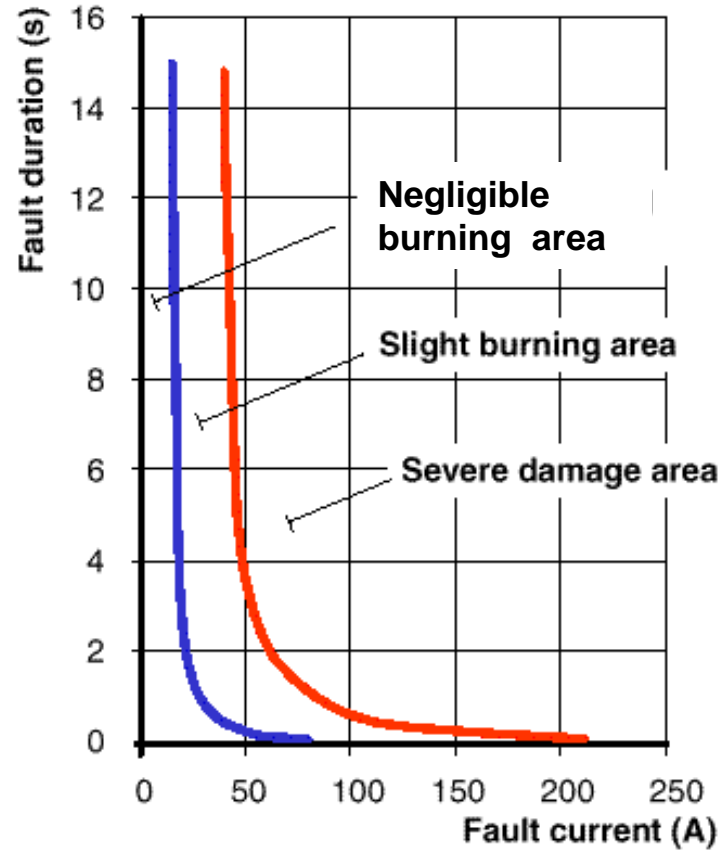


Measured voltage by the IED during an actual fault (2021)

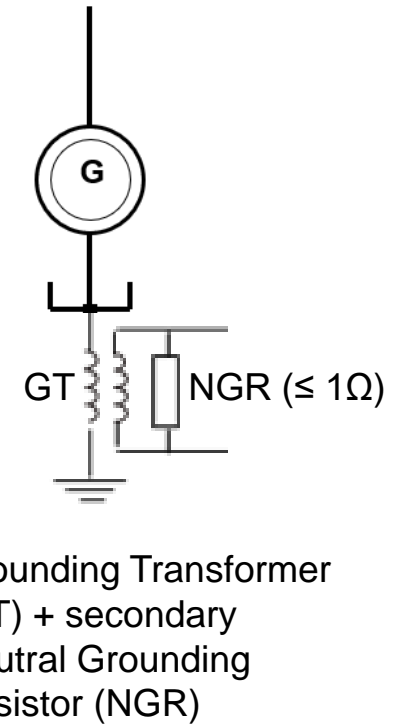
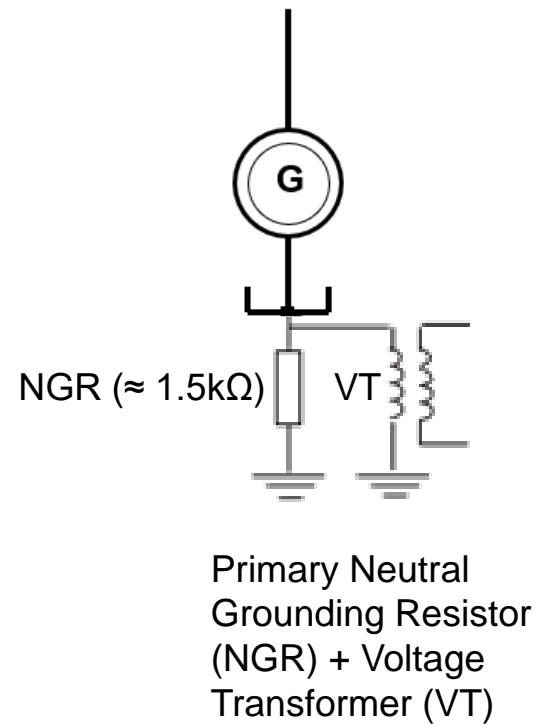
- 10V corresponds to a shaft current of 1.25A
- filter set to 50Hz

