

Application of Zero-Sequence Filter on Transformer Differential Protection

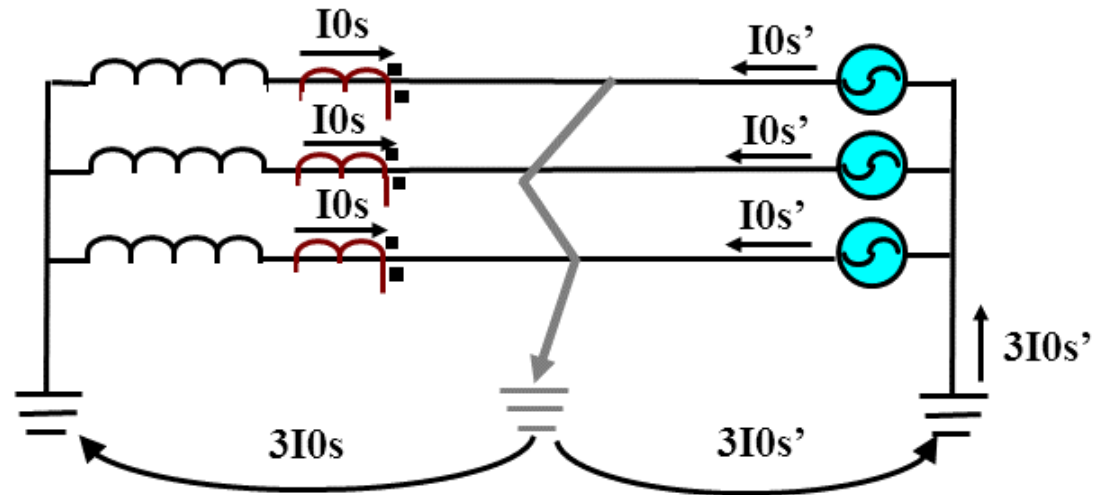
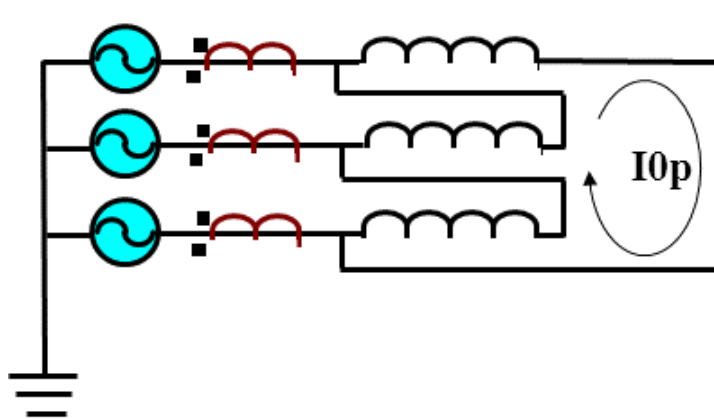
Roberto Cimadevilla



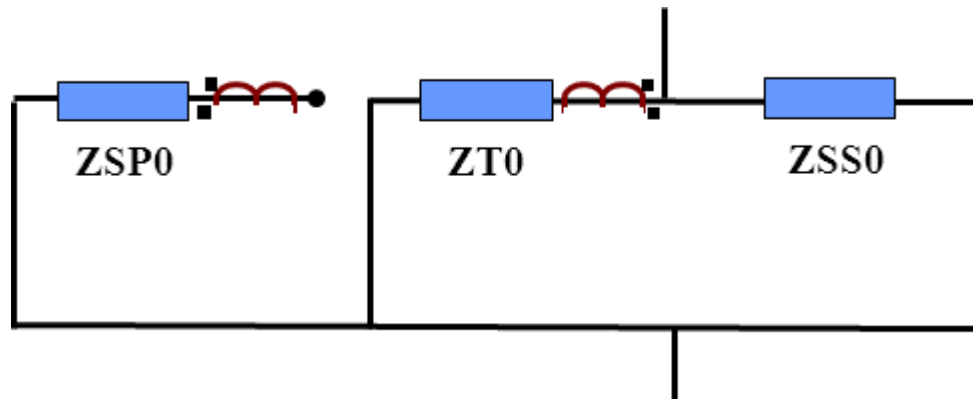
Overview

- Transformer configurations that require the use of the zero-sequence filter
- Methods for applying the zero-sequence filter
- Influence of the zero-sequence filter on the differential unit and complementary units

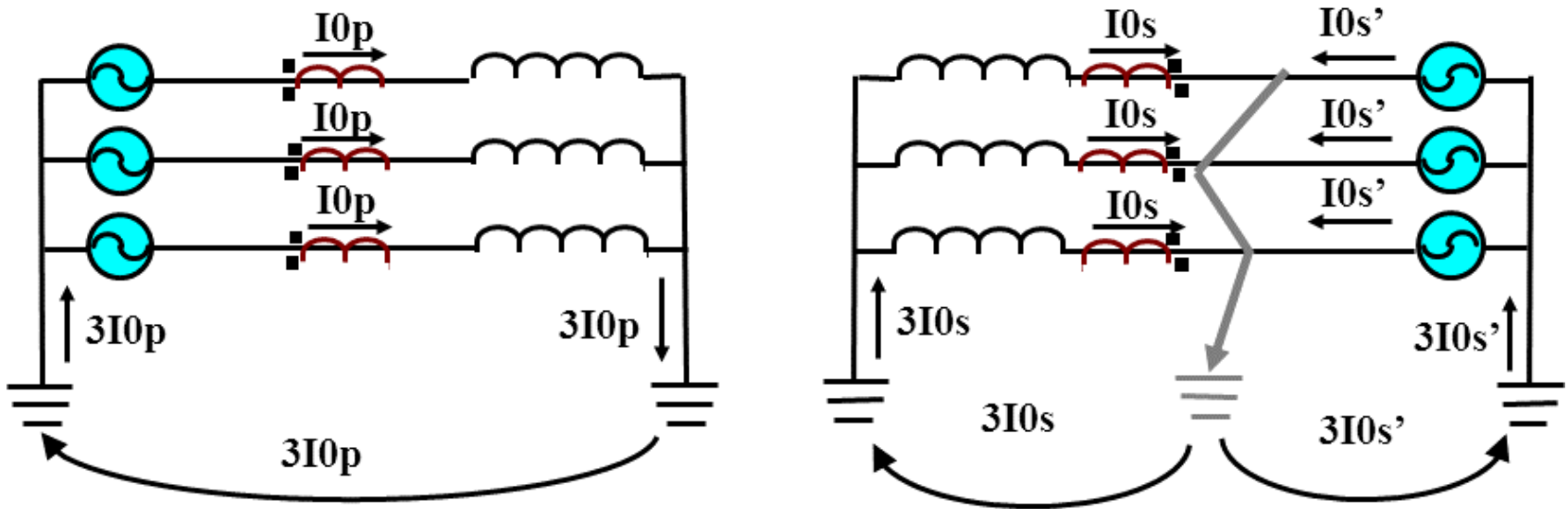
Transformer Dyn



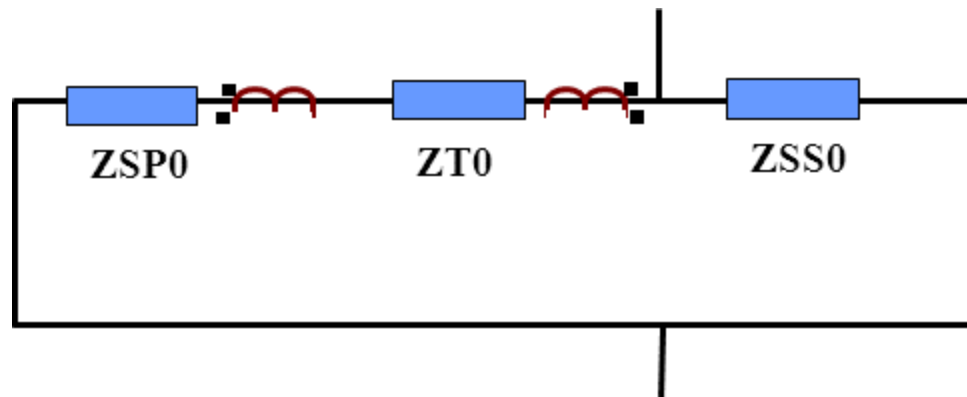
ZERO SEQUENCE FILTER=YES



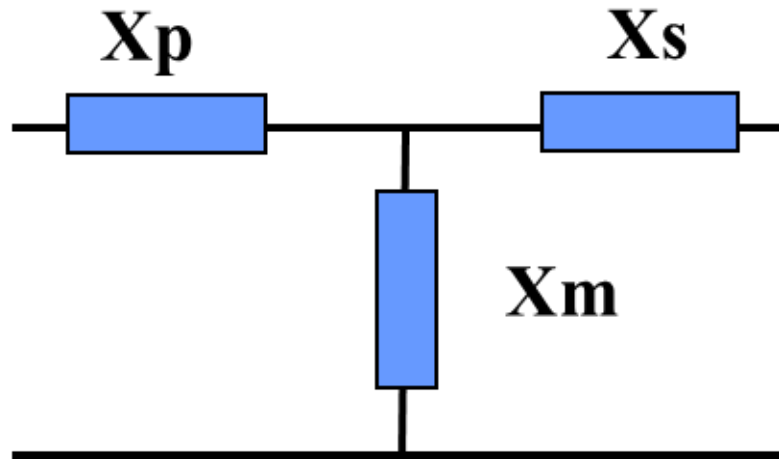
Transformer YNyn



ZERO SEQUENCE FILTER=NO

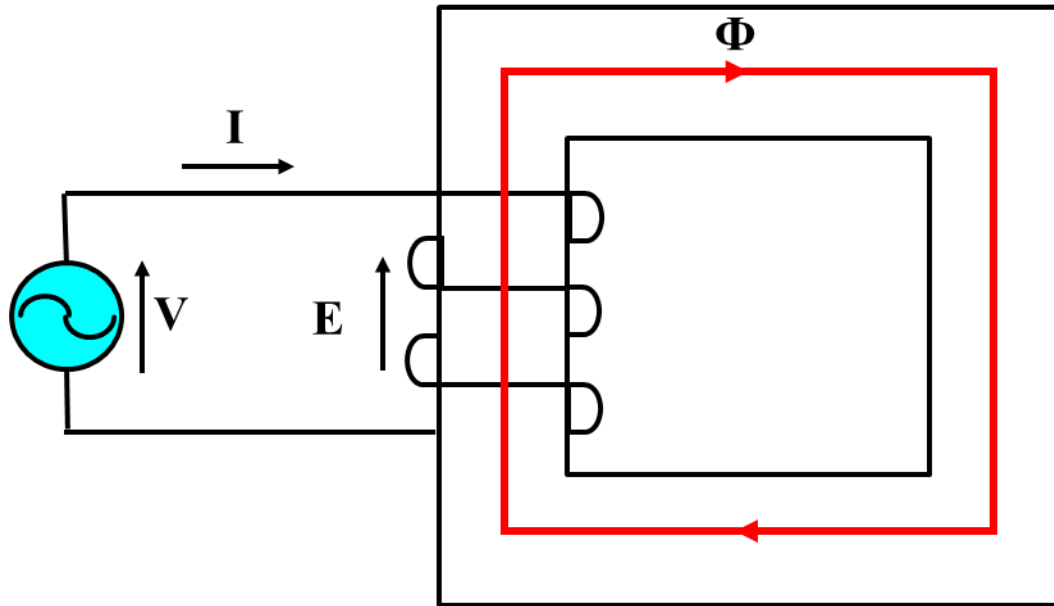


Magnetizing Reactance



Can we neglect X_m ?

Magnetizing Reactance



$$X = \frac{E}{I}$$

$$N \cdot i = \phi \cdot \mathfrak{R}$$

$$e = -N \cdot \frac{d\phi}{dt} = -N \cdot w \cdot \phi \cdot \cos(wt)$$

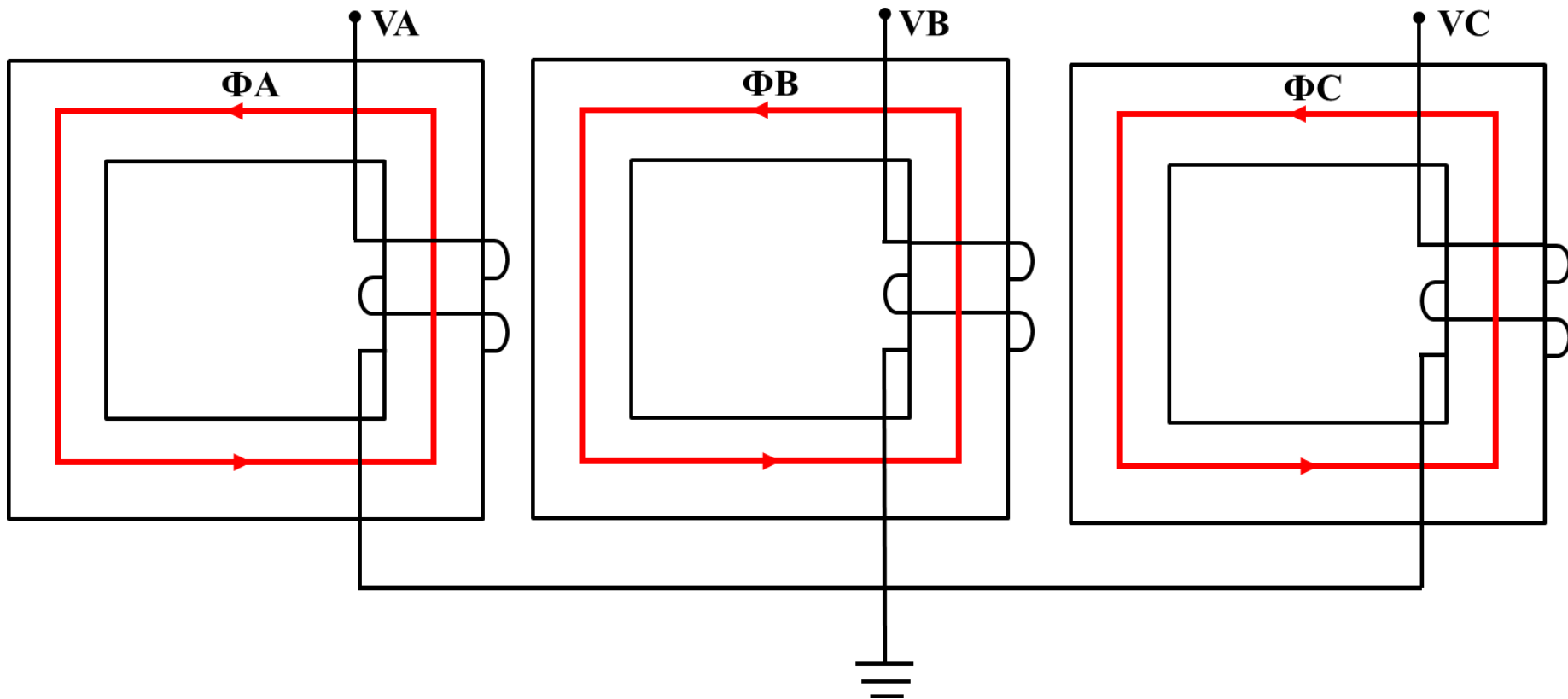
$$I = \frac{\Phi \cdot \mathfrak{R}}{N}$$

