

# Case study: Transformer Differential Incorrect Operation due to System Grounding

JC (Jacobus) Theron  
Snr Technical Applications Engineer  
GE Grid Solutions  
Calgary  
Canada  
Jacobus.Theron@ge.com

David Roh  
Utility Services Manager, Electrical  
University of Alberta  
Edmonton  
Canada  
david.roh@ualberta.ca

Lorne Clark  
Utilities Services Engineer  
University of Alberta  
Edmonton  
Canada  
lwclark@ualberta.ca

**Abstract** – Power system grounding is a key component of power system design and can have adverse effects to protection schemes. Particular protection functions that can be impacted are phase, neutral and negative sequence overcurrent, directional overcurrents, restricted ground fault and Transformer differential protection.

This paper discusses power system grounding, impacts of an in-zone solidly grounded parallel generator to the system and how this caused the transformer percentage differential to incorrectly operate.

Additional security measures added to the percentage differential is also presented to enhance transformer differential security against temporarily system grounding events causing circulating currents.

*Index Terms* — Transformer Differential (87), Percentage Transformer Differential, CT Saturation, Directionality Check, Instantaneous overcurrent (IOC or 50), time overcurrent (TOC or 51), Directional Overcurrent (67), Ground Fault Protection (GFP), Modified Differential Ground Fault, Intelligent electronic device (IED)

## I. INTRODUCTION

Power system grounding should be regarded as the connection of the three-phase AC power system to the mass of the earth, which is usually via the neutral terminal, to accomplish the following:

1. Provide a reference to ground for the power system
2. Stabilize the voltage during normal system operation
3. Limit the voltage rise on the power system occurring during abnormal system conditions such as ground faults, surges, lightning, unintentional contact with a higher voltage system or other abnormal system events
4. Safeguard against undue voltage stress on power system primary component insulation, such as cables, transformers, generators, motors.

A simple single ground on a power system typically would be grounded as follows:

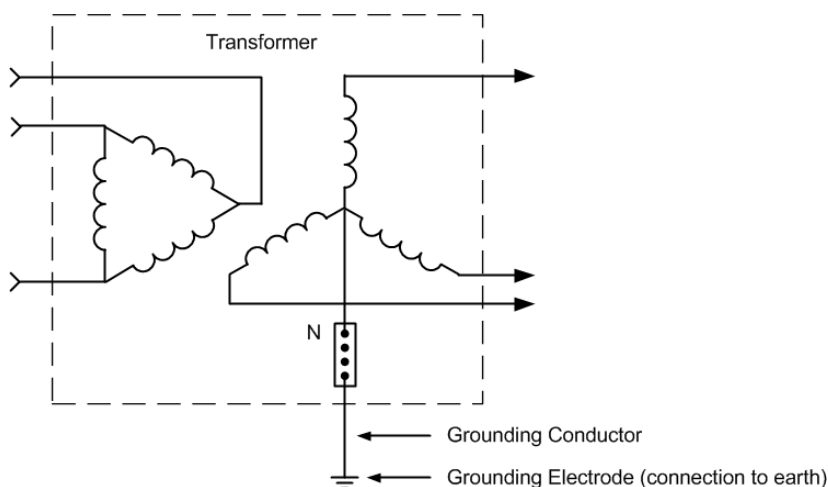


Fig 1: Simple Single Ground of LV Power System

All LV power system components must be electrically bonded and connected to ground; meaning interconnection of conductive materials enclosing electrical conductors and equipment must establish an equipotential plane such that the possibility of a potential difference between the exposed non-current carrying metal parts is minimized, as follows: (3-phase 4-wire LV power system)

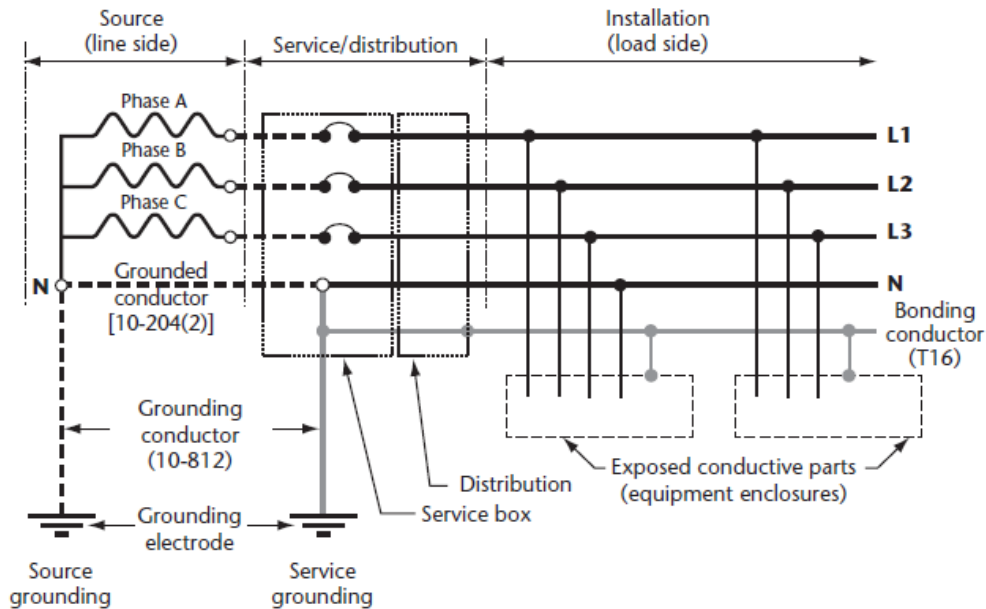


Fig 2: LV Bonding System and its Connection to Ground

The objective of equipment grounding and bonding is:

1. To provide adequate current-carrying capability in the ground fault return path for the duration of a ground fault without any equipment risk, e.g. overheating and fire
2. To provide a low-impedance path for ground fault current to facilitate the operation of overcurrent protective devices, including its coordination time
3. To reduce the risk of electric shock hazard to personnel

There are numerous standards addressing grounding, bonding and protection requirements of LV power systems. Some examples for single or multiple source LV 3-phase power systems are:

1. Canada: CSA C22.1-15
2. Canadian Electric Code CEC Rule 10-206
3. Canadian Electric Code CEC Rule 10-204
4. Canadian Electric Code CEC Rule 14-102
5. IEEE Green Book Std 142-1991
6. IEEE Orange Book Std 446-1995
7. USA National Electric Code NEC 230.95
8. USA National Electric Code NEC 250.24
9. USA National Electric Code NEC 250.30
10. USA National Electric Code NEC 250.5
11. USA National Electric Code NEC 250.21
12. USA National Electric Code NEC 250.23
13. USA National Electric Code NEC 250.26

## II. HISTORY OF LV POWER SYSTEM GROUNDING

Here's a brief history of LV power system grounding:

1. 1890's: Ungrounded 3-phase delta  
Power systems were initially ungrounded to power 3-phase squirrel-cage induction motors, and to protect personnel from hazards during ground faults. The consequence was that single-phase-to-ground faults could not be detected; only once it escalated to multi-phase faults with significant damage and danger. Furthermore, with no neutral voltage reference, phase-to-ground voltages were not controlled with insulation damage and higher voltage exposure risk to personnel.
2. 1920's: 120/240V, 1-phase ("high-leg delta") and 208Y/120V, 3-phase  
This was solid grounded with better ground fault detection
3. 1940's: Corner-of-Delta for 480V and 600V Delta Systems  
This was solidly grounded to prevent escalating system voltage to ground (5-6 times rated) during intermittent arcing ground faults in large LV systems from stray capacitance to ground.
4. 1950's: Solidly-grounded 4-wire, wye 600Y/347V and 480Y/277V Systems  
Fluorescent lighting came in use, which produced much less heat than incandescent lighting, however at this time, fluorescent lighting required more than 120V to operate.  
Service entrance ratings increased from 600A to 4000A as loads started to increase.  
To meet this increase of load demand, utilities changed from delta to wye secondaries on power transformers and started to deploy 277V and 347V line-to-neutral voltages while still providing 480V and 600V.  
Today, 90% of LV power systems uses this convention which are solidly grounded 4-wire wye.
5. 1960's: Devastating electrical equipment burn-downs on solidly grounded 480Y/277V and 600Y/347V systems occurred.  
This caused lots of fires, injuries and death, even though affected equipment were configured and protected in accordance with the CEC and NEC standards.  
A lot of these events occurred due to arcing ground faults that escalated into destructive three-phase arcing faults.  
Fuses and thermal magnetic circuit breakers did not interrupt the three-phase faults fast enough to protect primary equipment and personnel.
6. 1971: NEC added requirement for ground fault protection at service entrances, as per 230.95 (2014): (In effect today)

**230.95 Ground-Fault Protection of Equipment.** Ground-fault protection of equipment shall be provided for solidly grounded wye electric services of more than 150 volts to ground but not exceeding 1000 volts phase-to-phase for each service disconnect rated 1000 amperes or more. The

7. 1972: CEC added similar requirement as per 14.102 (2012): (In effect today)

### **14-102 Ground fault protection** (see Appendix B)

- (1) Ground fault protection shall be provided to de-energize all normally ungrounded conductors of a faulted circuit that are downstream from the point or points marked with an asterisk in Diagram 3 in the event of a ground fault in these conductors as follows:
  - (a) for circuits of solidly grounded systems rated more than 150 volts-to-ground, less than 750 V phase-to-phase and 1000 A or more; and
  - (b) for circuits of solidly grounded systems rated 150 V or less to ground and 2000 A or more.

### III. MULTIPLE SOURCES WITH SOLID NEUTRAL GROUNDS

The CEC and NEC rules require each source transformer of a LV power system to have a solidly grounded neutral (or neutral path). When it comes to the connection of a generator set to the LV power system, it might meet the requirements as a separately derived source and then its neutral must be solidly connected to that of the preferred source.

If a separately derived source meeting the requirements of NEC 250.20(B) includes an alternate power source whose neutral conductor is solidly connected to that of the preferred source, the alternate source neutral is considered grounded through the ground at the preferred source service disconnect. This means that, sometimes the neutral of a genset power source will be grounded at the genset neutral; other times, it won't. (To see what must be considered before deciding when to ground the neutral, see "When You Should Ground and Switch the GenSet Neutral" sidebar on page 31 and "When You Should Not ground the GenSet Neutral" sidebar on page 32.) of the NEC standard.

Grounding of a generator requirements are thus not clear-cut and must be reviewed.

Two major problems arise if the transformer and generator neutrals are grounded and tied together as per standard when using a 3-pole transfer switch or breaker:

1. Incomplete ground-fault sensing with a separate solidly grounded utility transformer and generator. Two neutral currents paths, due to the two separate grounds, will have each a neutral circulating current for single-phase-to-ground faults, as below

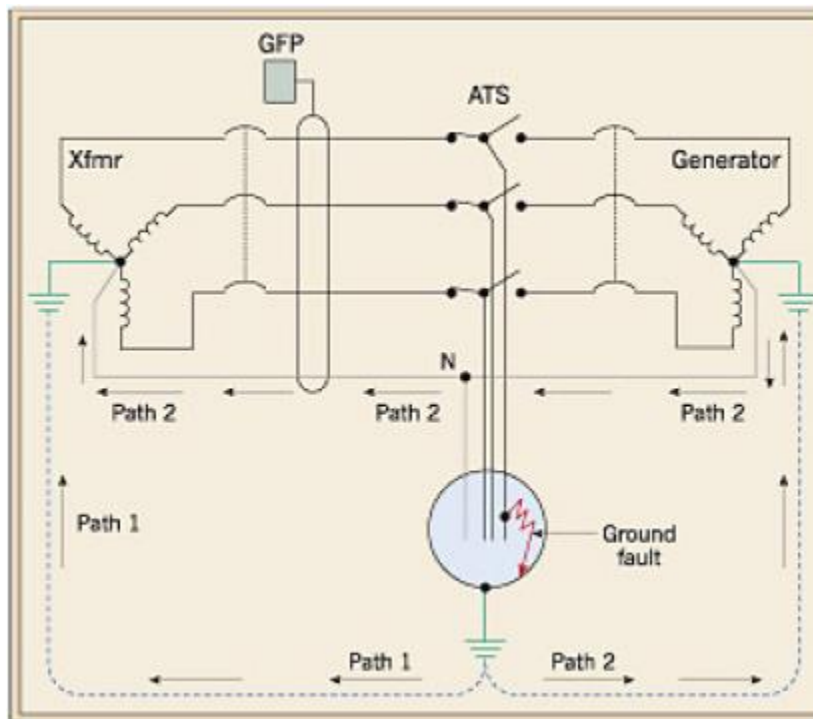


Fig 3: Circulating Ground-Gault currents for Transformer and Generator grounded separately

Path 1 is directly back to the transformer via the grounded-wye of the transformer.

Path 2 is along the solidly grounded neutral of the generator, then along the neutral conductor back to the transformer neutral. So, in this case, the transformer ground fault sensor (GFP) will see path 2 as if it is load current, and the zero-sequence GFP will sense only the fault current flowing from path 1. As a result, incomplete sensing of the total ground fault current is observed.

2. Nuisance tripping due to unbalanced load.

Again, the system will have two current paths due to an unbalanced load as below:

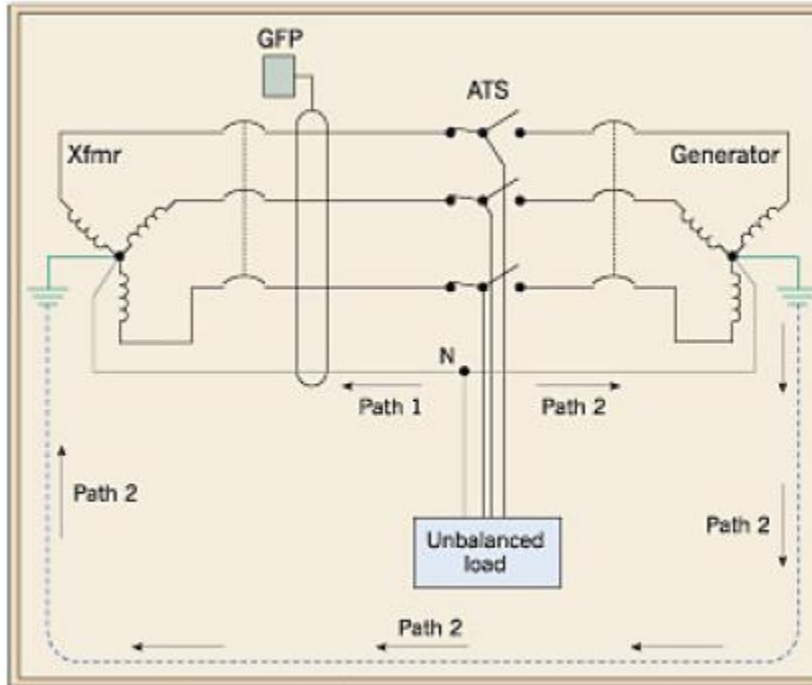


Fig 4: Circulating Neutral Unbalanced currents for Transformer and Generator grounded separately

Path 1 will be directly to the service neutral of the solidly grounded wye of the transformer and path 2 is the generator neutral current, circulating back to the transformer wye via the grounding of the generator metallic enclosure, conduit, fittings etc.