- The Rogowski scheme has been in successful operation in several Statkraft hydro stations for several years
- Several new sites/installations are in the pipeline

Stator ground fault protection

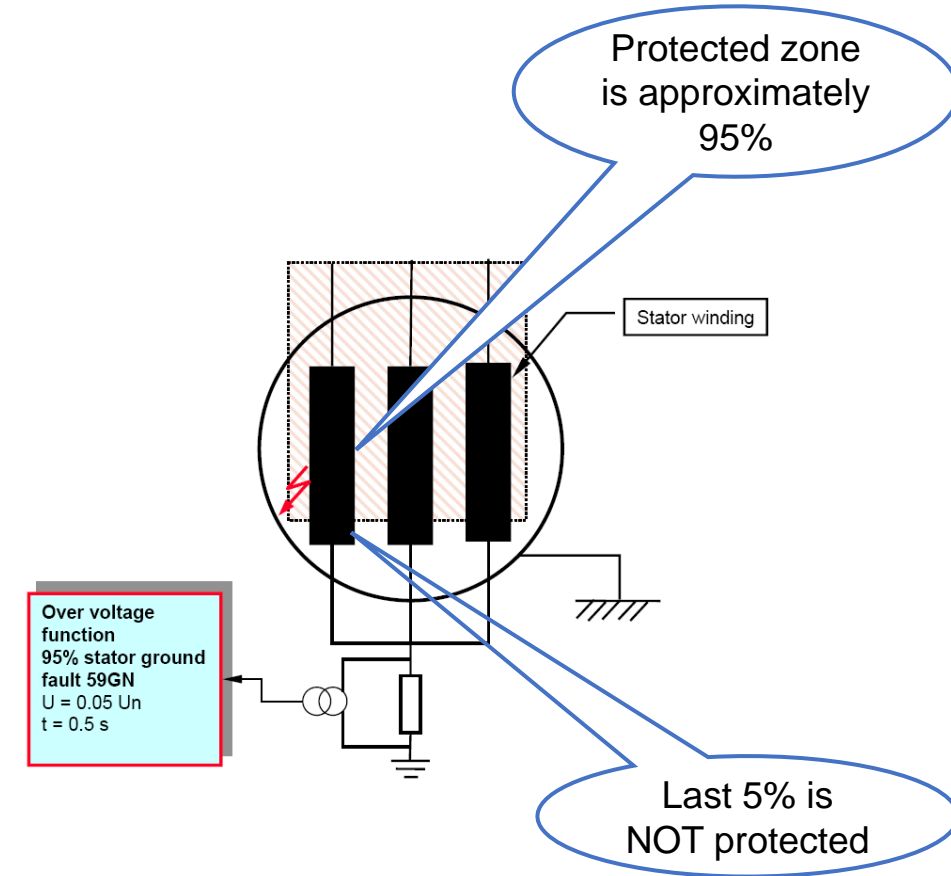


- Grounding methods



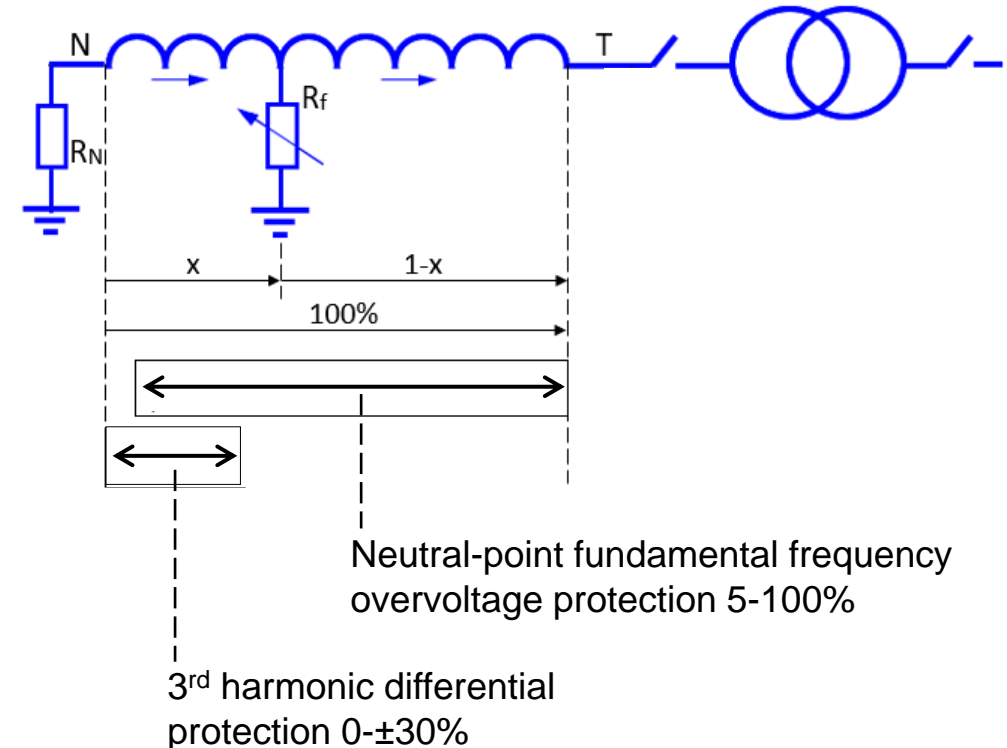
Stator ground fault protection

- 95% stator ground fault protection
 - stator ground faults cause a displacement of the generator neutral-point voltage – the magnitude of the neutral-point to ground voltage depends on where the ground fault occurs
 - = zero for a ground fault at the neutral-point
 - = the rated generator Ph-G voltage for a ground fault at the terminals
 - to detect, measure the voltage between the generator neutral-point and ground
 - even when healthy, a small amount of zero-sequence current will flow – the neutral-point therefore has a non-zero voltage