$$E = w \cdot N \cdot \Phi$$

$$X = \frac{E}{I} = \frac{N^2 \cdot w}{\mathfrak{R}}$$

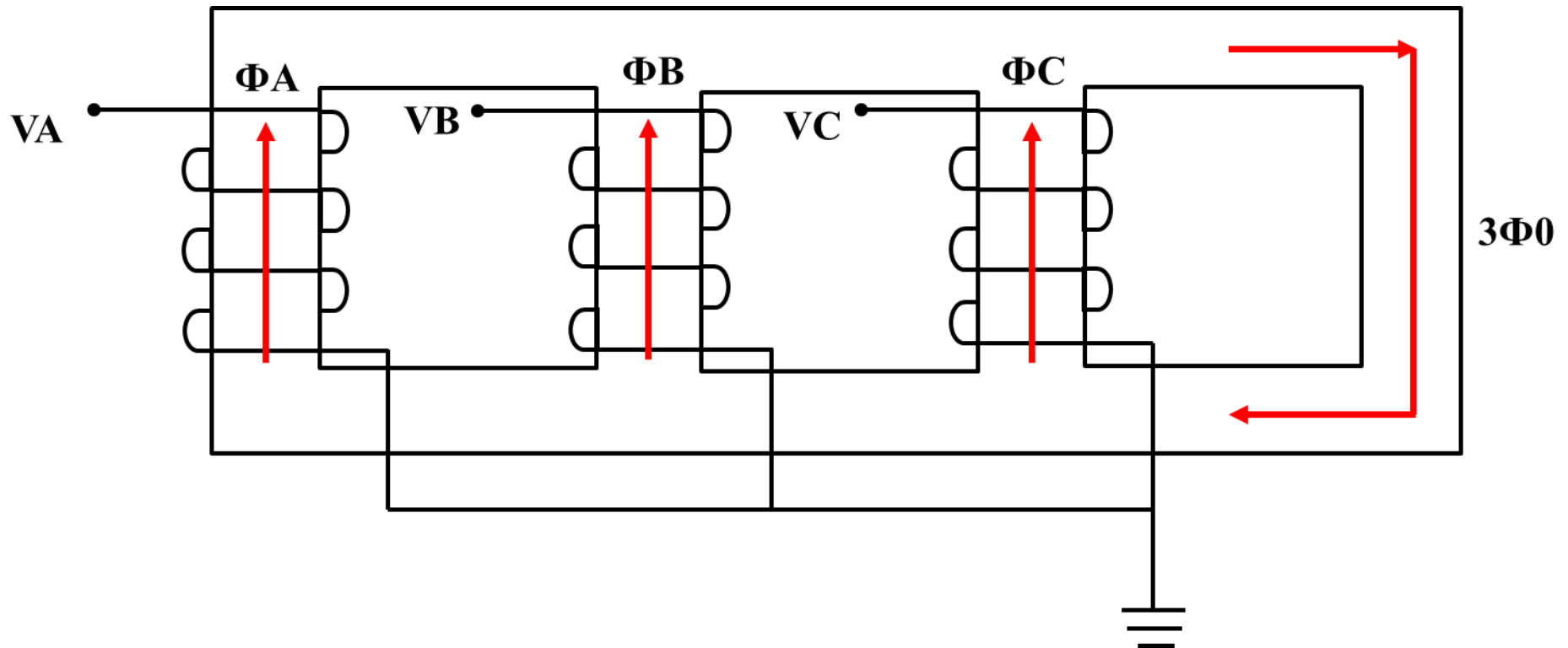
Single-Phase Banks

- $X_{m1} \approx X_{m0}$ (high value)
- $I_m = 0.5\% - 5\% \rightarrow X_m = 20000\% - 2000\%$



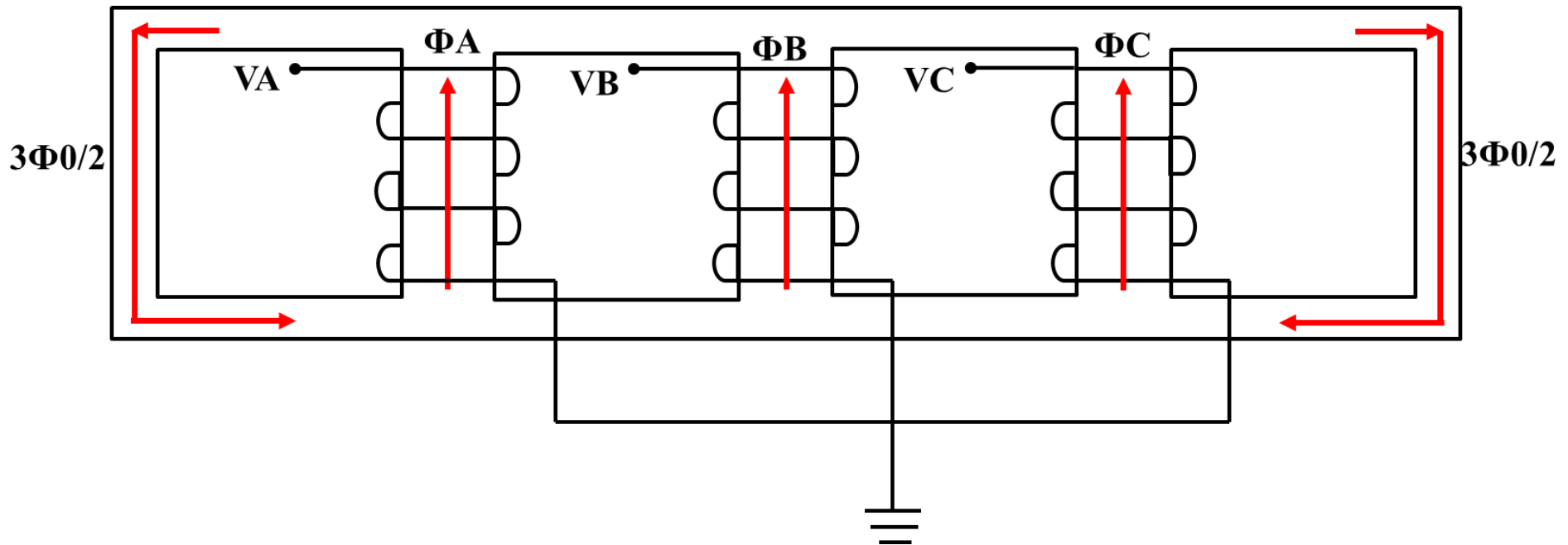
4-Legged Transformer

- $X_{m1} \approx X_{m0}$ (high value)



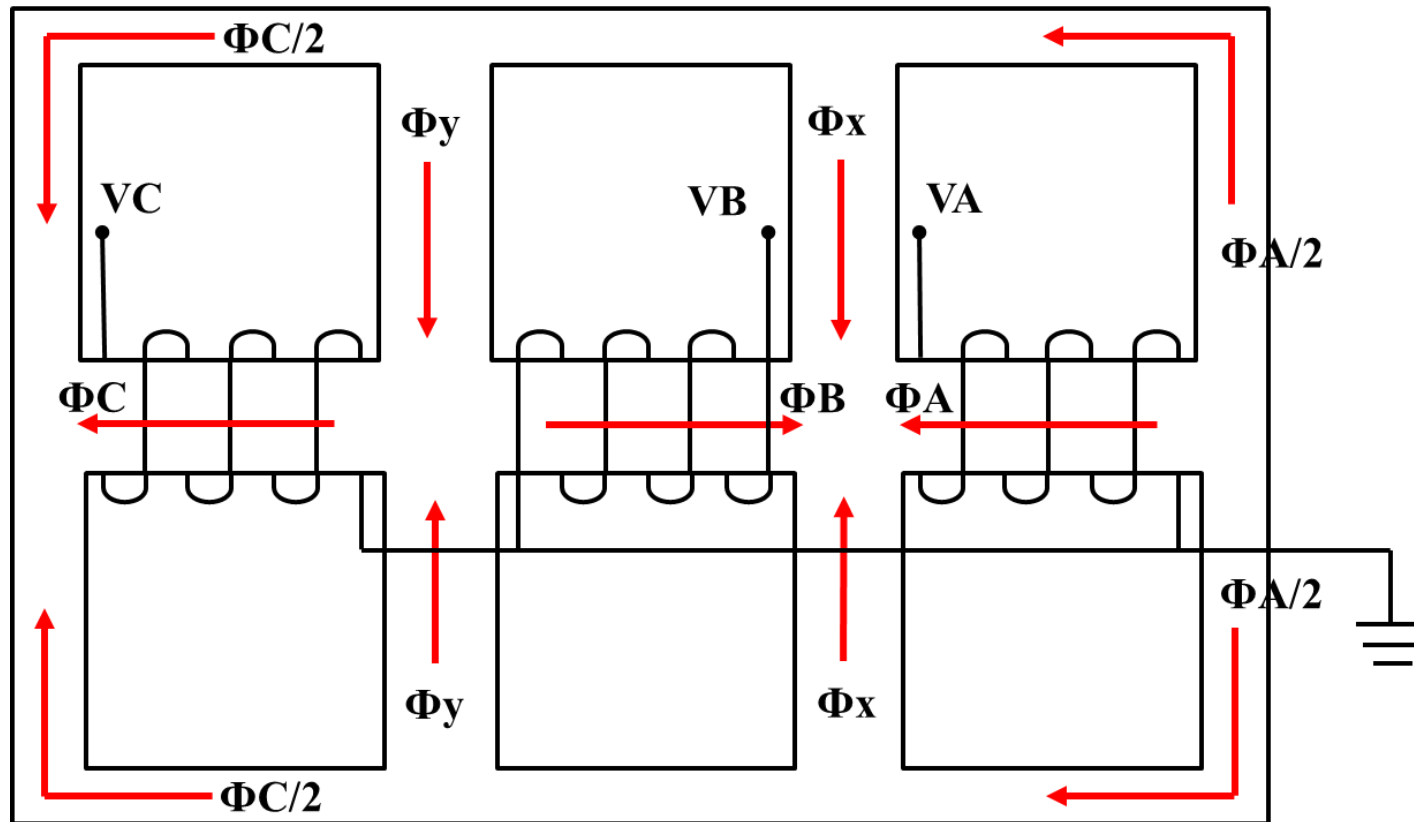
5-Legged Transformer

- $X_{m1} \approx X_{m0}$ (high value)



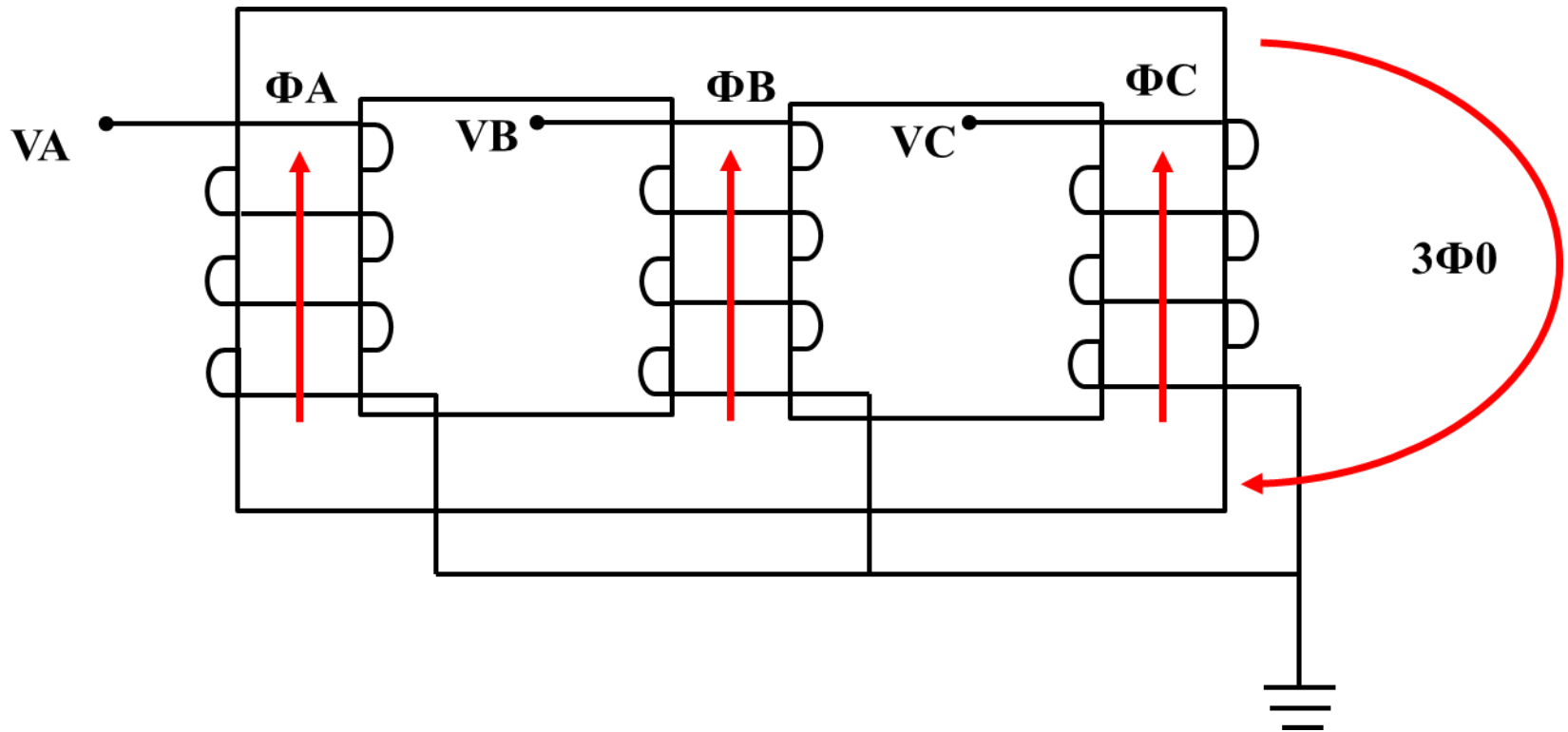
Shell-Type Transformer

- $X_{m1} \approx X_{m0}$ (high value)