The path 2 current would have the same effect on the transformer GFP as a ground-fault current, therefore, an unbalanced load would have the same effect as a ground fault on the transformer GFP, even if there are no faults on the system.

The multiple paths of neutral currents can also be described as follows:

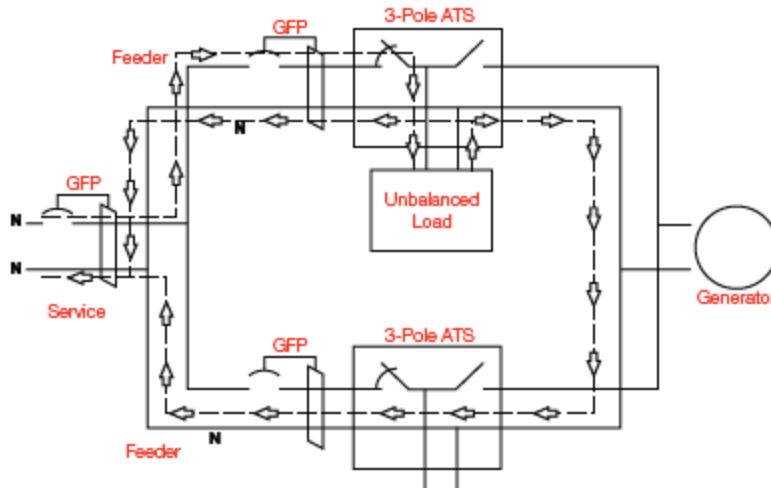


Fig 5: Multiple Paths for Neutral Currents on System with Multiple Grounds

3. Unbalanced currents due to generator paralleled with utility supply.

When a generator is operated in parallel with a Utility source, the voltage waveforms are likely to be somewhat dissimilar between the utility supply and generator and therefore result in neutral circulating current [5]. This can occur in either permanently paralleled applications or during closed transition transfers in peak shaving or back-up generation applications. Also, other sources of distributed generation, such as wind turbines, solar panels, fuel cells, microturbines, etc., can have excessive circulating neutral currents when paralleled with the Utility in 4-wire systems.

A solution to these separate circulating currents, is to use a 4-pole transfer switch by opening the neutral and to not ground the neutral a second time at the generator or ground the generator neutral and not connect the normal distribution and generator neutrals together. Switching of the neutral eliminates the extra neutral path. This is not always feasible for standby or emergency generator supplies.

Since there is no solid interconnection with the service-supplied neutral, the generator is considered a separately-derived system and its neutral must be grounded.

If the system has an emergency generator which is rated 277/480 or 347/600 wye, and the generator main disconnecting means is rated 1000 amps or more, NEC Article 700.7 (D) will require a ground fault indication on the generator. Note that this requirement is for an indication (alarm) only, and circuit interruption is not required. The NEC does not require that sensing ground fault current cause a trip that would result in a loss of power to emergency systems involving life safety. While ground fault indication is required by NEC above 1000 amps, it can be and often is provided on smaller systems below 1000 amps as well.

Sometimes the NEC requirement of 230.95 for ground fault protection on high capacity services is interpreted to apply to emergency standby generators as well. However, the NEC states in 700.26 that ground fault protection of emergency services that would include a trip shall not be required. Providing ground fault protection that includes circuit interruption may be contrary to the intent of codes for essential electrical systems. The codes suggest that higher priority be given to continuity of service than to the protection of essential electrical system equipment, except where equipment protection is required to prevent a greater hazard than lack of essential electrical service. In general, it is not recommend using ground fault protection that includes tripping off critical emergency service or feeders.

Another solution to mitigate and reduce the neutral circulating currents is to have an impedance installed between the generator neutral path connected to the transformer neutral.

To mitigate the ground fault protection, a modified differential ground fault scheme can be used as described in [1].

The impact of the two paths of neutral circulating currents due to two grounds on the system can also be seen on the differential protection of the main station transformer, as per below analysis.

#### IV. ANALYSIS OF 13.8kV/600 V TRANSFORMER DIFFERENTIAL INCORRECT OPERATION

##### A. Introduction

The University of Alberta's main utility transformers, standby generator and emergency supply looks as follows, with emphasis on the transformer differential connections:

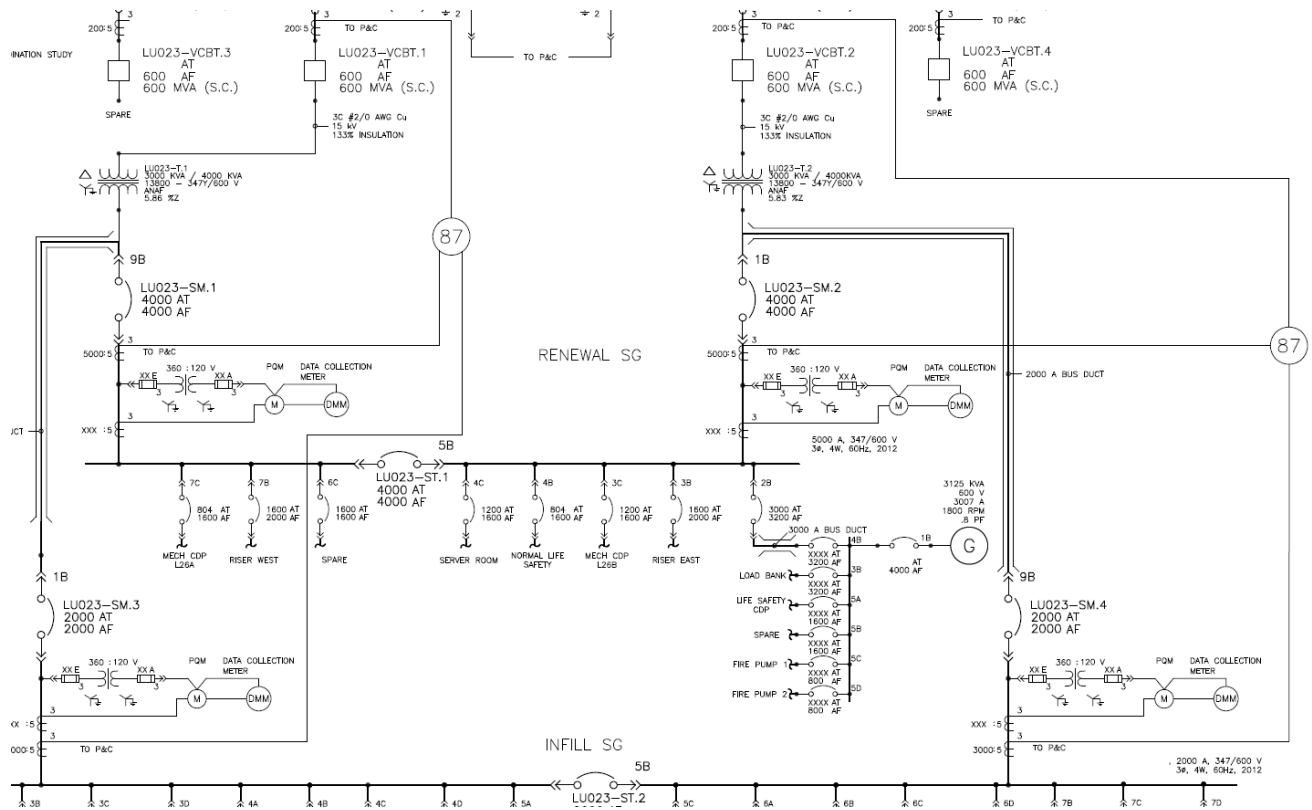


Fig 6: University of Alberta Utility Transformers, Backup Generator and Emergency Supply

The system consists of two utility transformers LU023-T1 and LU023-T2 feeding two supplies each, however of importance is the emergency supply Renewal SG which is also connected to a 3.125MVA 2 pole-pair 2.5MW backup, neutral solidly grounded diesel generator. The generator is intended for backup supply during emergency system outages and not to be permanently synchronized, however, is synchronized during maintenance runs and testing.