 - a 59N function will not remain selective if set too low
 - typical setting: pickup 5% of rated Ph-G voltage → 95% stator ground fault protection



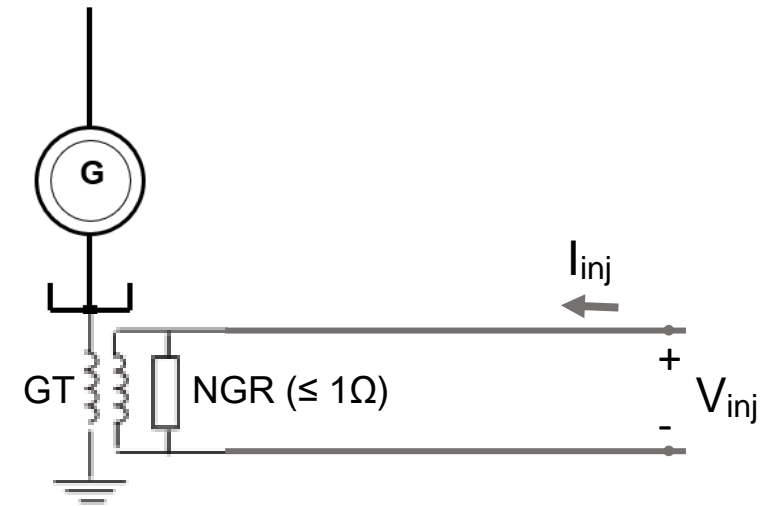
Stator ground fault protection

- 3rd harmonic-based 100% stator ground fault protection (100% together with 59N / 51N)
 - based on measurement of the 3rd harmonic voltages generated by the machine
 - provides stator ground fault protection for the so far uncovered last 5%
 - reason to cover the last 5%: a ground fault at or near the neutral-point shunts the high resistance, and so poses a serious threat should a second ground fault occur elsewhere in the stator winding
 - drawbacks
 - requires machine to be excited and able to generate sufficient 3rd harmonic voltage
 - cannot detect a ground fault when the machine is at standstill