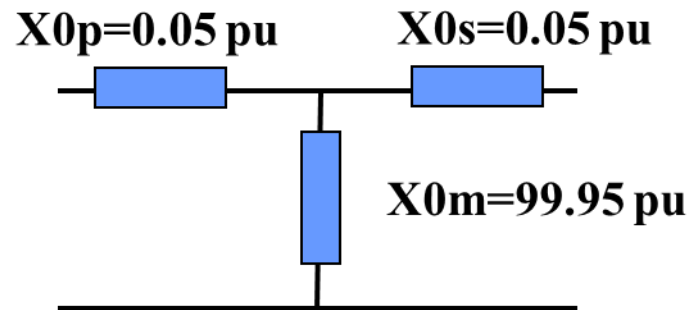
3-Legged Transformer

- $X_{m0} \ll X_{m1}$
- $X_{m0} \approx 50\% - 200\%$

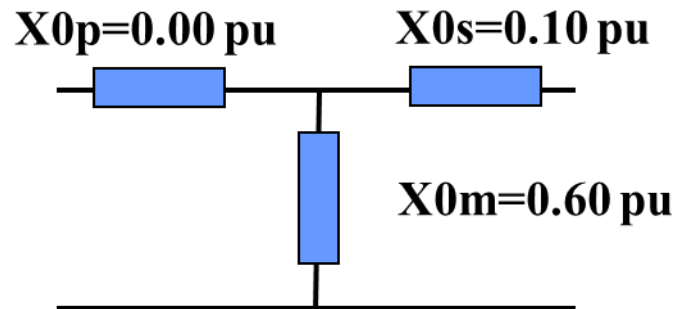


Typical Values for X0

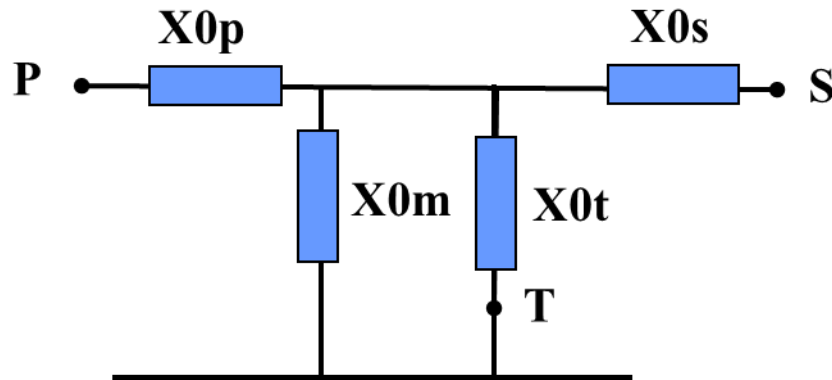
YY SHELL-TYPE OR 5/4 LEGGED



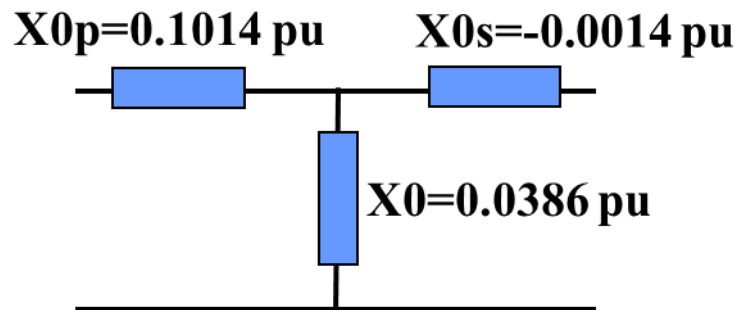
YY 3 LEGGED



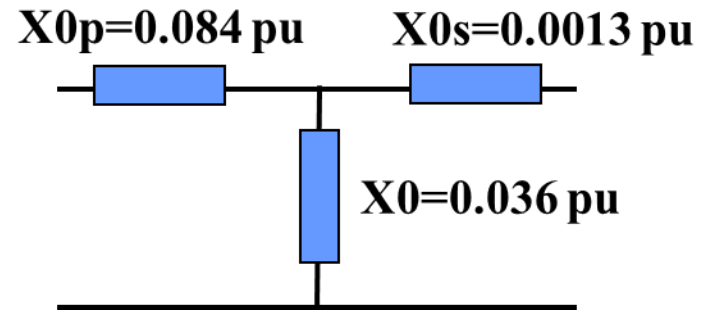
Third Winding



SHELL-TYPE AND 4/5 LEGGED

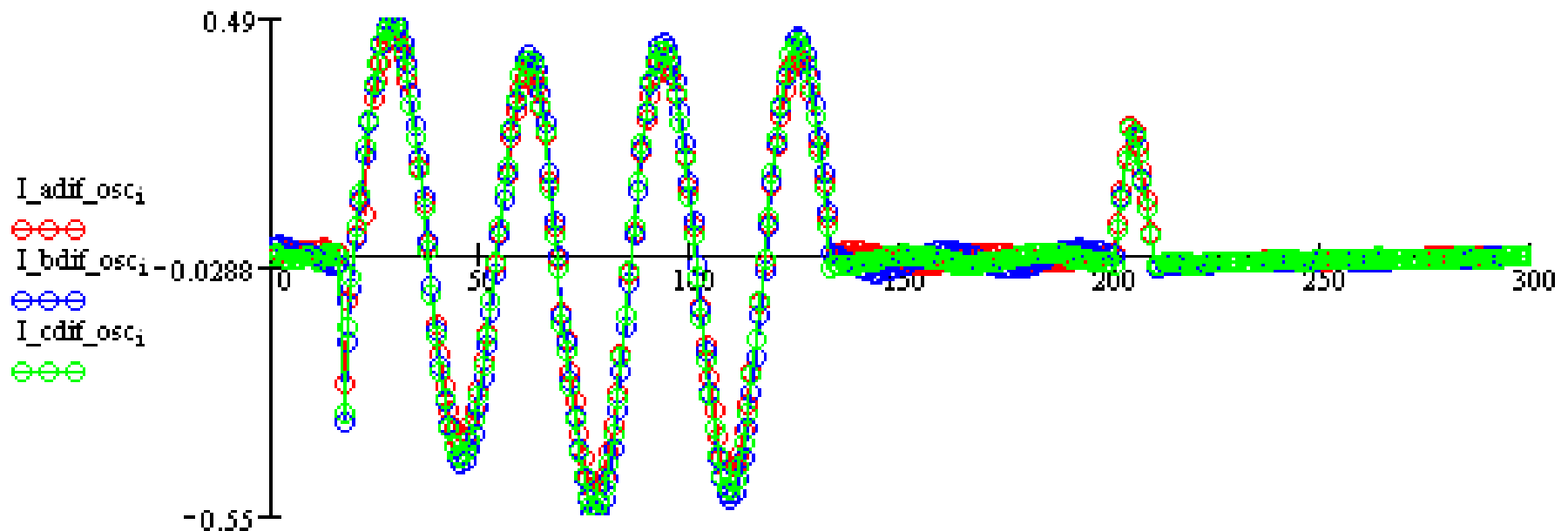


3 LEGGED



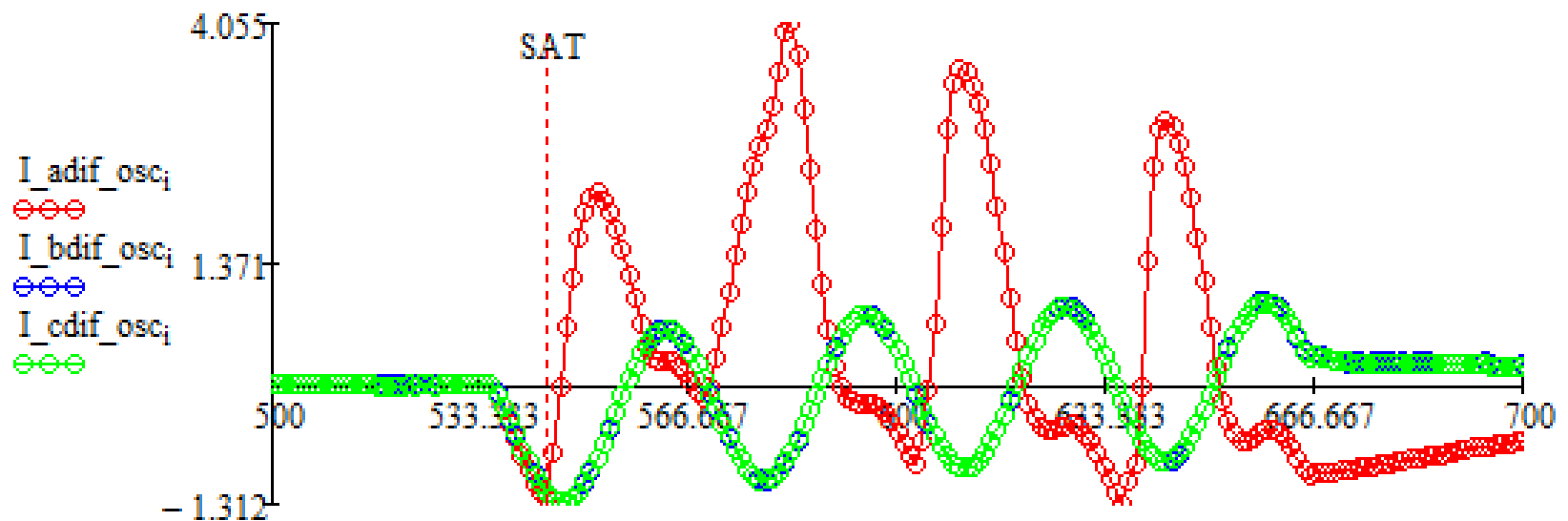
Real External Fault

3 legged YNyn0 30 MVA 115 kV – 13.8 kV



Real External Fault

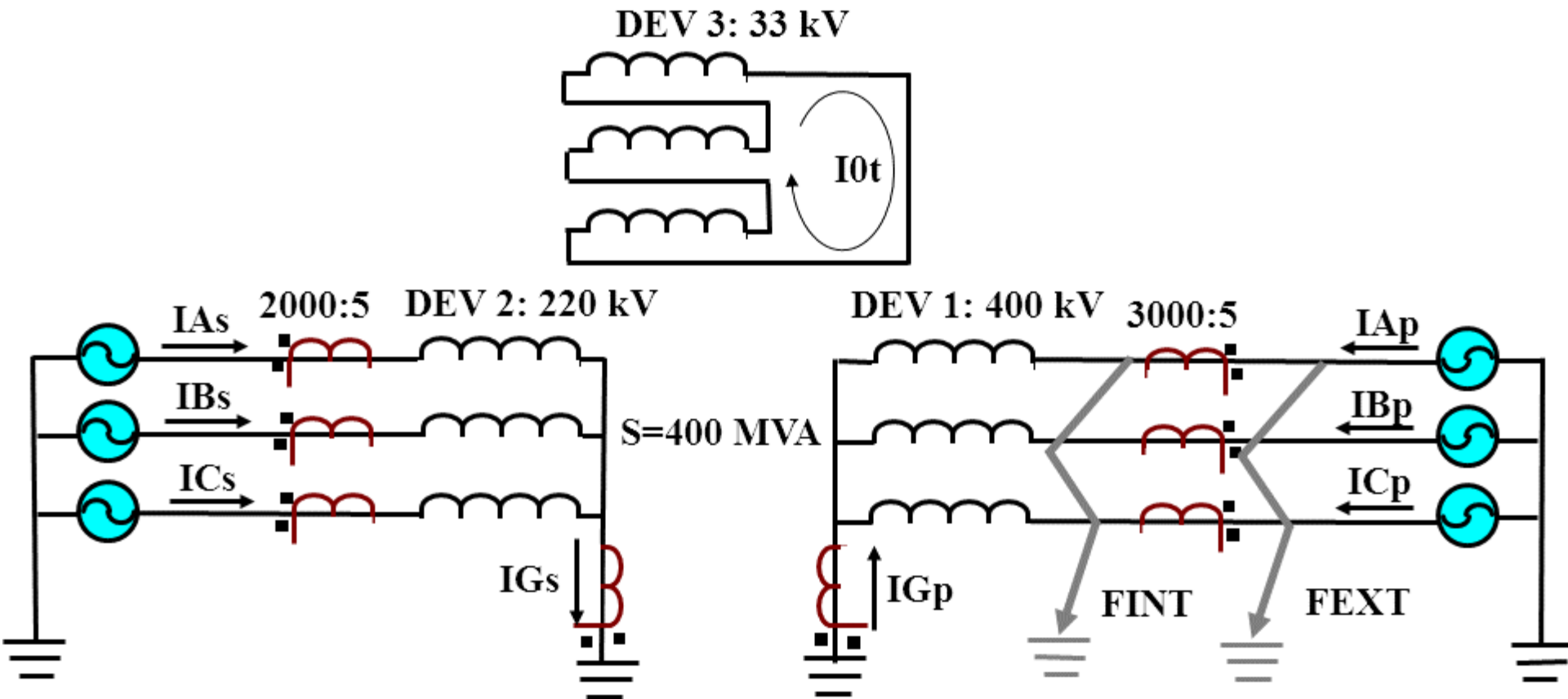
3 legged YNyn0 60 MVA 230 kV – 23 kV



Methods for Zero-Sequence Filter

- Subtract I_0 calculated from the phase currents (method 1)
- Apply a YD transformation matrix (method 2)
- Subtract I_0 calculated from the ground current (method 3)