The transformers are two-winding 3MVA delta/wye 13.8kV/600V, however differential protection is configured as a three-winding delta/wye/wye 13.8kV/600V/600V to allow separation of the loads feeding the emergency supply Renewal SG and regular supply Infill SG.

A closer look at transformer LU023-T2's connections to the Renewal SG emergency supply bus, diesel generator and its differential connections are as follows:

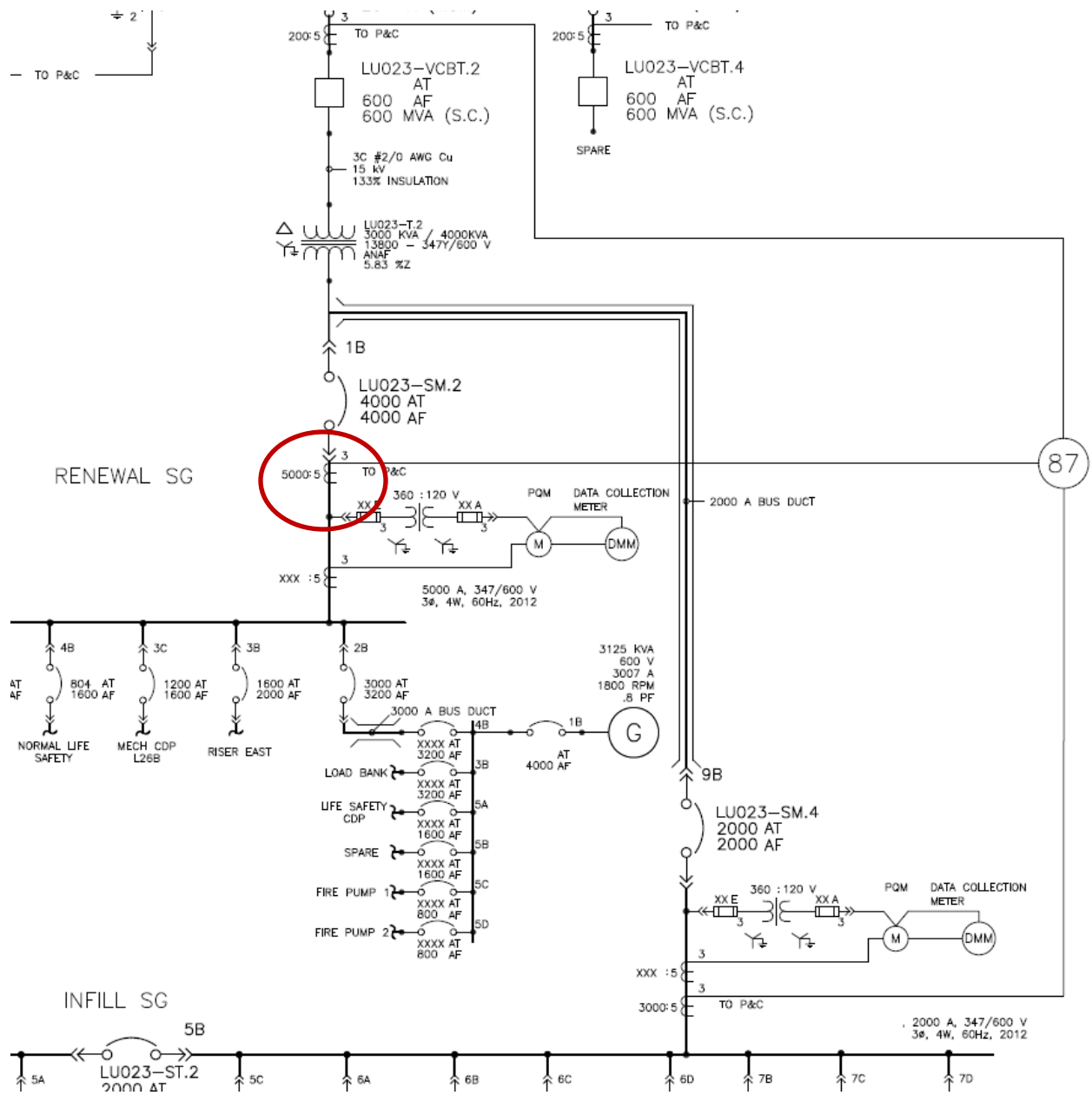


Fig 7: Transformer LU023-T2 Connections

Grounding and the modified differential ground fault topology are as below. This highlights the grounding path and the possibility of neutral circulating current between the generator and the transformer neutrals.



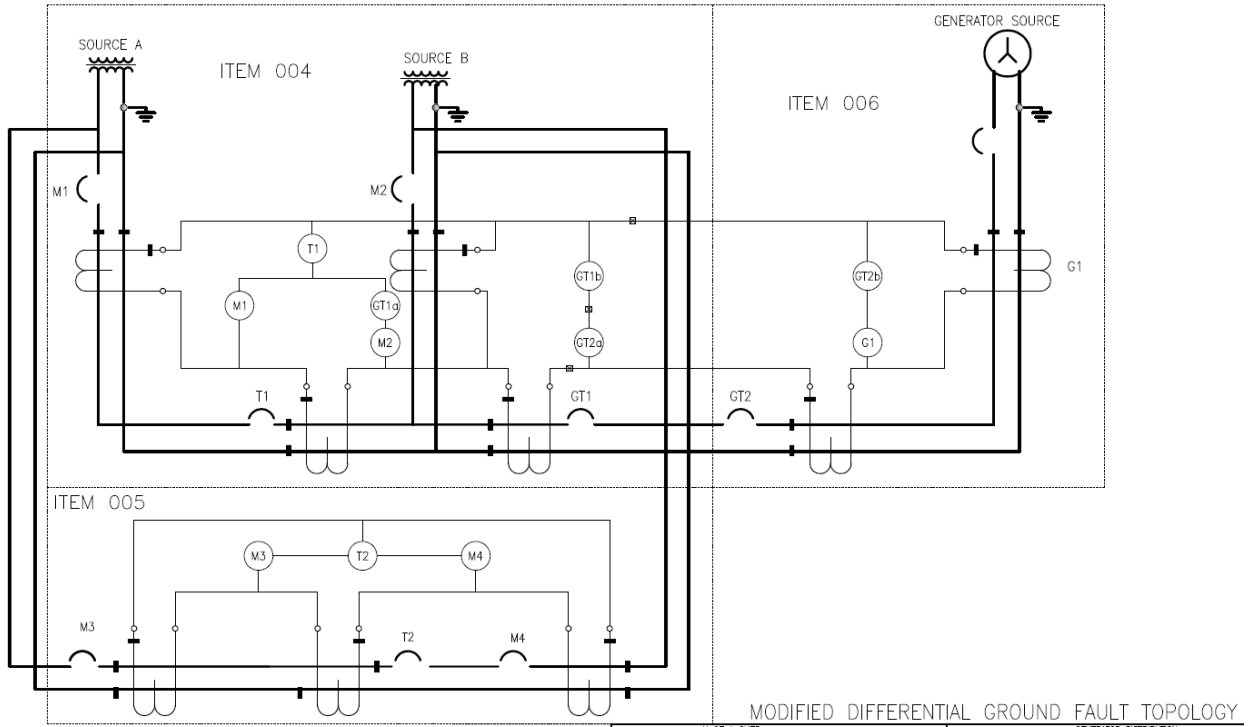


Fig 8: Utility Transformers and Generator with Modified Ground Fault Topology

The transformer percentage-differential protection function of transformer LU023-T2 had an undesired operation during a test run of the standby generator while it was synchronized and picking up load.