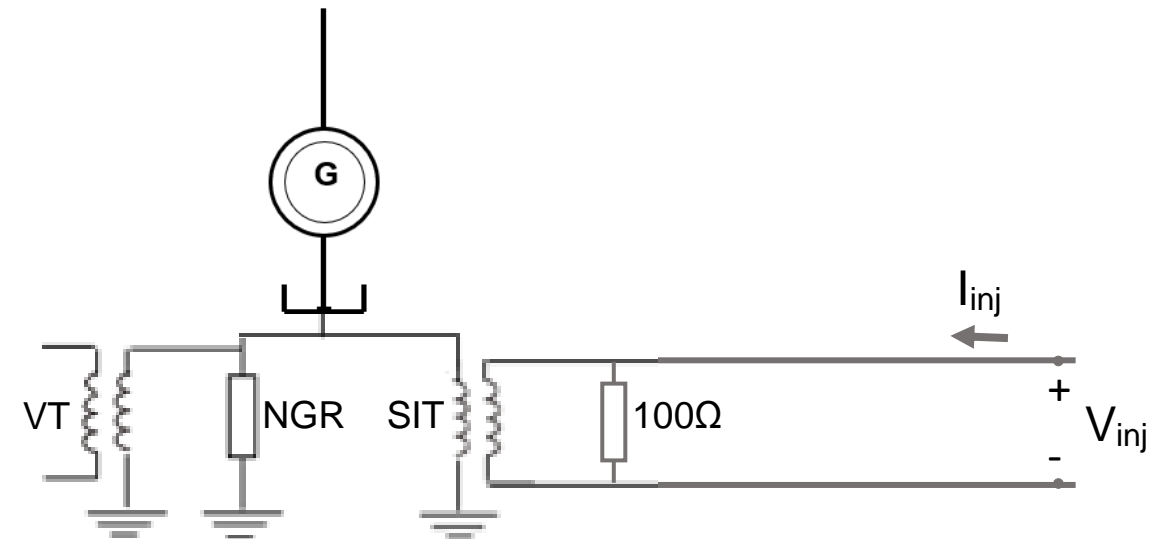
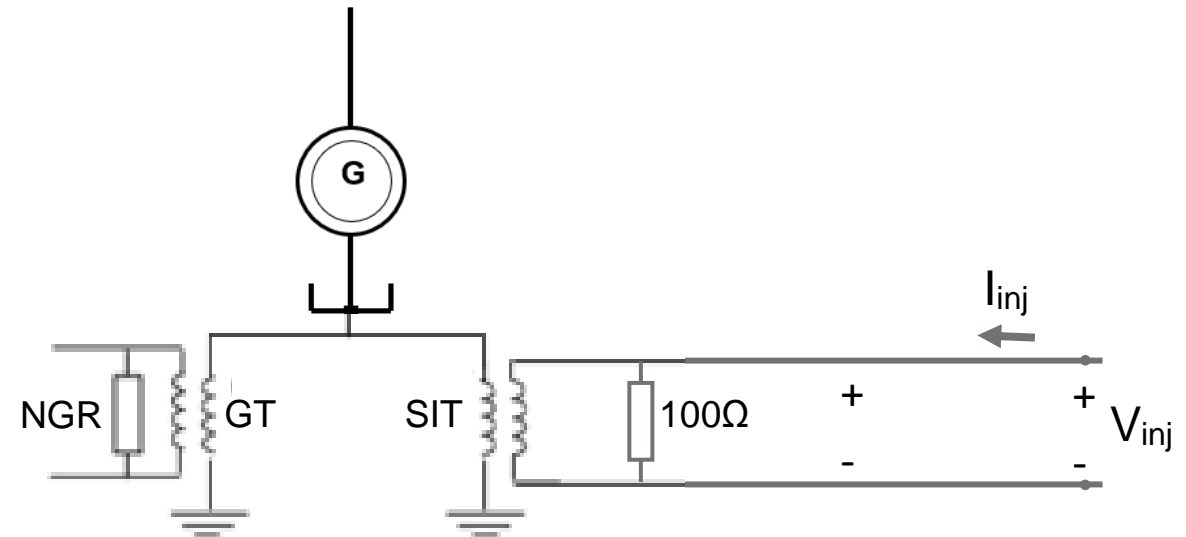
Stator ground fault protection

- Injection-based 100% stator ground fault protection
 - main challenge
 - injection is done through almost a “short circuit”
 - e.g. in the case when a GT with secondary NGR is used for stator grounding
 - for very large turbo machines, the NGR can have a value as low as 0.05Ω (typically $\leq 1\Omega$)
 - limited sensitivity as not much of the injected signal power is being transferred to the stator (thermal rating of injection equipment limits the amount of current which can be injected)
 - for a ground fault at the stator terminal a voltage will be pushed back onto the injection equipment, which must be designed to handle this



Stator ground fault protection

- Injection-based 100% stator ground fault protection
 - incorporate a dedicated Signal Injection Transformer (SIT) → universal way to inject into the stator regardless of the actual grounding arrangements
 - the generator neutral-point must be accessible
 - reliable 100% stator ground fault protection can be achieved by proper SIT design and the level of the injected signal – i.e. by ensuring that a sufficient amount of the injected signal power is transferred into the stator primary circuit
 - detects a change in the measured impedance from a reference value obtained during commissioning



Generator out-of-phase synchronizing (OOPS)