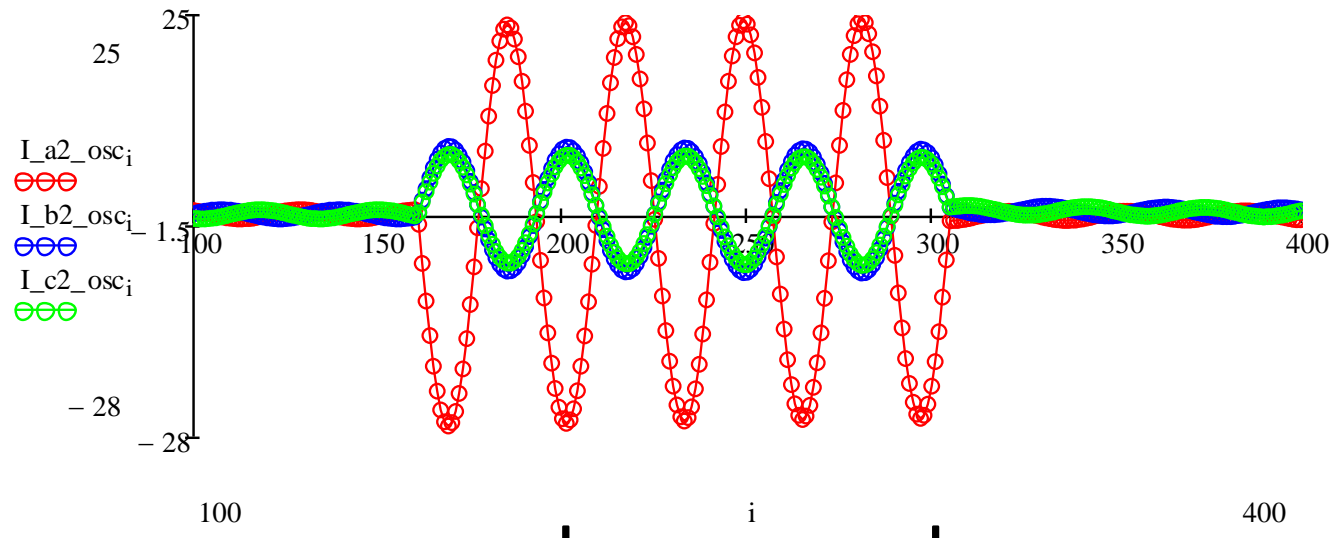
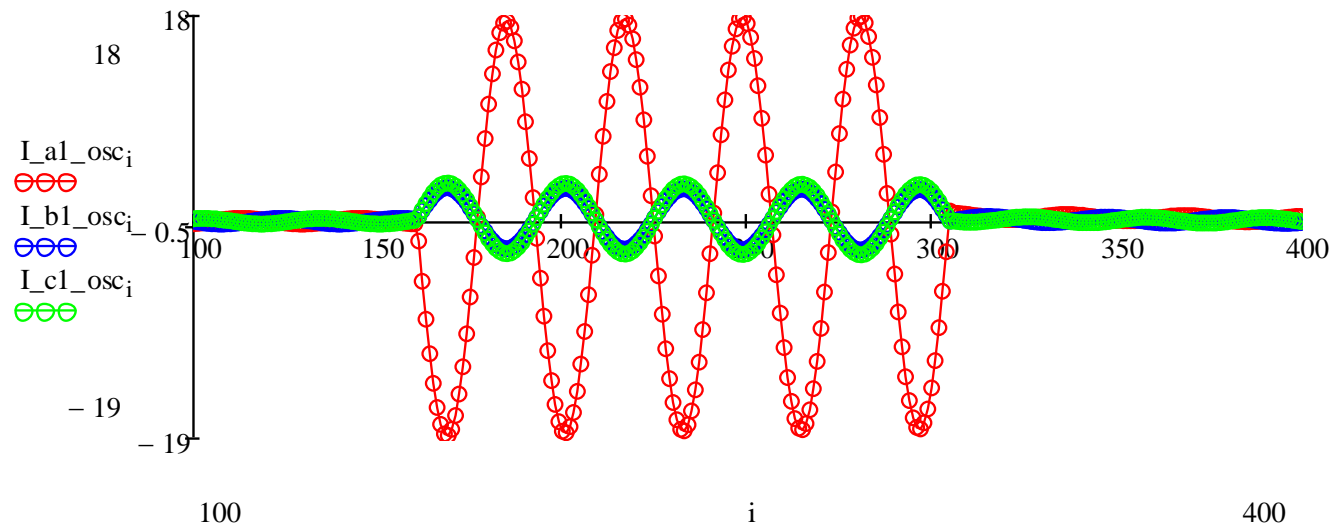
Zero-sequence Filter Effect



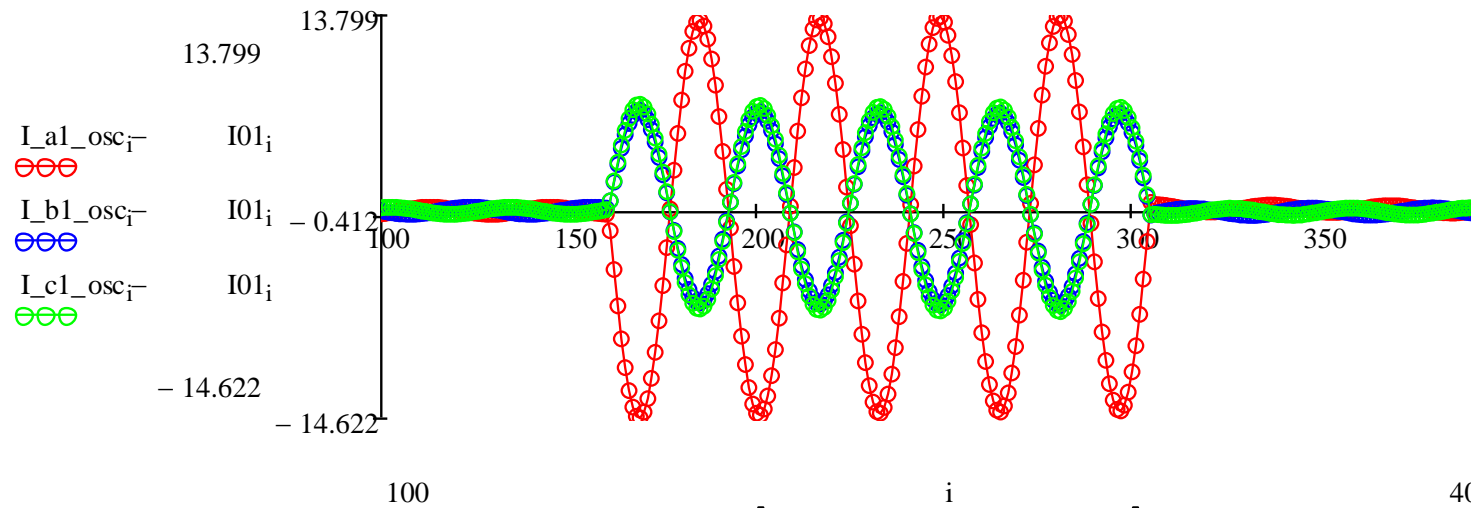
EXTERNAL FAULT: $-(I_A + I_B + I_C) = +I_G$