The load currents were very low, with some harmonics mostly in the Renewal winding indicated above, which is tied to the Renewal SG bus and diesel generator. Unfortunately, the exact load of the generator and loads on bus Renewal SG at the moment of trip is not known.

This transformer protection was installed and commissioned in 2011 and has been in service since then. Below are the waveforms captured from the transformer differential protection IED:

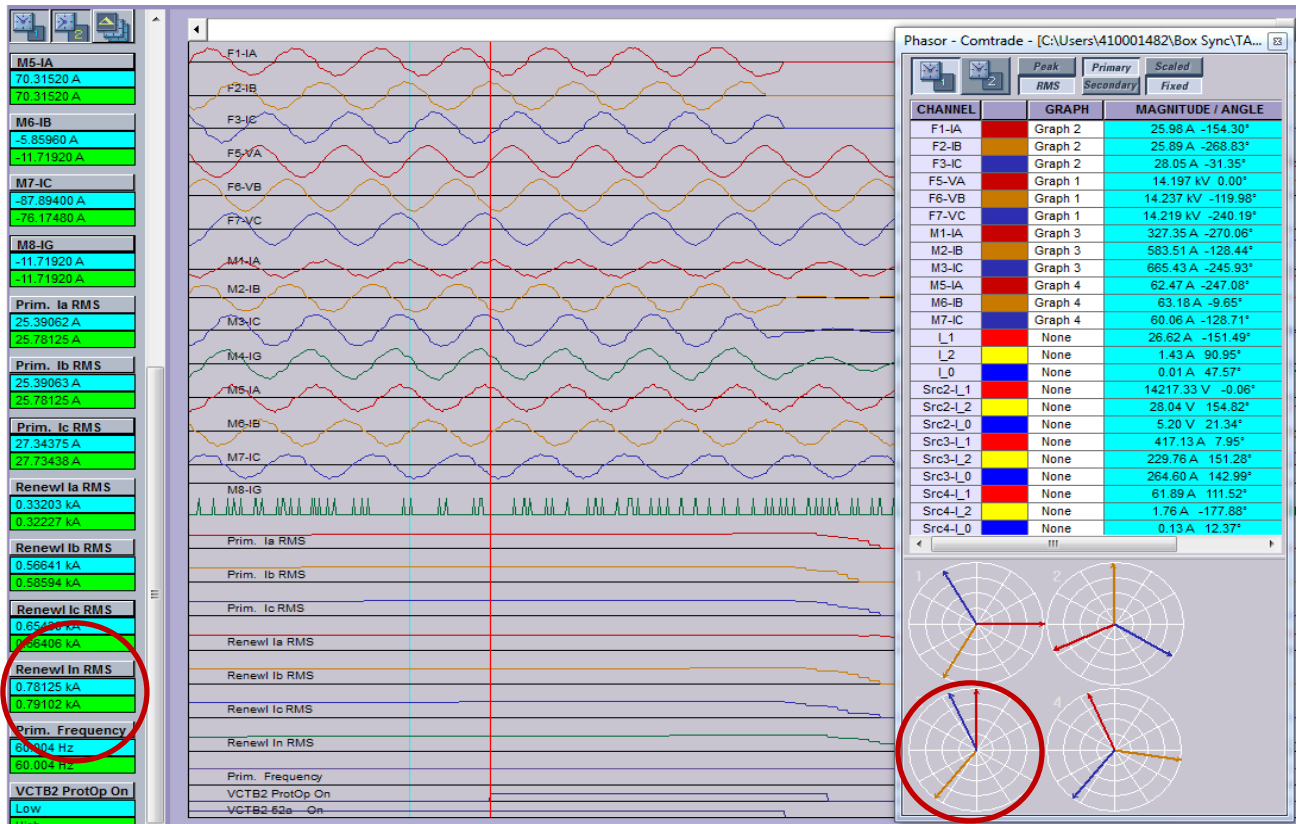


Fig 9: Transformer Differential Operation Waveforms

Upon first review, there was clearly no fault and it appears that the polarity of the C-phase winding is reversed in the Renewal winding, however it has been operating correctly for years.

Below are the waveforms of the same transformer during normal operating conditions without the generator:

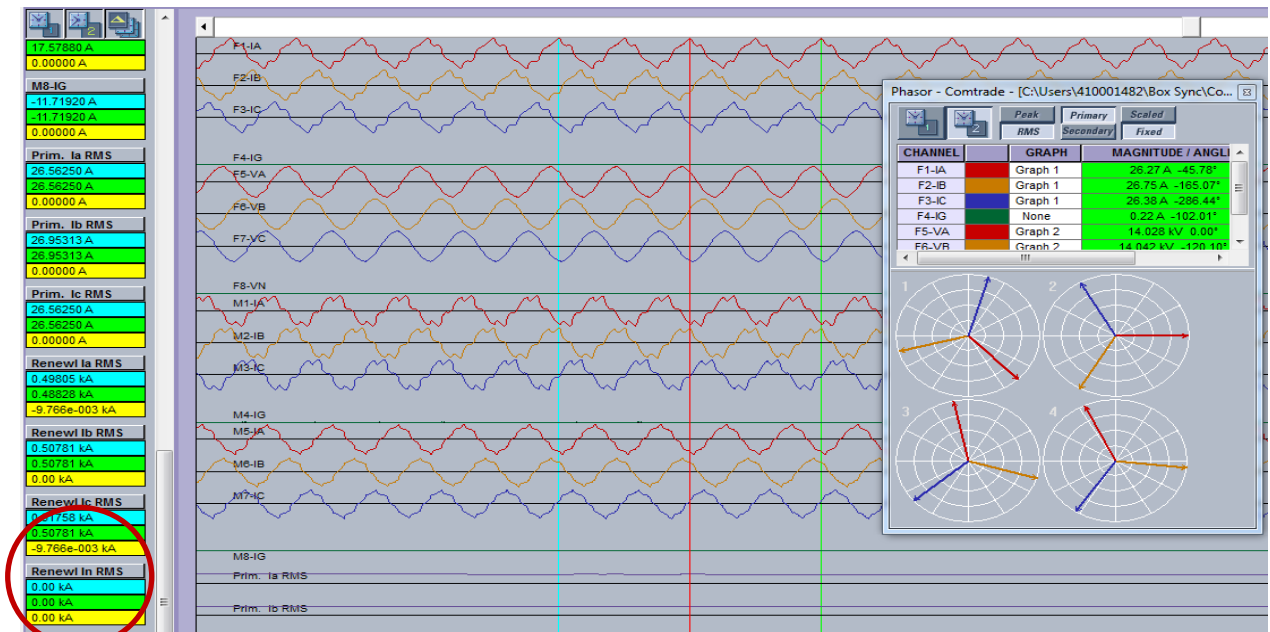


Fig 10: Transformer Differential Normal Operation Waveforms

On the IED operating characteristic, this is where the differential operated; well within the load region.