- An OOPS incident is hazardous (high forces and currents that can cause damage) to
 - stator windings; rotor damper (amortisseur) windings; shaft; circuit breaker (if it is tripped)
- The forces depend on how big the phase angle was between the generator and grid voltages
 - the larger the OOPS angle, the larger the OOPS forces (currents)
- From the perspective of the CB
 - closing for an OOPS is not a problem
 - opening (trip by protection) following an OOPS exposes the CB to difficult operating conditions
 - the large DC time constant of the generator leads to a relatively slow decay of the DC component of the current
 - fast decrease of the AC component
 - delayed zero-crossings

Generator out-of-phase synchronizing (OOPS)

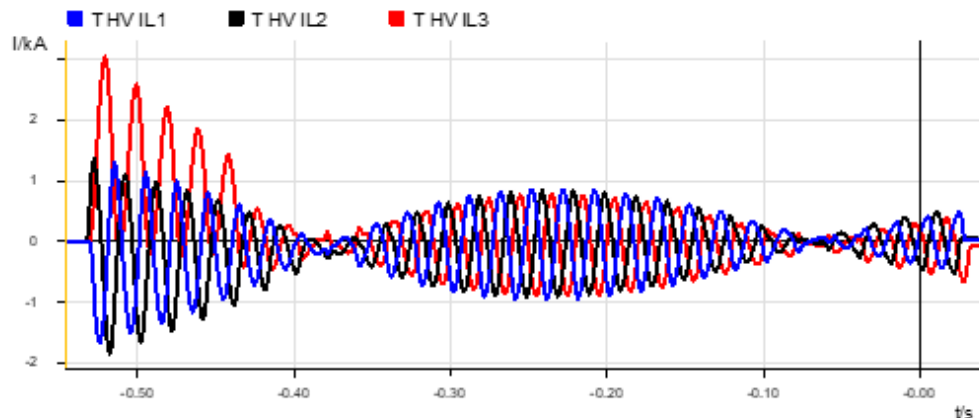
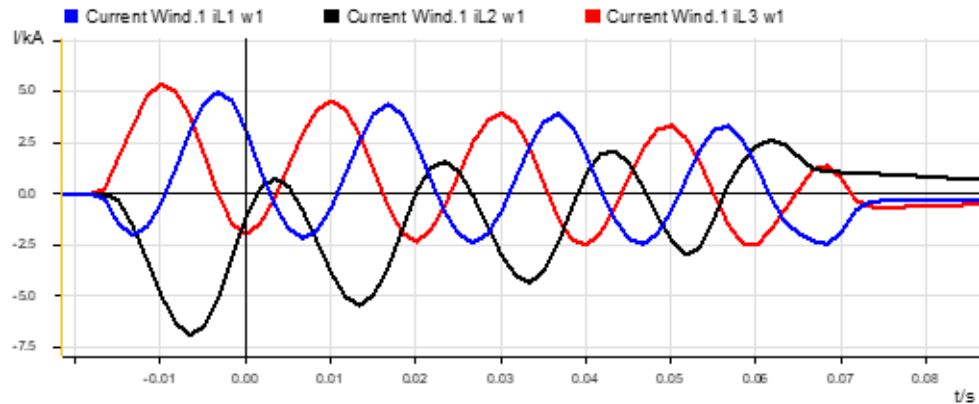
- Synchronizing the generator can occur by closing
 - the generator breaker; the HV breaker (HV-side of the GSU)
 - if an OOPS occurs when synchronizing (closing) the HV breaker, the forces on the generator will be less than if synchronizing with the generator breaker due to the GSU impedance
 - much of Statkraft's synchronizing is done via the HV breaker – avoids the high inrush currents when energizing the GSU from the grid

Generator out-of-phase synchronizing (OOPS)

- Depending on the OOPS angle, the recovery voltage (RV) and the transient recovery voltage (TRV) may be among the highest a circuit breaker may experience
 - the larger the OOPS angle, the larger the RV, the TRV and the OOPS currents
- Synchronizing via the generator breaker
 - has an OOP breaking capacity of 50% of the rated short circuit breaking current – may only correspond to a 90° out of phase angle
 - an OOPS angle of 180° might give a current up to 80% larger than for an OOPS angle of 90°
 - an OOPS current should be interrupted within 80-100ms after closing, before the AC component becomes too low (causing a delay in the zero-crossing) to ensure a successful interruption
- Synchronizing via the HV breaker
 - has an OOP breaking capacity of 25% of the rated short circuit breaking current
 - an OOPS angle of 180° might give
 - a current up to 40% larger than for an OOPS angle of 90°
 - and a 40% increased steepness in the TRV

Generator out-of-phase synchronizing (OOPS)