INTERNAL FAULT: $-(I_A + I_B + I_C) \neq +I_G$

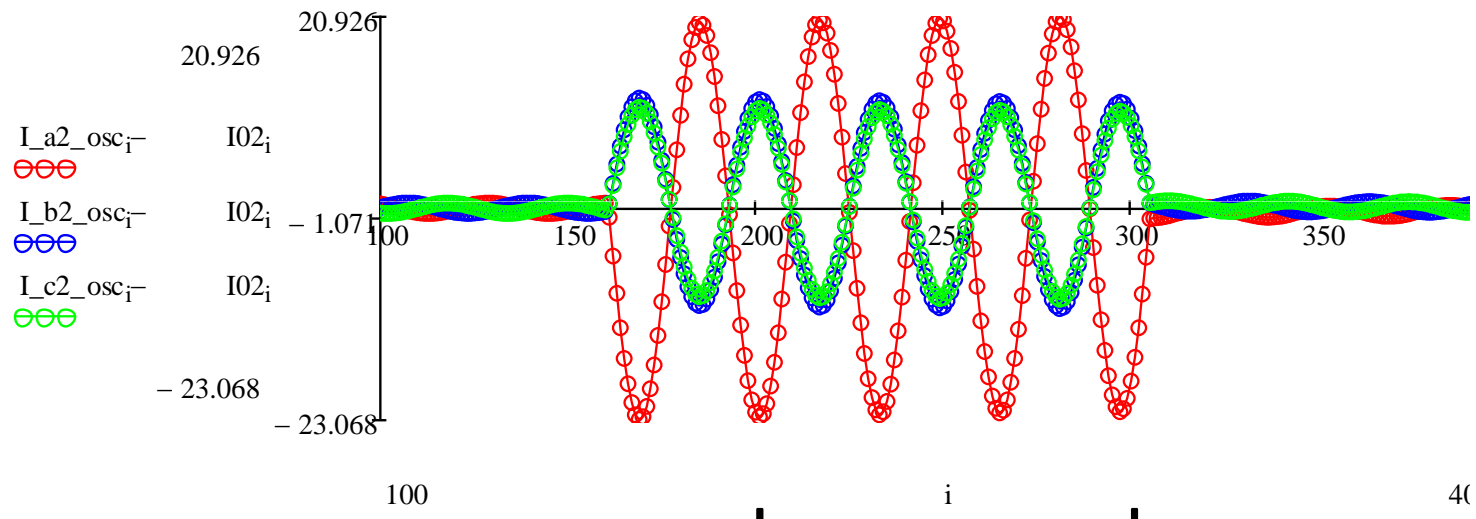
Internal AG fault



Internal AG fault with zero-seq. filter 1

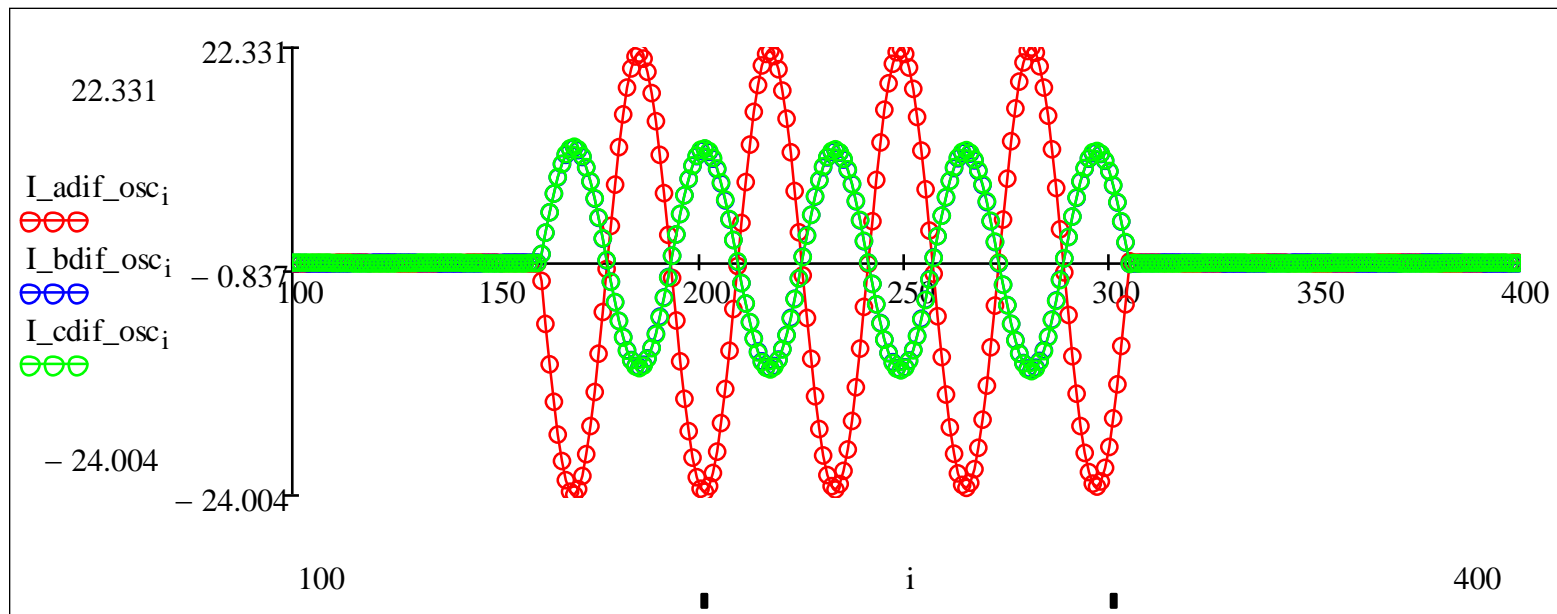


Currents in the healthy phases in phase

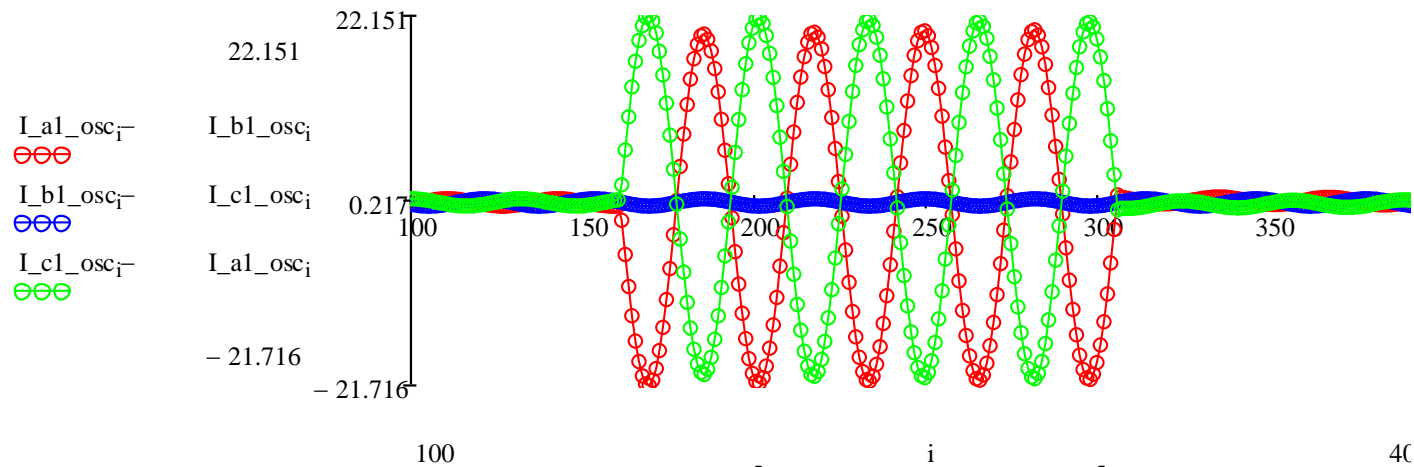


Internal AG fault with zero-seq. filter 1

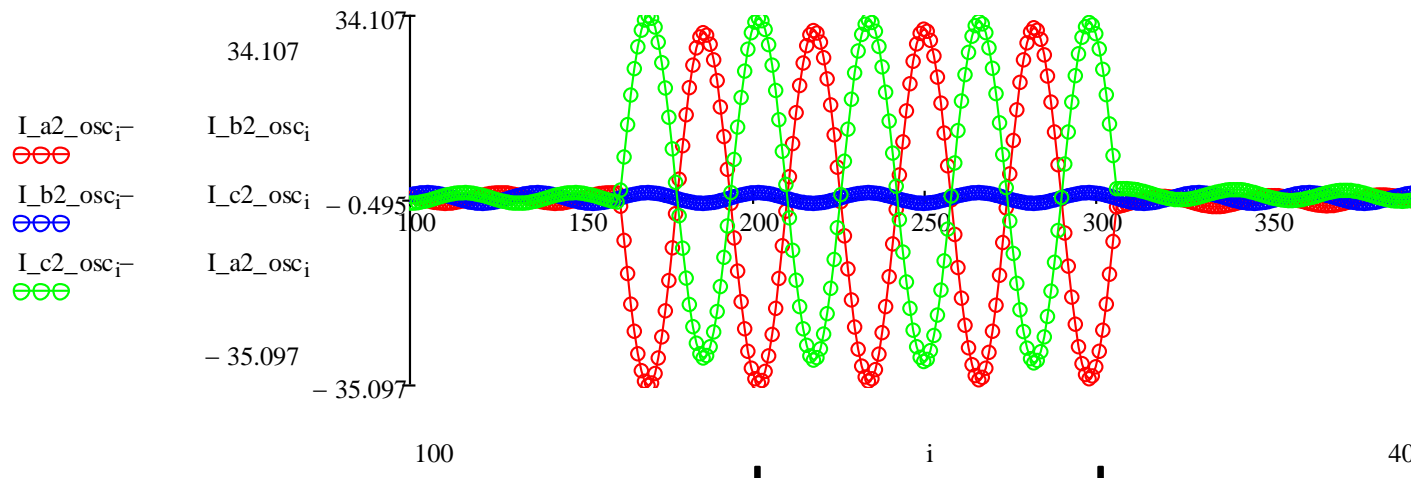
- Appearance of differential current in the healthy phases \rightarrow erroneous faulted phase selection



Internal AG fault with zero-seq. filter 2

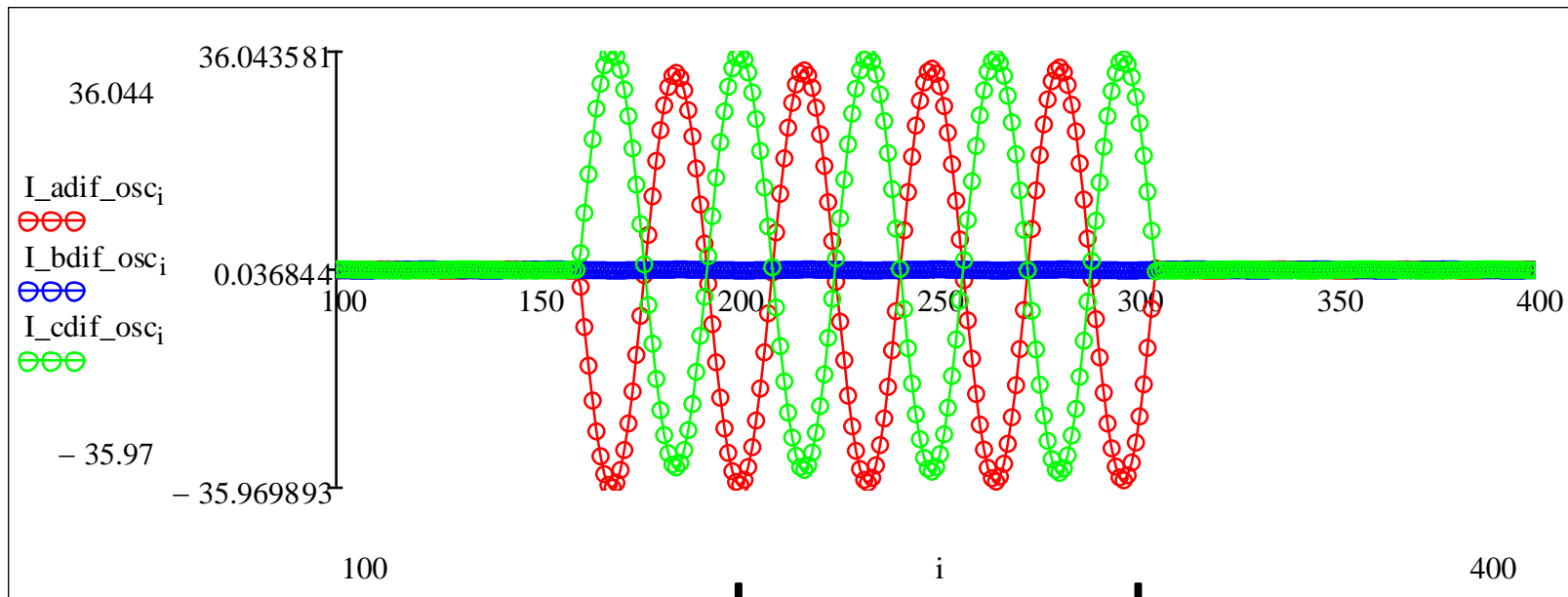


Currents in the healthy phase C in phase

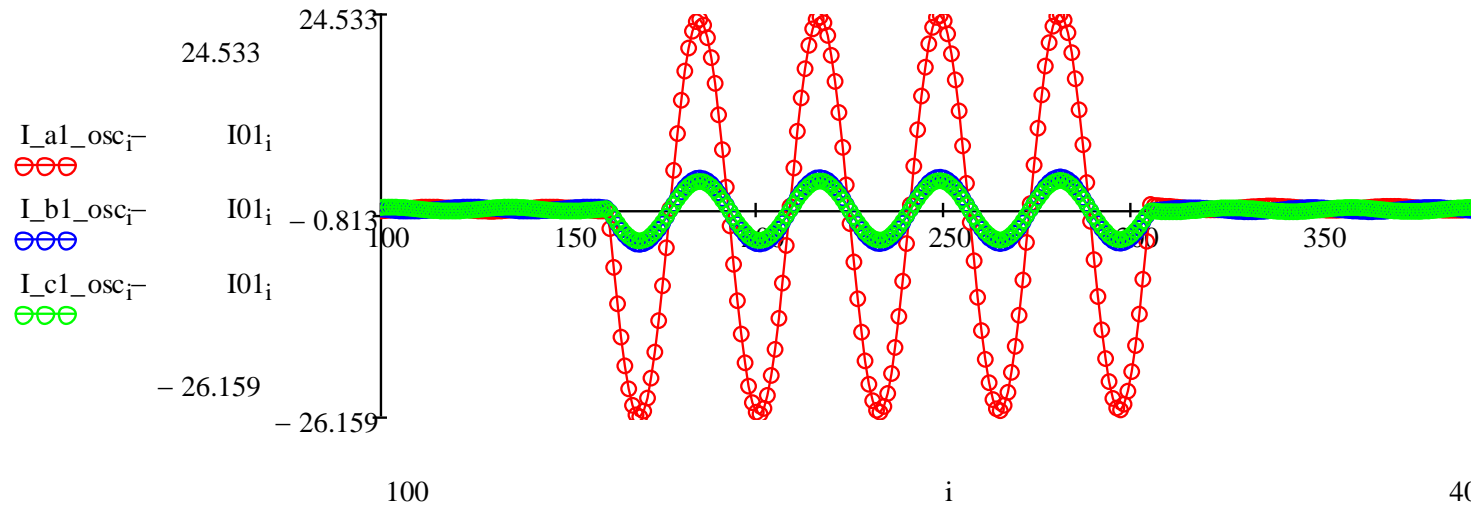


Internal AG fault with zero-seq. filter 2

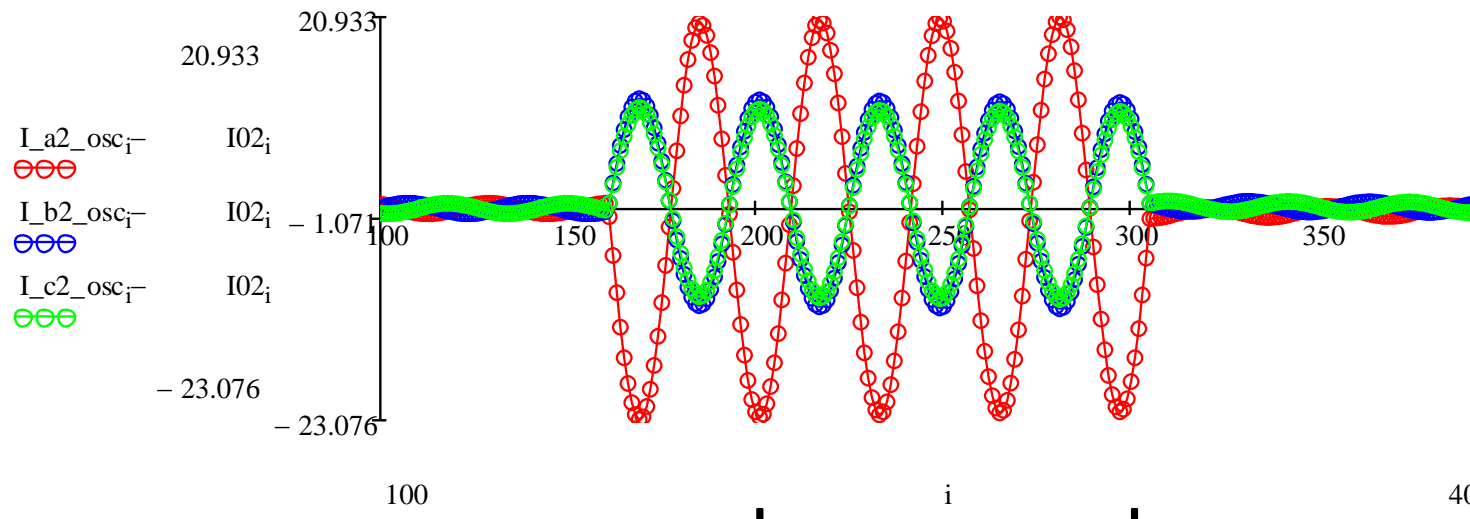
- Appearance of differential current in a healthy phase C \rightarrow erroneous faulted phase selection