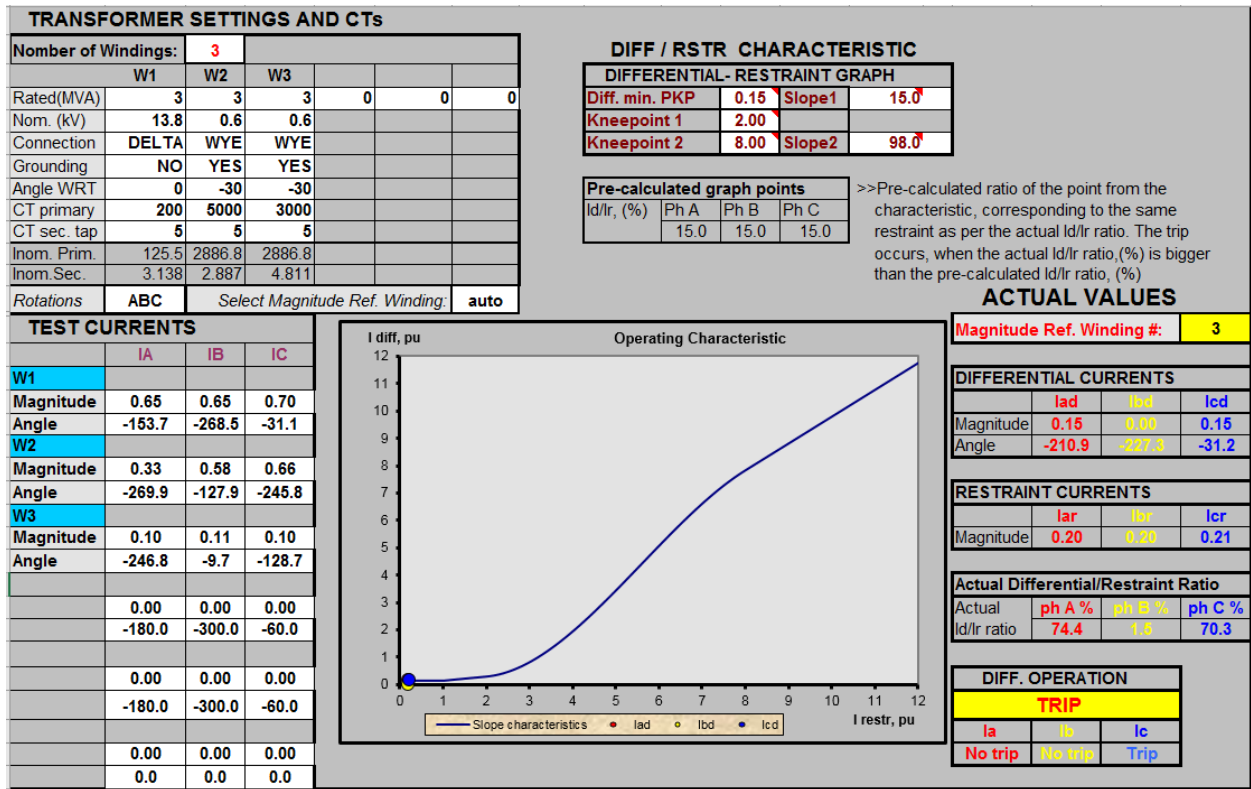


Fig 11: Percentage-Differential Operation Characteristic

The transformer differential thus operated on the C-phase.

### B. Investigation

Upon further review and comparing the transformer IED waveforms between the trip condition with the generator synchronized (figure 9) and normal conditions without the generator running (figure 10), the following differences are observed:

1. The Renewal winding phasing seems to have polarity issues in figure 9. Its phases should be very similar to the Infill winding of the transformer since both windings are on the 600V wye side of the transformer i.e. graphs 3 and 4 should be very similar. In figure 10, these two windings are very similar as expected.
2. The sequence components differences of the Delta and Renewal winding with the generator running and not running are: (Loads are a little different)

Sequence Components	Generator Running		Generator Not Running	
	Prim 13.8kV	Renewl 600kV	Prim 13.8kV	Renewl 600V
I1	26.51A∠-151.1°	416.87A∠8.3°	26.46A∠-45.8°	497.20A∠101.8°
I2	1.37A∠87.9°	230.37A∠151.5°	0.3A∠114.4°	11.06A∠-69.8°
I0	0.02A∠59.4°	263.06A∠143.1°	0.14A∠-97.7°	0.98A∠-162.1°

3. The Renewal winding neutral current In with the generator running is about 800A, and without the generator running it is 0A.

4. The Renewal winding is very unbalanced with the generator running, compared to when the generator is offline:

Phase	Generator Running	Generator Not Running
	RMS Currents	RMS Currents
Ia	322A	498A
Ib	586A	508A
Ic	664A	508A
In	791A	0A

This high neutral current is due to the neutral circulating current from the generator to the utility neutral.

The transformer differential settings are as follows, which is correct compared to transformer ratings:

PARAMETER	CT F1	CT M1	CT M5
Phase CT Primary	200 A	5000 A	3000 A
Phase CT Secondary	5 A	5 A	5 A
Ground CT Primary	200 A	5000 A	3000 A
Ground CT Secondary	5 A	5 A	5 A

PARAMETER	WINDING 1	WINDING 2	WINDING 3
Source	Prim. (SRC 1)	Renewl (SRC 2)	Infill (SRC 3)
Rated MVA	3.000 MVA	3.000 MVA	3.000 MVA
Nominal Phs-phs Voltage	13.800 kV	0.600 kV	0.600 kV
Connection	Delta	Wye	Wye
Grounding	Not within zone	Within zone	Within zone
Angle Wrt Winding 1	0.0 deg	-30.0 deg	-30.0 deg
Resistance	10.0000 ohms	10.0000 ohms	10.0000 ohms

SETTING	PARAMETER
Operating Characteristic Graph	View
Function	Enabled
Pickup	0.150 pu
Slope 1	15 %
Break 1	2.000 pu
Break 2	8.000 pu
Slope 2	98 %
Inrush Inhibit Function	Trad. 2nd
Inrush Inhibit Mode	Average
Inrush Inhibit Level	20.0 % fo
Overexcitation Inhibit Function	Disabled
Overexcitation Inhibit Level	10.0 % fo
Block	OFF
Target	Latched
Events	Enabled

Fig 12: Percentage-Differential and Transformer Settings

### C. Analysis

From the above waveforms, it is clear that there is a significant neutral circulating current from the generator to the transformer neutral when the generator is synchronized. This level of circulating current increases as generator load increases.

The main question is; was the transformer differential operation correct?

Transformer settings for the Renewal winding do have the connection as Wye and grounding as “Within Zone”, which is correct based on transformer configuration and grounding. All other winding settings are also correct based on transformer info, ratings and CT ratios.

Based on these settings, the transformer differential algorithm should remove zero sequence currents in the differential calculation, however, percentage-differential did operate.

Calculation of the differential currents are as follows:

1) Rated current and CT margin

The rated current for each winding as calculated using:

$$I_{rated}[w] = \frac{P_{rated}[w]}{\sqrt{3} \times V_{nom}[w]}$$

CT margin for each winding is calculated:

$$I_{margin} = \frac{CT\ primary[w]}{I_{rated}[w]}$$

Winding	Rated Current	CT Margin
Primary	125.51A	1.59
Renewal	2886.71A	1.73
Infill	2886.71A	1.04

The reference winding selection is set to “Automatic Selection”, hence the winding with the lowest CT margin (or closest to 1) will be selected as the reference winding, hence the winding associated with Infill.