- Real OOPS events



- event 1

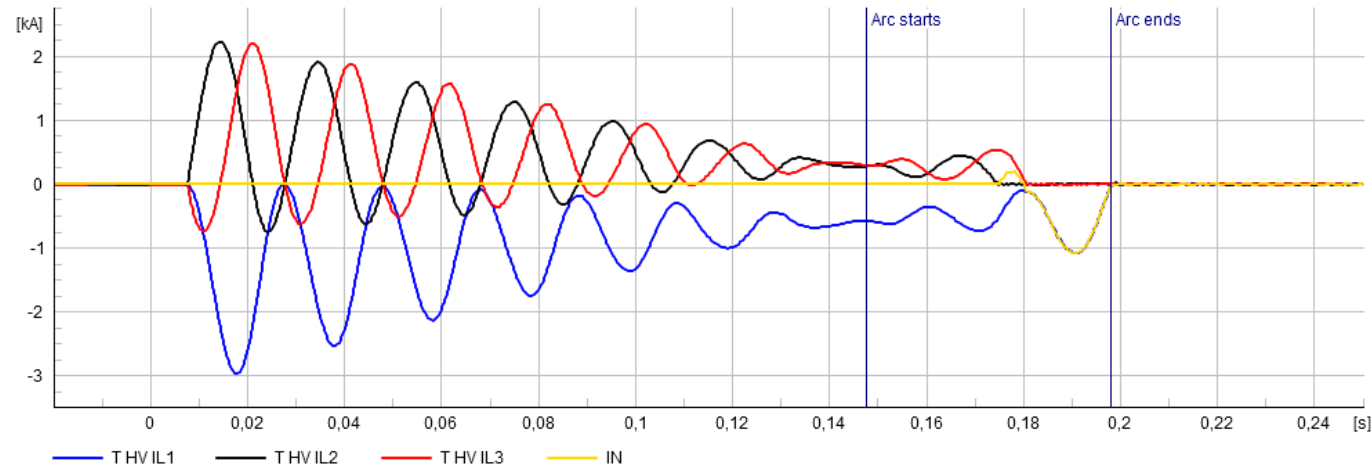
- synchronize (close) via HV breaker
- instantaneous trip – GSU HV-side overcurrent

- event 2

- synchronize (close) via HV breaker
- trip 533ms after the OOPS – GSU differential – should not trip for an OOPS, but due to CT saturation the differential current reached the trip level after some time

Generator out-of-phase synchronizing (OOPS)

- Simulated OOPS event



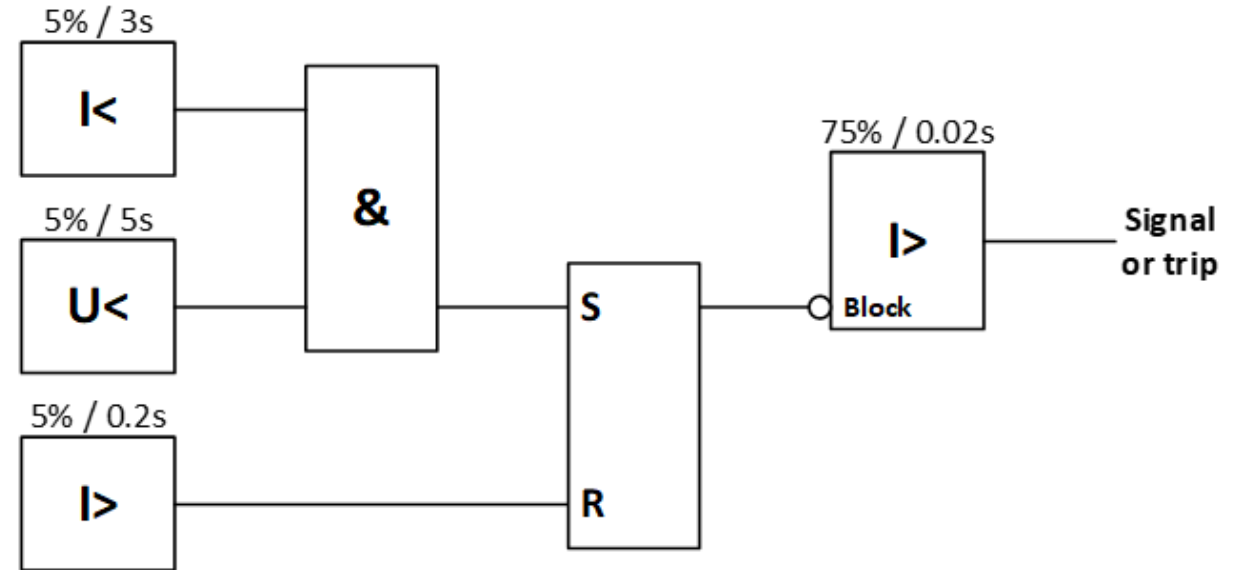
- close HV breaker, 90° out of phase, protection trip at +0.1s
 - the CB internal arcing begins at a very unfavorable moment (the AC component of the current is very low, and the current in one of the phases is almost pure DC)
 - in this case, for a trip signal with a 0.1s delay (or near to that), the arcing time will be so long (51ms) that the circuit breaker would most likely be destroyed
 - if the protection were to operate with a longer time delay (e.g. >0.2s), the DC component of the OOPS current would be much lower, and current zero crossings would occur, leading to much shorter arcing time