Internal AG fault with zero-seq. filter 3

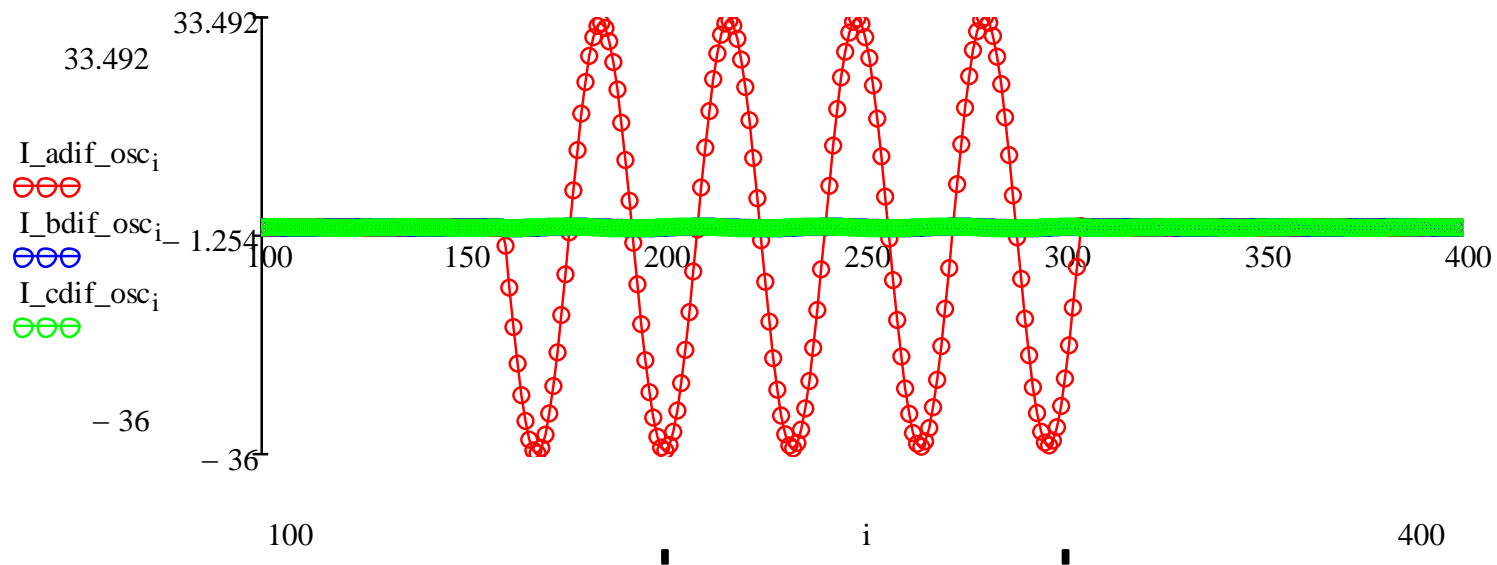


Currents in the healthy phases out of phase



Internal AG fault with zero-seq. filter 3

- No differential current in the healthy phases → correct phase selection
- Higher differential current in the faulted phase → Better sensibility



Testing 87 With Zero-Sequence Filter

WITHOUT FILTER

IADEV1=3.288_{0°}
 BDEV1=0
 ICDEV1=0

 IADEV2=4.713_{180°}
 BDEV2=0
 ICDEV2=0

WITH FILTER (I_s NOT FILTERED)

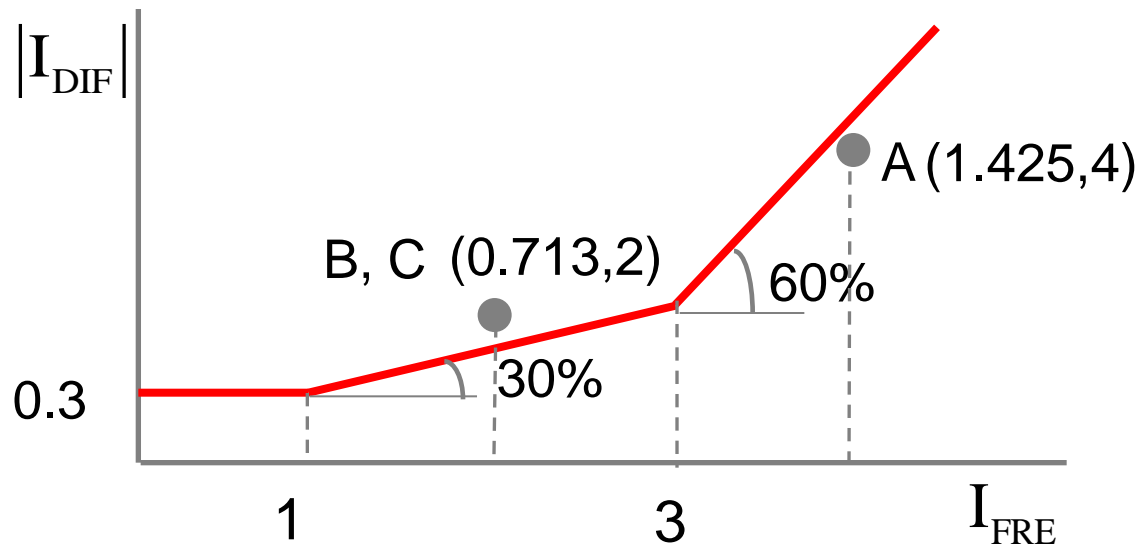
IADEV1=4.939_{0°}
 BDEV1=0
 ICDEV1=0

 IADEV2=7.069_{180°}
 BDEV2=0
 ICDEV2=0

WITH FILTER (I_s FILTERED)

IADEV1=3.288_{0°}
 BDEV1=1.644_{0°}
 ICDEV1=1.644_{0°}

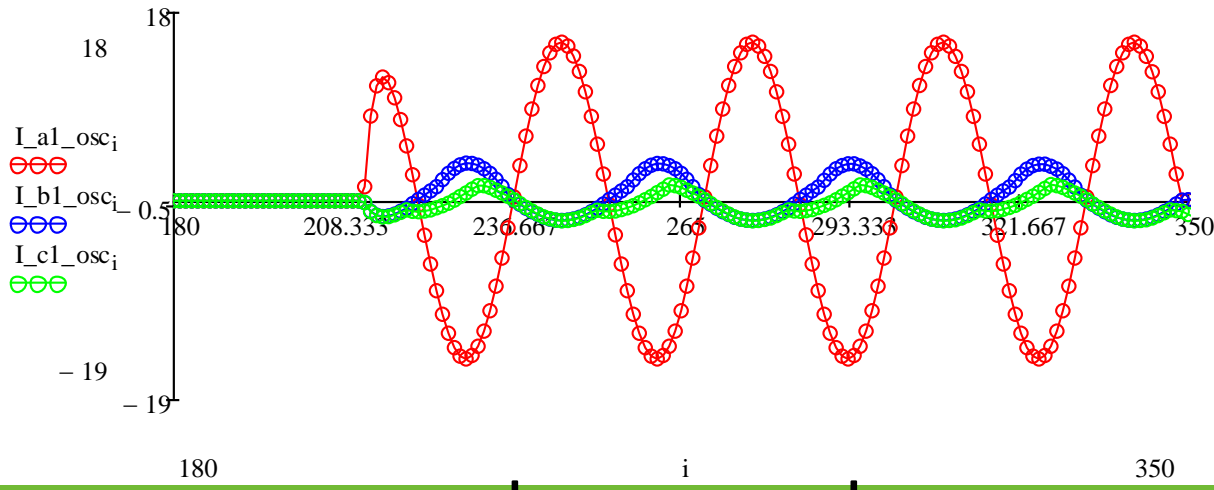
 IADEV2=4.713_{180°}
 BDEV2=2.356_{180°}
 ICDEV2=2.356_{180°}



Zero-Sequence Filter with Inrush

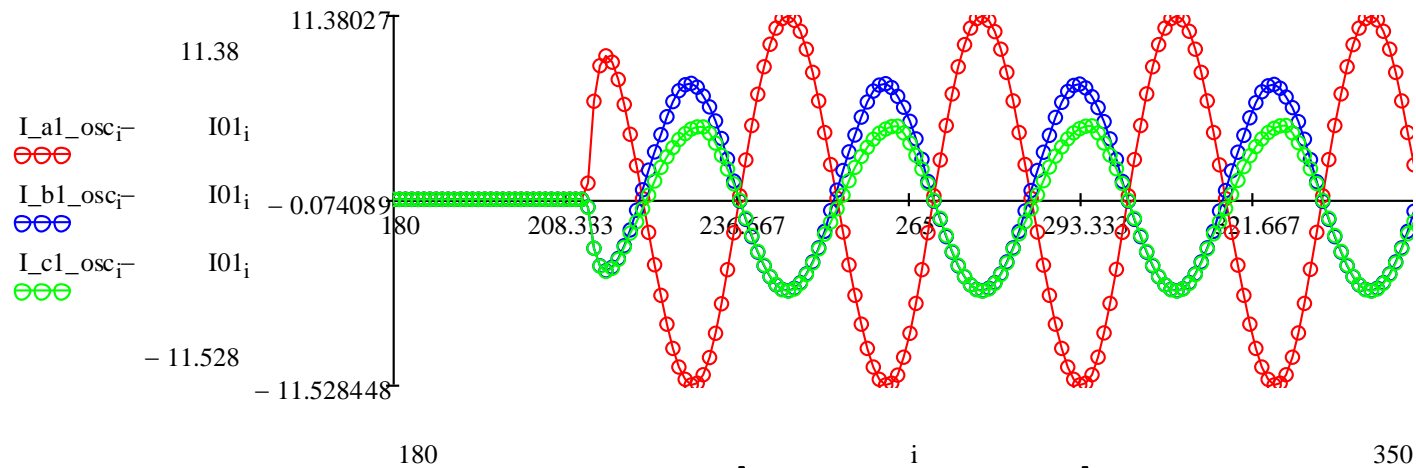
- Cross-blocking logic increases the security during inrush
- What about the dependability?
- “2 out of 3” logic is very dependable with zero-sequence filter method 1 and 2

CLOSE ONTO INTERNAL AG FAULT

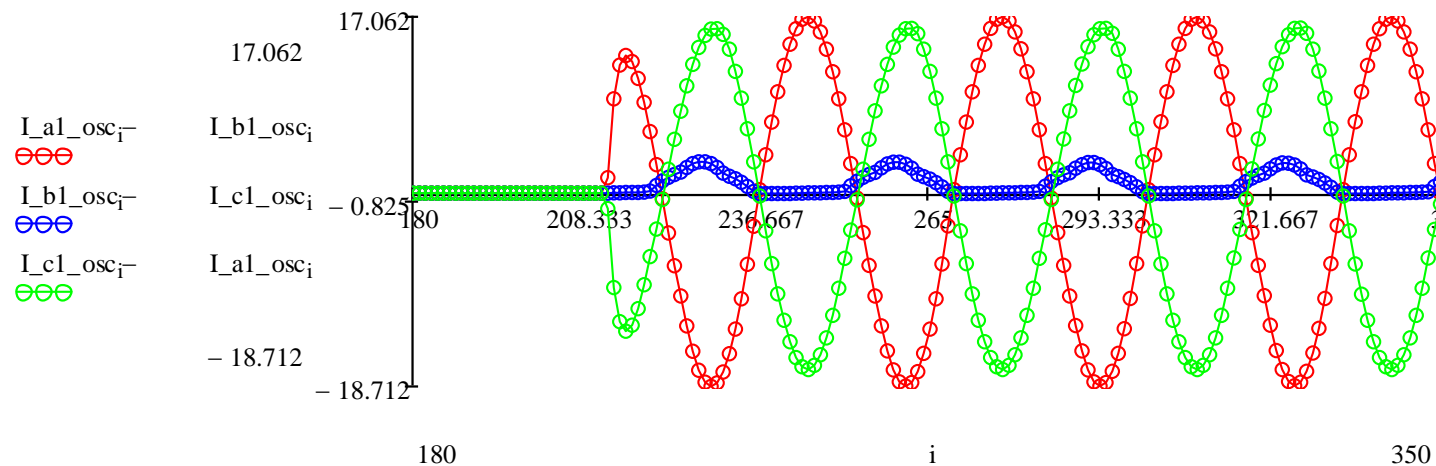


Zero-Sequence Filter with Inrush

ZERO-SEQUENCE FILTER WITH PHASE CURRENTS (METHOD 1)

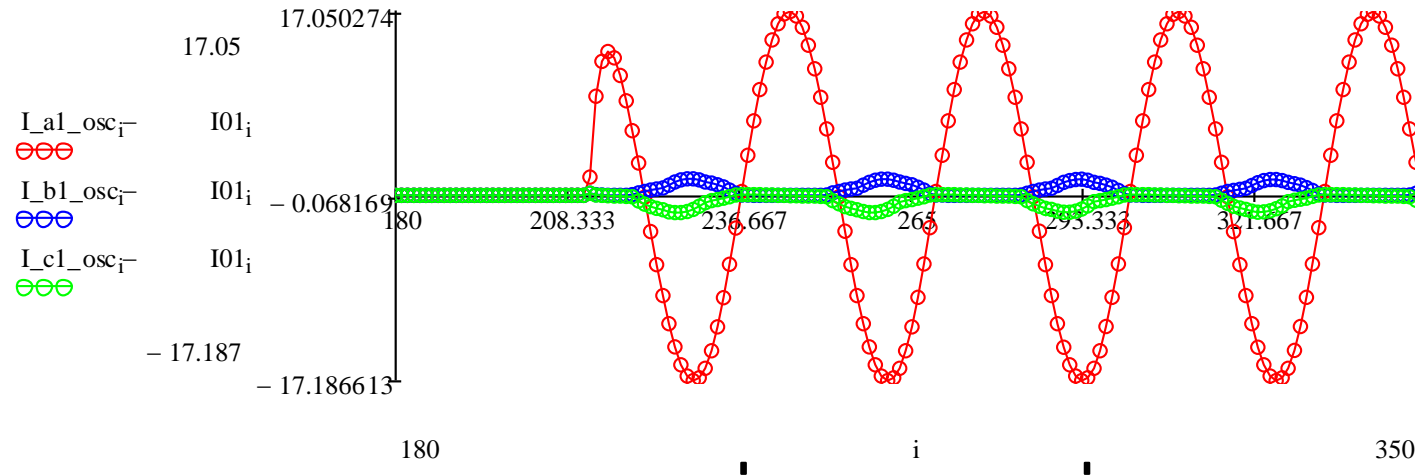


ZERO-SEQUENCE FILTER WITH PHASE CURRENTS (METHOD 2)



Zero-Sequence Filter with Inrush

ZERO-SEQUENCE FILTER WITH GROUND CURRENT (METHOD 3)