2) Magnitude compensation factors

The magnitude compensation factors are calculated using:

$$M[w] = \frac{I_{primary}[w] \times V_{nom}[w]}{I_{primary}[w_{ref}] \times V_{nom}[w_{ref}]}$$

Winding	Compensation Factor
Primary	1.53
Renewal	1.67
Infill	1

3) Phase and zero-sequence compensation equations

The compensated currents can then be calculated based on the transformer type of Dy-1:

Delta:

$\Phi_{comp}[w]$	Grounding[w] = "Not within zone"
$0^\circ$	$I_A^P[w] = I_A[w]$ $I_B^P[w] = I_B[w]$ $I_C^P[w] = I_C[w]$

Wye: (Grounding within zone)

$330^\circ \text{ lag}$	$I_A^P[w] = \frac{1}{\sqrt{3}}I_A[w] - \frac{1}{\sqrt{3}}I_B[w]$ $I_B^P[w] = \frac{1}{\sqrt{3}}I_B[w] - \frac{1}{\sqrt{3}}I_C[w]$ $I_C^P[w] = \frac{1}{\sqrt{3}}I_C[w] - \frac{1}{\sqrt{3}}I_A[w]$
-------------------------	--

#### 4) Magnitude, phase angle and zero-sequence compensation equations

The total compensated current for each phase is calculated using:

$$I_A^C[w] = M[w] \times I_A^P[w]$$

$$I_B^C[w] = M[w] \times I_B^P[w]$$

$$I_C^C[w] = M[w] \times I_C^P[w]$$

The secondary currents of each winding captured at differential operation, was as follows: (From figure 9)

Winding	$I_A^C$	$I_B^C$	$I_C^C$
Primary	$0.65A \angle -153.7^\circ$	$0.65A \angle -268.5^\circ$	$0.7A \angle -31.1^\circ$
Renewal	$0.33A \angle -269.9^\circ$	$0.58A \angle -127.9^\circ$	$0.66A \angle -245.8^\circ$
Infill	$0.1A \angle -246.8^\circ$	$0.11A \angle -9.7^\circ$	$0.1A \angle -128.7^\circ$

Using all the above equations, the compensated currents for each winding comes to:

Winding	$I_A^C$	$I_B^C$	$I_C^C$
Primary	$0.99A \angle -153.7^\circ$	$0.99A \angle -269.9^\circ$	$1.07A \angle -31.1^\circ$
Renewal	$0.83A \angle -299.7^\circ$	$1.02A \angle -94.7^\circ$	$0.37A \angle -45.1^\circ$
Infill	$0.1A \angle -36.7^\circ$	$0.1A \angle -6.2^\circ$	$0.099A \angle -277.7^\circ$

#### 5) Differential and restraining current calculation:

Differential currents are calculated:

$$I_{dA} = I_A^C[1] + I_A^C[2] + I_A^C[3]$$

$$I_{dB} = I_B^C[1] + I_B^C[2] + I_B^C[3]$$

$$I_{dC} = I_C^C[1] + I_C^C[2] + I_C^C[3]$$

Restraining currents are calculated:

$$I_{rA} = \max \{ |I_A^C[1]|, |I_A^C[2]|, |I_A^C[3]| \}$$

$$I_{rB} = \max \{ |I_B^C[1]|, |I_B^C[2]|, |I_B^C[3]| \}$$

$$I_{rC} = \max \{ |I_C^C[1]|, |I_C^C[2]|, |I_C^C[3]| \}$$

Differential and restraint currents in A:

	$I_A$	$I_B$	$I_C$
Differential	0.741A.∠-210.9°	0.035A.∠-227.3°	0.754A.∠-31.2°
Restraint	0.99A	0.99A	1.07A

Differential and restraining currents in p.u.

	$I_A$	$I_B$	$I_C$
Differential	0.148p.u.∠-210.9°	0.007p.u.∠-227.3°	0.151p.u.∠-31.2°
Restraint	0.20p.u.	0.20p.u.	0.21p.u.
Trip/No-trip	No-trip	No-trip	Trip

The differential in C-phase is right at the edge just above the differential/restraint characteristic (minimum setting is 0.15p.u.) and operates which can also be seen in figure 11. A-phase is just below the operating point where B-phase has very little differential current.

Analysis thus confirms that the percentage-differential operation was correct for this particular system conditions.

Two algorithms that adds additional security to the percentage-differential are the directionality check and CT saturation detection.

The directionality check, described in section V, will secure a differential operation against such events.

## V. SECURING PERCENTAGE-DIFFERENTIAL USING DIRECTIONALITY CHECK AND CT SATURATION DETECTION

The percentage-differential function can be secured additionally for external through-faults or CT saturation, using the following newer algorithms:

### A. Directionality Check

The directionality check compares the current angles between all windings and a main or reference winding, for CT's connected in Wye and polarities as per Figure 14.

Voltages are NOT used for this directionality check.

This directionality check can be used to supervise percentage-differential against incorrect operations for any external fault during severe CT saturation, CT or CT wiring issues or failures.

For external faults, at least one of the current phase angles will be between +90 to +270 degrees i.e. more than 90 degrees to the reference, and for all internal faults, all current phase angles will be within 90 degrees to the reference, as per below:

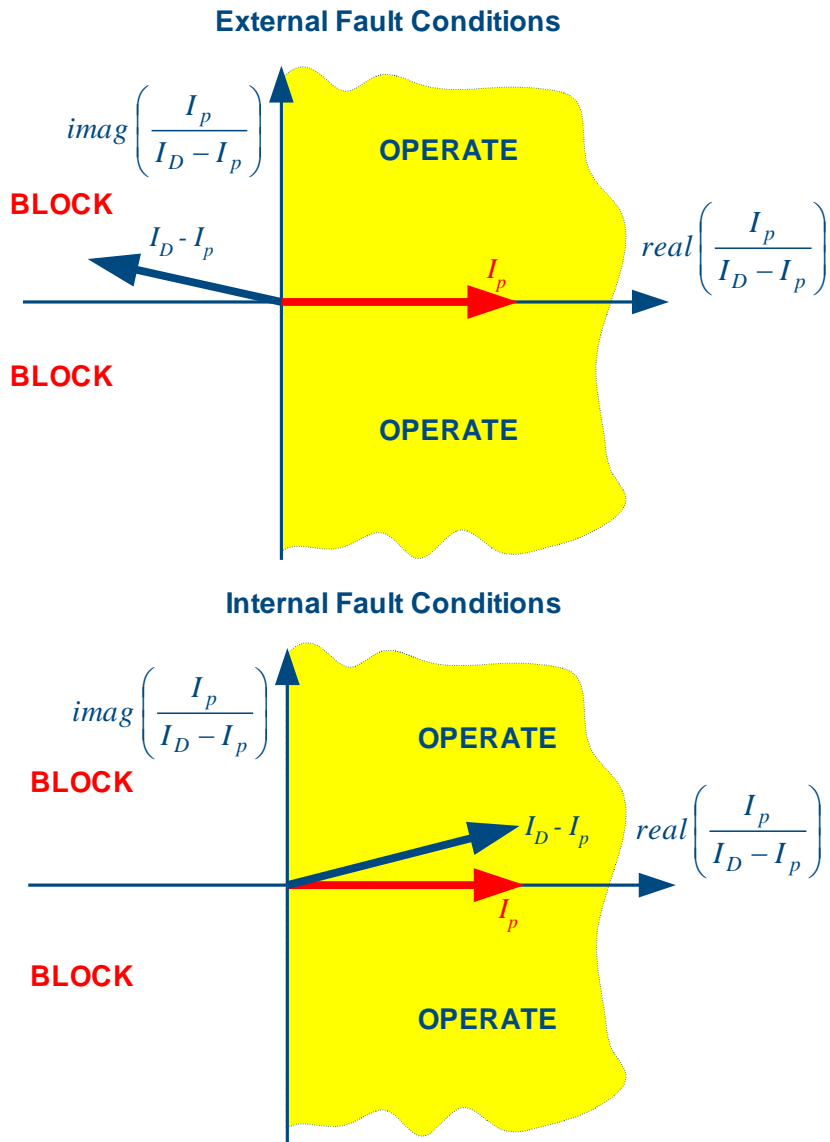


Fig 13: Directionality Check of Current Angles

**B. CT Saturation Detection**

During CT saturation events, the CT will typically provide unsaturated current for a brief period of 2 – 4 ms. This can be used to detect CT saturation based on the movement of the percent-differential characteristic as follows:



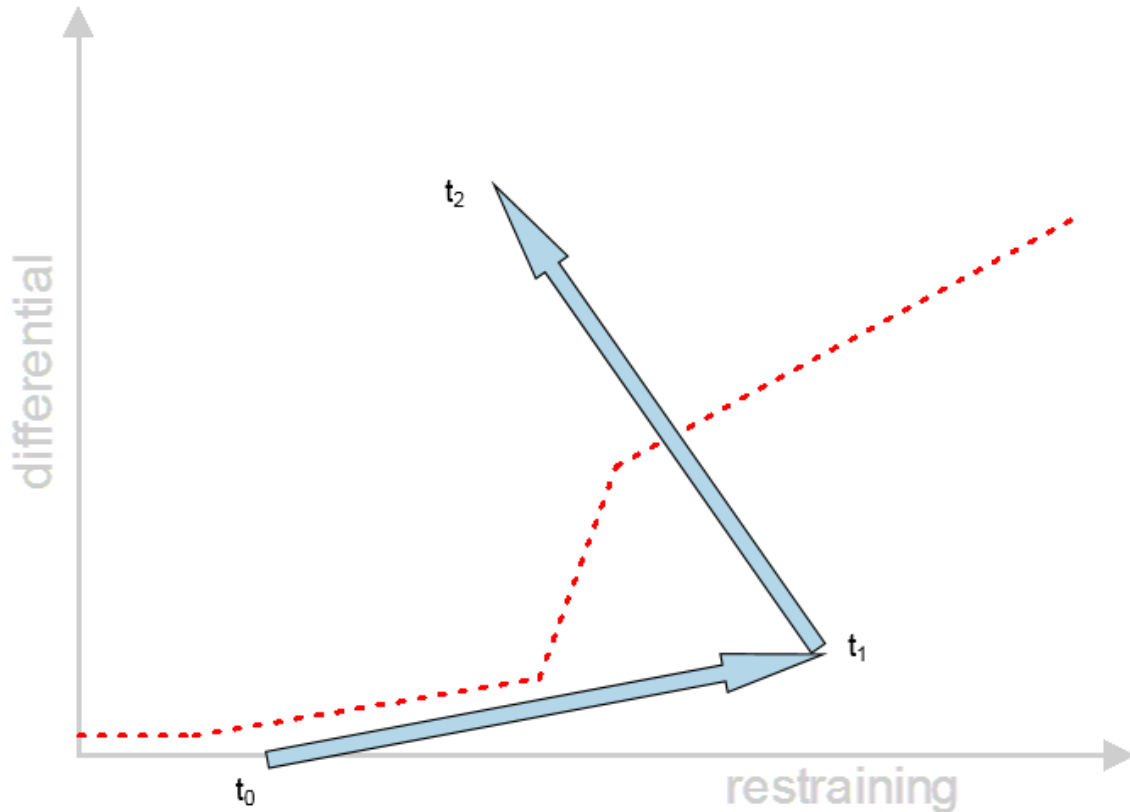


Fig 14: Percentage-Differential Characteristic During CT Saturation

At  $t_0$ , the external fault occurs. At  $t_1$ , the weakest CT starts to saturate and at  $t_2$  the CT fully saturated.

This movement from load region to beyond breakpoint 2 and then towards the operating region is used to determine the fault is external and CTs are saturating; hence can the percentage-differential be blocked to remain secure.

## VI. CONCLUSION

LV power system neutral currents can be significantly impacted by the presence of two grounds from dissimilar sources such as a utility transformer and standby generator. In this particular case it was due to the synchronization of a solidly grounded backup diesel generator, which is not intended to be synchronized continuously, connected to two utility transformer solidly grounded wye-winding neutrals. The ground fault protection scheme did not operate since a Modified Differential Ground Fault scheme [1] is deployed, which is adapted for scenarios like this, however, the impact of this neutral circulating current on the transformer differential should be considered. Utilizing the directionality check of the transformer percentage-differential would mitigate this particular operation, however the presence of the neutral circulating current and reducing it is being reviewed.

An unusual percentage-differential operation is covered during system running conditions, highlighting the need to have all power system operating conditions reviewed and its possible impacts on the protection performance.

## VII. REFERENCES

- [1] David L Swindler, Carl J Fredericks: "Modified differential ground fault protection for systems having multiple sources and grounds". Published by Square D, Smyrna, Tennessee, July 1994
- [2] Anthony Hoevenaars, "Preventing Neutral circulating currents when paralleling generators", Mirus International, August 2011.
- [3] John DeDad.: "Ground-fault current: problems and solutions", EC&M development, Electrical Construction and Maintenance, March 2007
- [4] Lawrence A Bey, Jim Iverson: "White Paper: Ground fault protection and switching the neutral", Cummins Power Generation, 2006
- [5] Stephen Drouillhet, Preparing an Existing Diesel Power Plant for a Wind Hybrid Retrofit: Lessons Learned in the Wales, Alaska, Wind-Diesel Hybrid Power Project, National Renewable Energy Laboratory, NREL/CP-500-30586, August 2001
- [5] T60 Transformer Protection System Instruction Manual, GE Publication GEK-131066.

### Authors' Information

**David Roh** is the Utilities Services Manager, Electrical at the University of Alberta, Utilities department. David is a graduate of the Red River Community College in Winnipeg, MB and has over 36 years' experience in electrical equipment application, sales and service and Consulting Engineering. He has been with the University of Alberta for over 13 years and now serves as Utility Services Manager.

**Lorne Clark**, P. Eng is the Utilities Services Engineer at the University of Alberta, Utilities department, He received the degree of Bachelor of Science in Electrical Engineering from the University of Alberta in 2000. Mr. Clark has 19 years of engineering experience: 5 years with GP Technologies Ltd. as a consultant and 14 years with the University of Alberta Utilities department as the Utilities Services Engineer. He specializes in power systems distribution operations and maintenance support as well as project management. He is a member of IEEE.

**JC (Jacobus) Theron** is Technical Applications Engineer for Grid Automation division of GE Grid Solutions. He received the degree of Electrical and Electronic Engineer from the University of Johannesburg, South Africa in 1991. Mr. Theron has 27 years of engineering experience; 6 years with Eskom (South Africa) as Protection / Control and Metering Engineer, 14 years with GE Multilin (Canada) as Technical Applications Engineer / Product / Technical support / Protective Relaying Consultant/Protection and Systems Engineer leading the Project and Consulting Engineering team and as Product Manager, 2 years with Alstom T&D (USA) as Senior Systems Engineer and 5 years with Hydro One as Operations Assessment Engineer / P&C Technical Services Manager. He specializes in transmission, distribution, bus and rotating machines protection applications support and Fast Load Shed Systems, system designs and transient system testing. He is member of IEEE.