Generator out-of-phase synchronizing (OOPS)

- If an OOPS occurs it is likely that some protection will trip – differential, overcurrent – but an OOPS can also occur where no protection trips
 - the trip may be instantaneous, or in some cases time delayed
- For events 1 and 2, there was no dedicated OOPS protection function
 - the difference in the trip times was due to other protection functions tripping when their trip conditions were fulfilled
 - this means that the trip signal could occur in a timeframe which is unfavorable for the interruption of the OOPS currents, leading to higher arcing times than acceptable and causing possible destruction of the circuit breaker

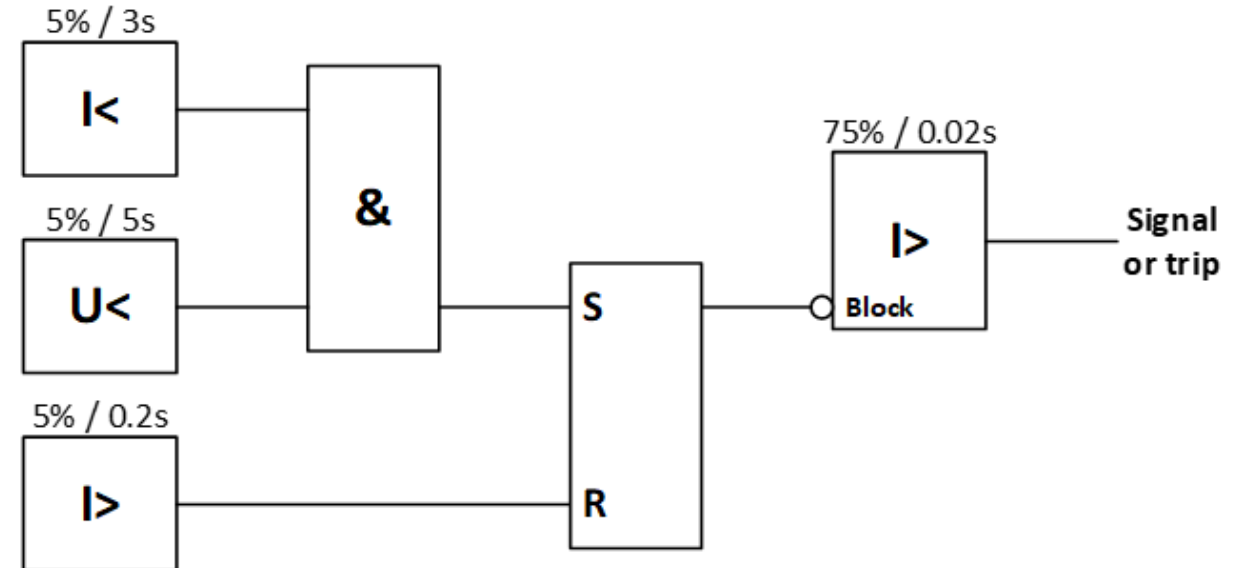
Generator out-of-phase synchronizing (OOPS)

- The Statkraft philosophy is that the generator (especially its damper windings), shall be inspected after an OOPS has occurred
 - how to know the OOPS has occurred?
- Logic was designed to detect an OOPS incident