Method 3 will activate the "2 out of 3" cross-blocking logic

Directional Comparison

INTERNAL FAULT

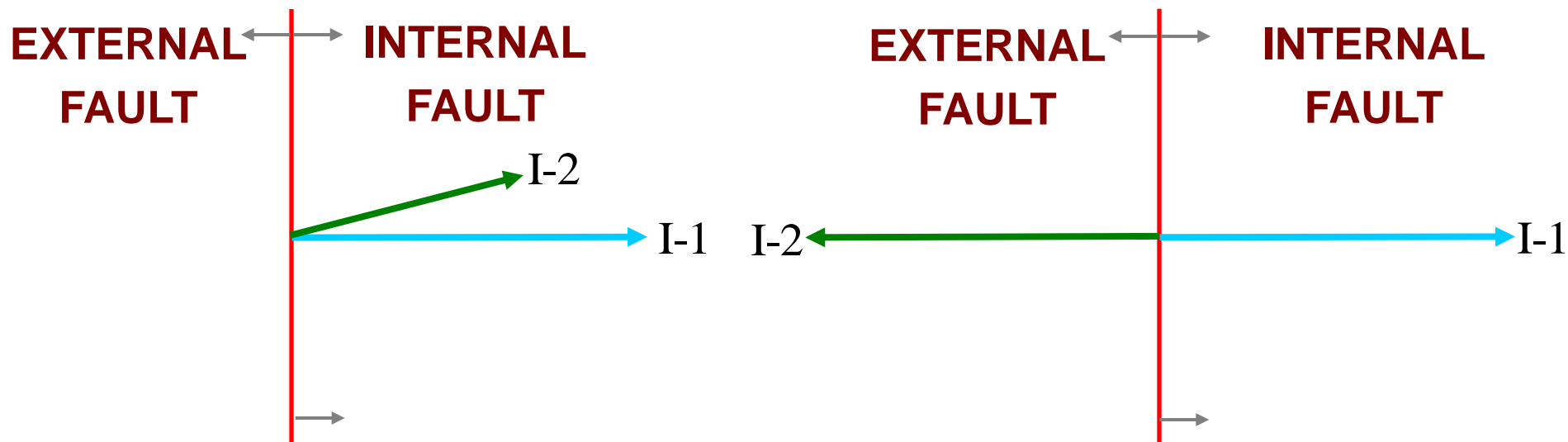
Currents “in phase”

$$|\arg(I_2) - \arg(I_1)| < 90^\circ$$

EXTERNAL FAULT

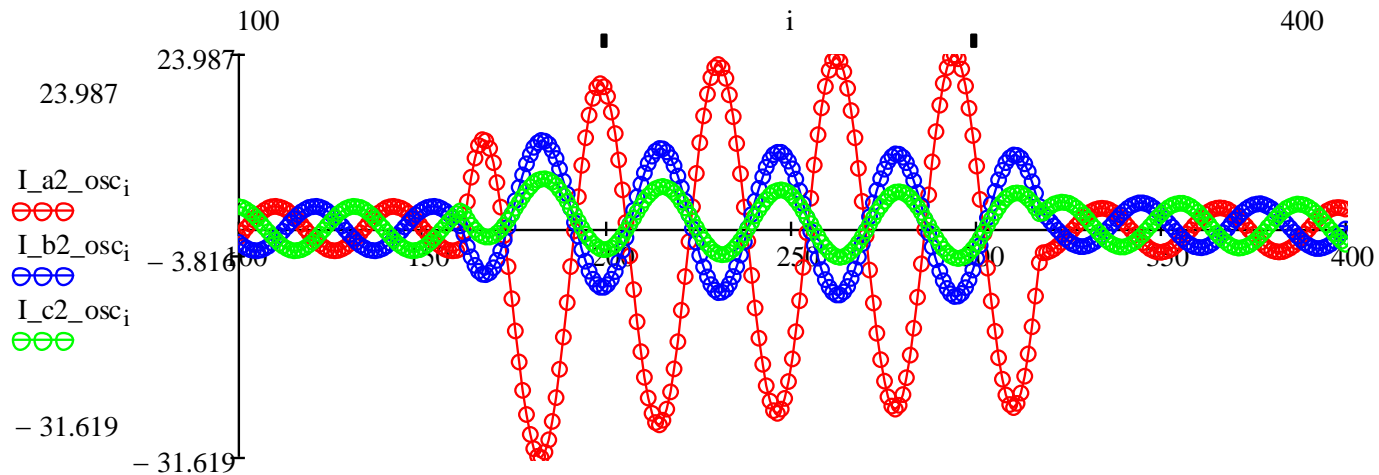
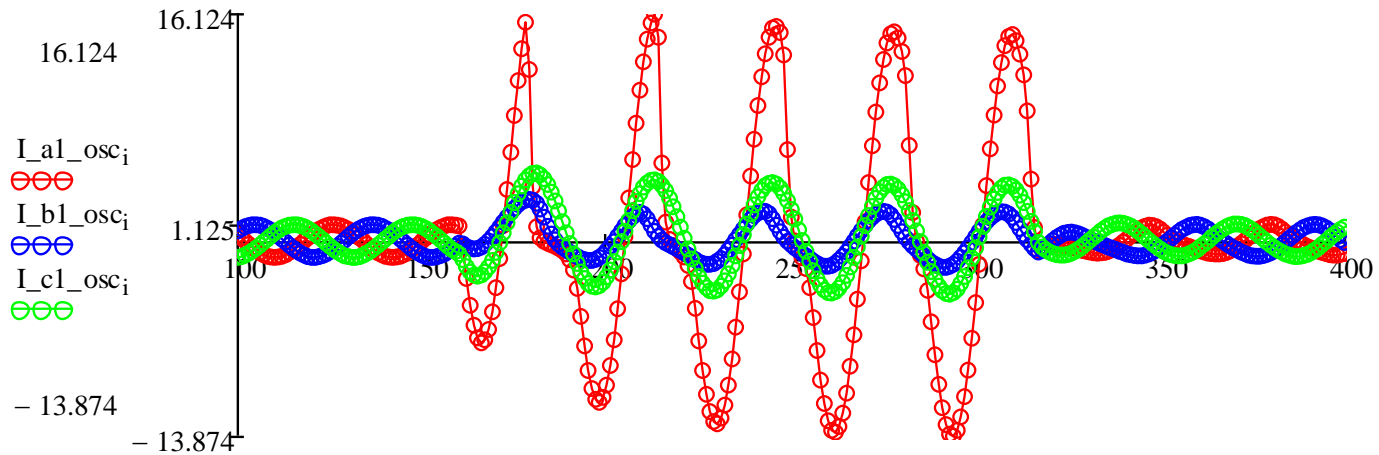
Currents “out of phase”