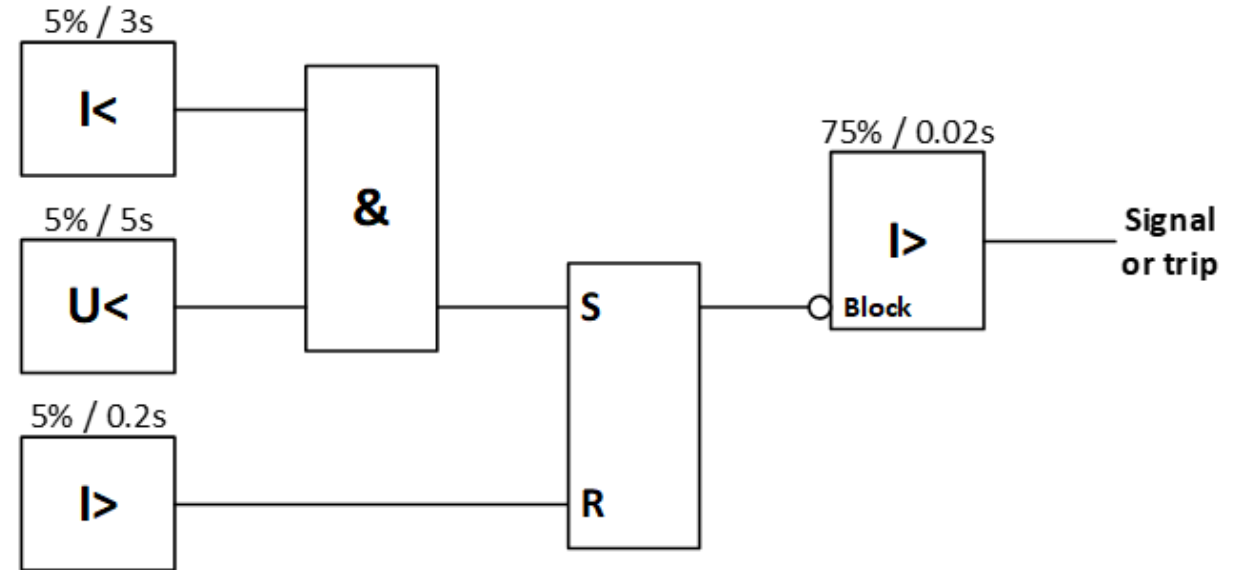
Generator out-of-phase synchronizing (OOPS)

- Statkraft have used this logic for a few years now, but only on the largest generators
- Presently only an alarm is given to SCADA by this logic (no trip issued)
- Current thinking – no gain by tripping
 - if the forces are high enough, other protection will trip
 - after an OOPS has occurred it may be harmful for the circuit breaker to be tripped
 - operational experience with this logic is limited, so need more experience to trust in its security
- to date there has been no unwanted operation of this logic



Generator out-of-phase synchronizing (OOPS)

- Further discussion
 - if an OOPS occurs should the generator always be inspected?
 - if the generator isn't tripped, is it then safe to operate it until the next planned outage?
 - no definitive answer yet, but the discussion is ongoing within Statkraft



Generator islanding operation

- In Norway islanding operation is quite common
 - the generation shall remain in service
 - required to withstand and operate for large frequency deviations from the 50Hz rated frequency (e.g. $\pm 10\text{Hz}$ – in some parts even up to 70Hz for 10s is possible)
 - grid code specifies requirements hydro power plants must satisfy – expected to operate normally within 45-60Hz

Allowed frequency deviation for network in Norway

Frequency region	Duration of required operation
45.0 Hz – 47.5 Hz	60 seconds
47.5 Hz – 49.0 Hz	30 minutes
49.0 Hz – 51.0 Hz	Unlimited
51.0 Hz – 53.0 Hz	30 minutes
53.0 Hz – 57.0 Hz	20 seconds
57.0 Hz – 60.0 Hz	10 seconds

- hydro power generators connected to the transmission grid
 - underfrequency
 - <45Hz
 - overfrequency
 - normally not used, but is permitted – must withstand a full load rejection

Proposed settings for under- and over-frequency protection

Generator rating	f<< Time delay	f< Time delay	f> Time delay	f>> Time delay
240 MVA	43Hz 0.1s	45Hz; 30s	57Hz 30s	70Hz 0.1s
130 MVA	43Hz 0.1s	45Hz 30s	55Hz 30s	65Hz 0.1s

Generator islanding operation

- The protection relays need to work correctly within the wide frequency range
 - poses no problem for the generator protection which is fully capable to track and adapt to the actual power system frequency
 - the distance protection on the power lines in the vicinity of the hydro power plants can be a real challenge due to the wide frequency range
 - the fixed X-reach in ohms will become variable with respect to the distance to fault due to the frequency excursion
 - line differential protection can be a possible better solution

Conclusions

- Several important but quite special protection functions/functionality for generator protection have been described
- Regardless of the complexity of such protection functions/functionalities, they can be implemented in a modern protection IED