$$|\arg(I_2) - \arg(I_1)| > 90^\circ$$



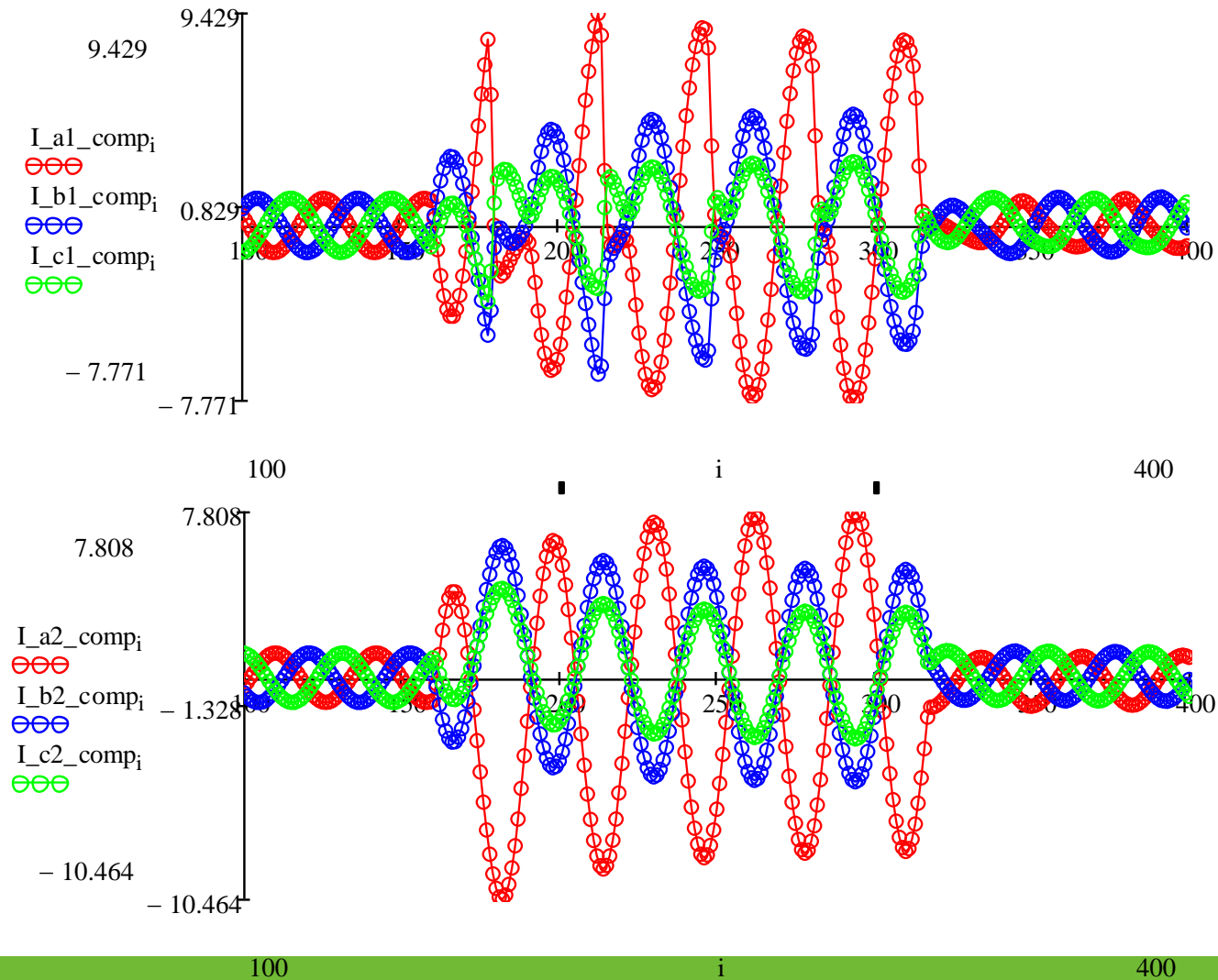
Directional Comparison

EXTERNAL FAULT WITH AG SATURATION



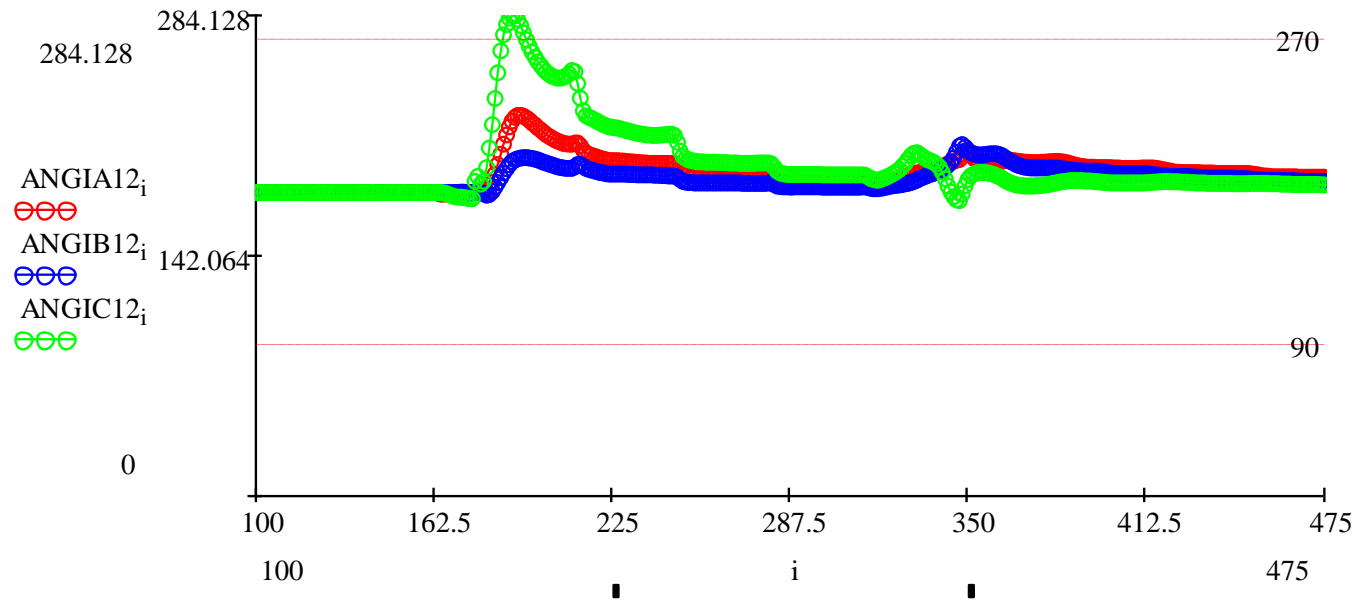
Directional Comparison

CURRENTS WITH ZERO-SEQUENCE FILTER



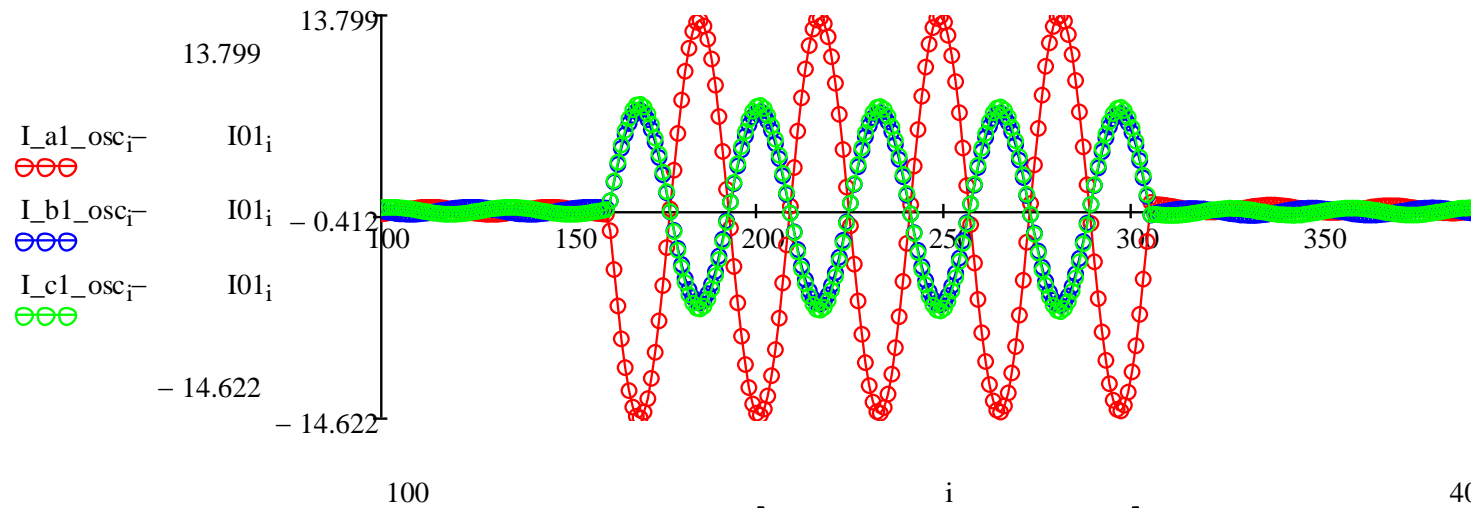
Directional Comparison

ANGLE DIFFERENCE

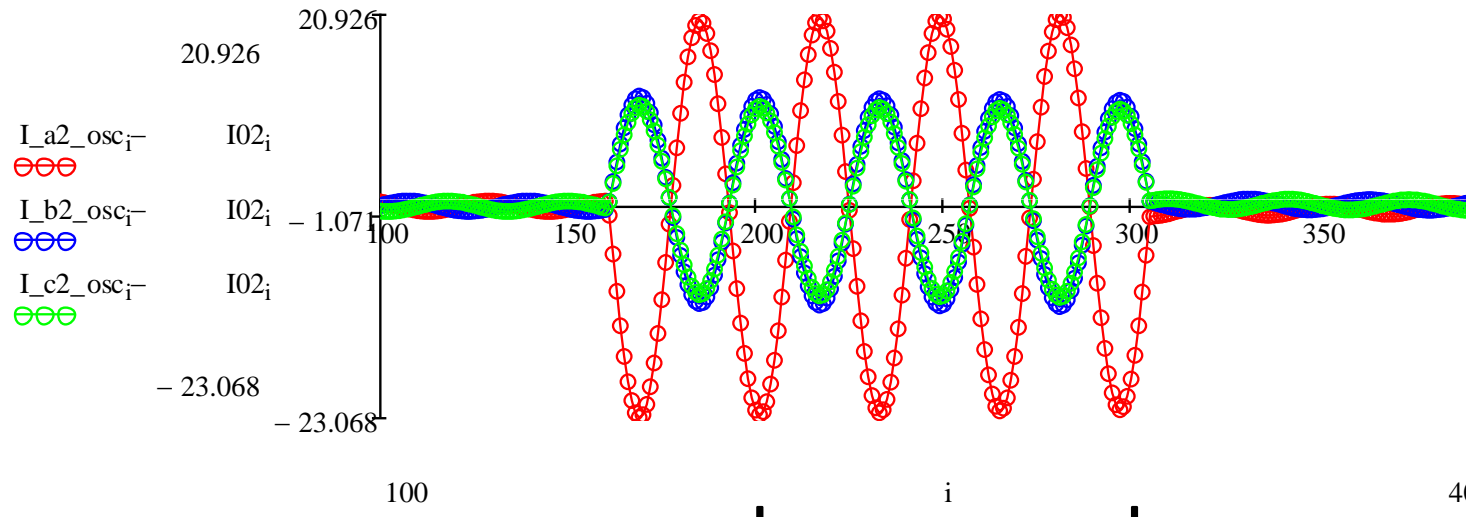


- Use of “2 out of 3” logic for method 1 and 2 improves the security

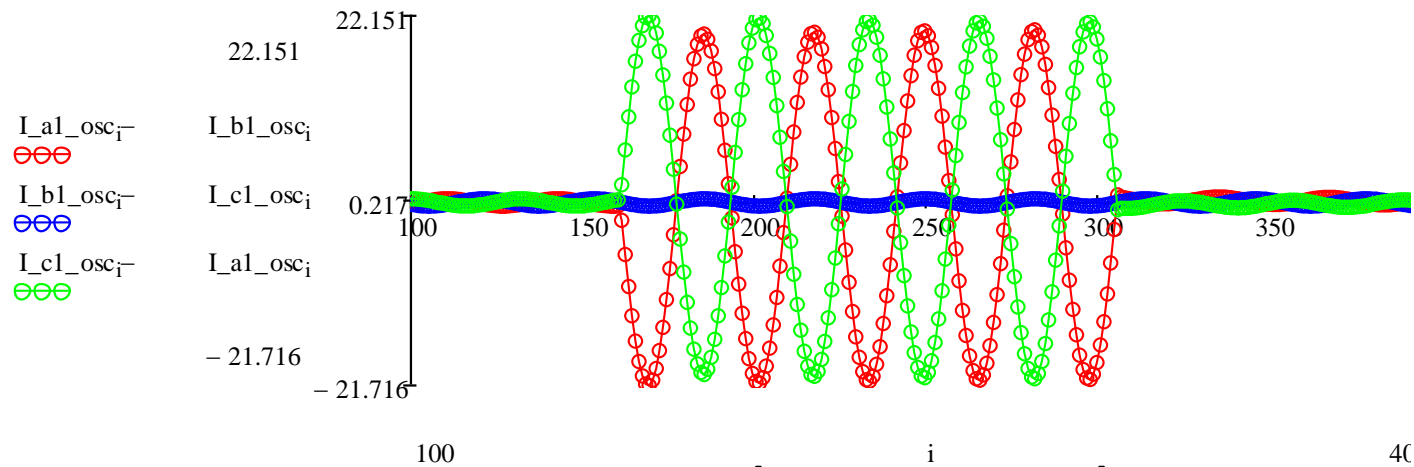
Internal AG fault with zero-seq. filter 1



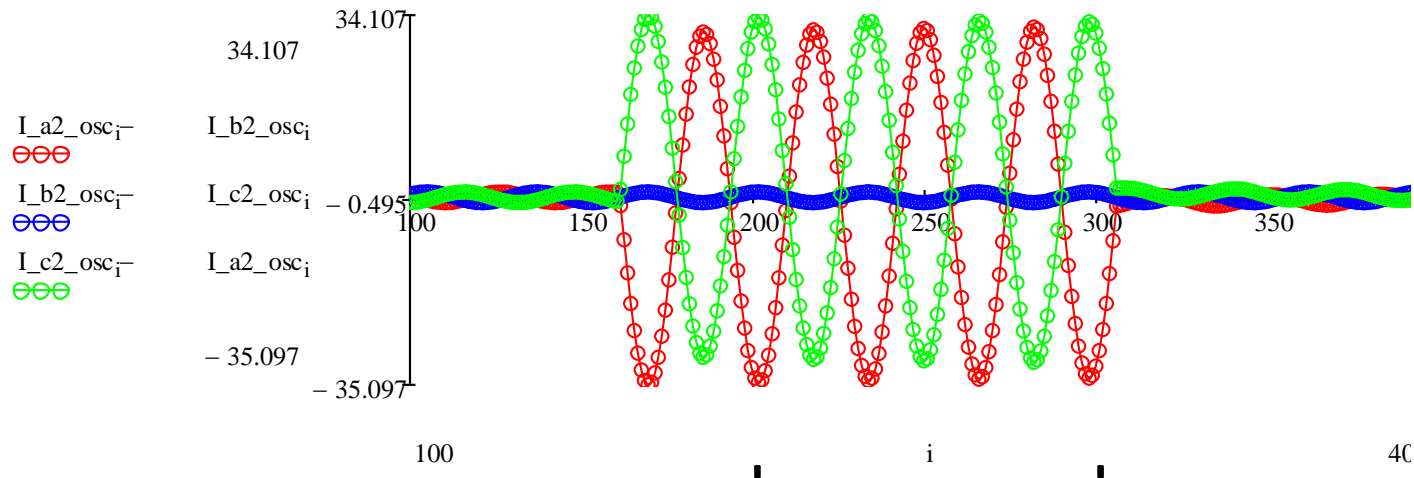
"2 out of 3" logic in directional comparison not fulfilled



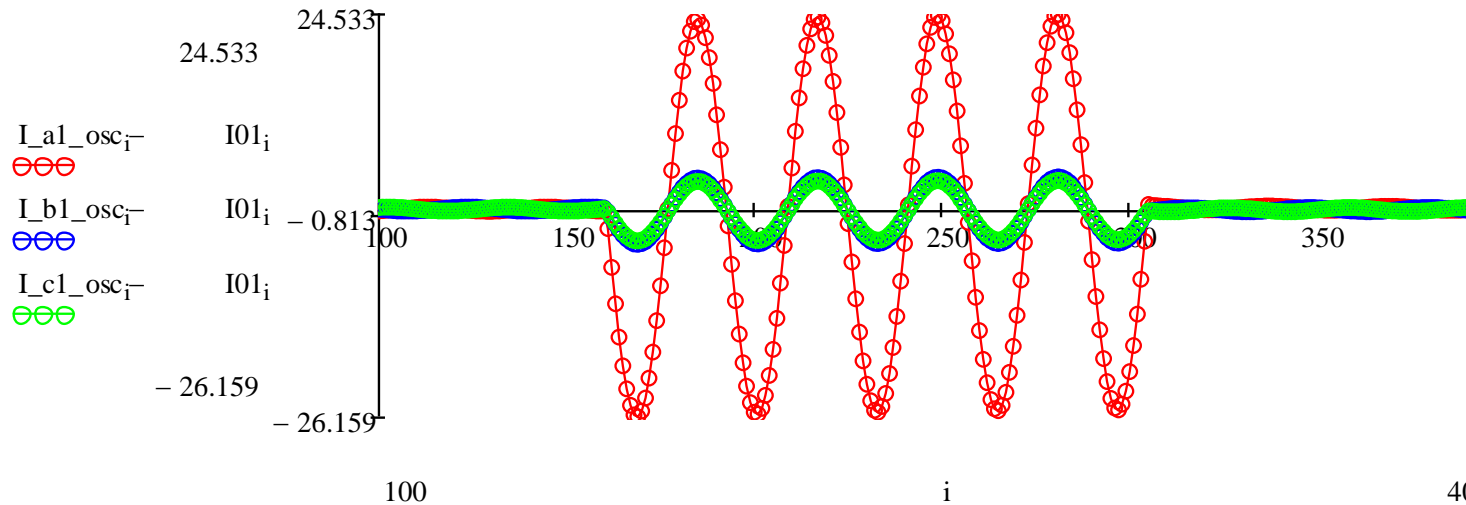
Internal AG fault with zero-seq. filter 2



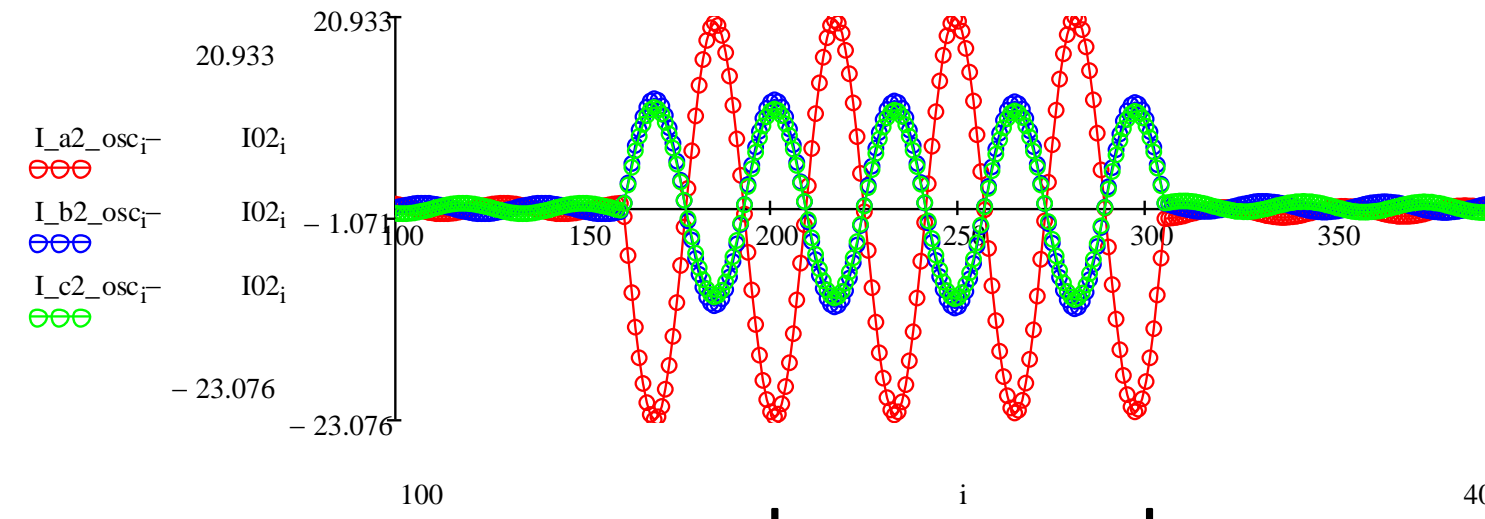
"2 out of 3" logic in directional comparison not fulfilled



Internal AG fault with zero-seq. filter 3



"2 out of 3" logic in directional comparison fulfilled



Conclusions

- Not only YND transformers require the use of the zero-sequence filter but also YNY 3-legged transformers
- Zero-sequence filter applied from the **phase currents (methods 1 and 2)**:
 - Produces a loss of sensibility and an erroneous phase selection: an independent phase selector should be used
 - Allows the application of “2 out of 3” logics increasing the security both for directional comparison and harmonic blocking

Conclusions

- Zero-sequence filter applied from the **ground current (method 3)**:
 - Provides good sensibility and phase selection
 - Does not allow the use of “2 out of 3” logics decreasing the security both for directional comparison and harmonic blocking

Thank you

Roberto Cimadevilla
r.cimadevilla@ziv.es